



# Digital Sonar **KDS-5000BB**



Koden Electronics Co.,Ltd. 5278 Uenohara, Uenohara-shi Yamanashi-Ken 409-0112 Japan

6

## **Declaration of Conformity**

This declaration is issued according to the Directive 2014/30/EU of the European Parliament and of the Council of 26 February 2014 on the harmonization of the laws of the Member States relating to electromagnetic compatibility.

We, Koden Electronics Co., Ltd.; 5278 Uenohara Uenohara-Shi, Yamanashi-Ken ; 409-0112, Japan declare as manufacturer under our sole responsibility that the KODEN Digital Sonar

## KDS-5000BB

intended for use as a Marine Fish Finder for use aboard vessels to which this declaration relates conforms to the following standard(s):

IEC 60945 Ed.4.0 2002 (Clauses 9,10 & 12)

#### Type names: KDS-5000BB

Consisting of

| ng of: | Processor Unit:        | DPU-510                              |
|--------|------------------------|--------------------------------------|
|        | <b>Operation Unit:</b> | DOU-520                              |
|        | Hull Unit:             | DHU-5301 ; Transducer Unit: ESR-1603 |
|        | Junction Box:          | DJB-540                              |
|        | Power Cable:           | 31524D-1                             |
|        |                        |                                      |

#### For assessment, see

1. Suzuki Fish Finder Co.,Ltd S-1900MBB E.M.C. Test Report No.SFF-002 at Aichi Center for Industrie and Science Technology tested by Suzuki engineers

#### Software: Processor Unit: DPU-510 – f2cs.m.s19 x.x.xx Frequency: 180kHz ± 10kHz ; 0.1kHz step

Our product is also in compliance to Directive 2011/65/EU of the European Parliament and of the Council of 8 June 2011 on the restriction of the use of certain hazardous substances (RoHS) in electrical and electronical equipment.

EU representative:

Koden Elektronik GmbH

Point of contact:

Am Gewerbepark 15, D-64823 Gross-Umstadt Koden Electronics Co.,Ltd. 5278 Uenohara, Uenohara-shi, Yamanashi-Ken, Japan Mr. JUN HARAYAMA, Manager, Quality Assurance Dept. Tel.: +81 554 20 5860 Fax: +81 554 20 5875

Date: 30 July, 2020

Jún Harayama Manager, Quality Assurance Dept. Document No. 80-2731U-X001

#### KDS-5000BB Operation Manual Doc No: 0093150002

#### **Document Revision History**

| No. | Doc. No Rev. No. | Revised Date | Revised Content  |
|-----|------------------|--------------|--|
|     |                  | (Y/M/D)      |  |
| 0   | 0093150002-00    | 2017/01/27   | First edition  |
| 1   | 0093150002-01    | 2017/04/19   | Declaration, Transducer auto down $\rightarrow$ TD auto down |
| 2   | 0093150002-02    | 2019/01/15   | Specifications   |
| 3   | 0093150002-03    | 2020/10/01   | Declaration, Cover   |
| 4   |                  |              |  |
| 5   |                  |              |  |
| 6   |                  |              |  |
| 7   |                  |              |  |
| 8   |                  |              |  |
| 9   |                  |              |  |
| 10  |                  |              |  |

#### **Document No. Revised Version Norm**

When part of the document needs to be revised, the document has advanced revision number.

The document No. is indicated at the lower right side on the cover and at the left or right side of the footer region of each page.

#### © 2017-2020 Koden Electronics Co., Ltd. All rights reserved.

No part of this publication may be reproduced, transmitted, translated in any form by any means without the written permission of Koden Electronics Co., Ltd. The technical descriptions contained in this publication are subject to change without notice. Koden assumes no responsibility for any errors, incidentals or consequential damages caused by misinterpretation of the descriptions contained in this publication.

#### **Important Notice**

- For copy and transcription of this Operation Manual (hereinafter referred to as this manual), permission from Koden is needed. Koden prohibits the un-authorized copy and transcription of this manual.
- If this manual is lost or damaged, consult a dealer of Koden or Koden.
- The specification of the products and the contents in this manual are subject to change without notice.
- The contents displayed on the menu of product may be different from the expression of this manual. The fonts and shapes of the keys and menus in the illustration may differ from the actual ones, and some parts may be omitted.
- Koden is not liable for damages and troubles arisen from misunderstanding of the contents in this manual.
- Koden is not liable for any damages caused by earthquake, lightning, wind and flood damage and fire for which Koden is not responsible, and actions by third parties, other accidents, customer's unintended error/abuse and the use under other abnormal conditions.
- Koden is not liable for damages of accompaniment (change/loss of memorized content, loss of business profit, stop of business) arisen from use or failure of our products.
- If the stored data are changed or lost, irrespective of causes of troubles and damages, Koden is not liable for them.
- Koden is not liable for any damages arisen from malfunction caused by combination of software and connected equipment in which Koden is not engaged.

### For Your Safe Operation

#### Symbol used in this Operation Manual

The following pictograms are used in this manual. The meaning of each symbols shall be well understood and the maintenance and inspection shall be carried out.

| Symbol     | Meaning  |
|------------|--|
| Warning    | <b>Mark for warning</b><br>This mark denotes that there is a risk of death or serious injury when dealt<br>with incorrectly.                               |
| Â          | Mark for danger of high voltage<br>This mark denotes that there is a risk of death or serious injury due to<br>electric shock when dealt with incorrectly. |
| Caution    | <b>Mark for caution</b><br>This mark denotes that there is a risk of slight injury or damages of devices when dealt with incorrectly.                      |
| $\bigcirc$ | <b>Mark for prohibition</b><br>This mark denotes prohibition of specified conducts. Description of the prohibition is displayed near the mark.             |

#### **Caution items on equipment**

| Â       | <b>Be careful of high voltage inside</b><br>High voltage, which may risk your life, is used. This high voltage may<br>remain in the circuit even after the power is switched off. To prevent<br>contact with the high voltage circuits accidentally, a protective cover or<br>the label with this mark is provided on the high voltage circuit. When the<br>inside is to be checked, ensure to switch off the power and to discharge<br>the residual voltage for safety. An engineer authorized by Koden shall |
|---------|--|
| Warning | carry out the inspection and maintenance works.<br><b>Power off in the boat</b><br>An accidental power-on during works may result in worker's<br>electrification. To prevent such accident in advance, ensure that power<br>in the boat and on the equipment are switched off. Furthermore, it is<br>safer to hang a caution tag saying "Under work" near the power switch<br>of equipment.  |
| Warning | <b>Be careful of dust</b><br>Inhaled dust may cause respiratory affection. At the time of cleaning the<br>inside of equipment, be careful not to inhale dust. Wearing a safety<br>mask is recommended.   |

| Caution | <b>Caution on location of installment</b><br>The equipment shall not be installed at locations which are excessively<br>damp and suffers from water drops. Otherwise, dew condensation may<br>occur inside the display screen, and corrosion may occur inside the unit<br>box.   |
|---------|--|
| Caution | <b>Measures against static electricity</b><br>Static electricity may be generated from the carpet on the floor in the<br>cabin or clothes made of synthetic fiber, and it may destroy the<br>electronic components on circuit boards. The circuit boards shall be<br>handled with appropriate measures against static electricity. |
| Caution | <b>Caution at installation of Transducer unit</b><br>Transducer unit shall be installed at locations where there is no effect by<br>bubble and noise. Bubble and noise may seriously degrade the<br>performance of this equipment.   |

### Cautions on handling

| Warning | No disassembly or modification of this equipment is allowed. It may lead<br>to failure, firing, smoking or electric shock. In case of failure, please<br>contact Koden's dealers or Koden.  |
|---------|---|
| Warning | In case of smoking or firing, switch off the power in the boat and of this equipment. It may lead to firing, electric shock or damages.   |
| Â       | <b>Be careful of residual high voltage</b><br>High voltage may remain in capacitors for several minutes after<br>switching off the power. Before inspection of the inside, please wait at<br>least 5 minutes after switching off or discharge the residual electricity in<br>an appropriate manner. Then, start the work. |
| Caution | The information displayed on this equipment is not intended to use for your navigation. For your navigation, be sure to see the specified materials.  |
| Caution | Please use the specified fuses. If un-specified fuses are used, they may cause firing, smoking or damages.  |
| Caution | Be sure to submerge the Transducer unit in water before transmission.<br>If not, it may be damaged.   |

## CONTENTS

## **SONAR OPERATION**

| Chapter 1 Introduction |   |                  |
|------------------------|---|------------------|
|                        | Before Use<br>For Your Safety<br>Components                     | 3<br>5<br>7      |
| Chapter 2 Installat    | ion   | 10               |
| Chapter 3 Basic O      | peration  | 34               |
| Chapter 4 Function     | n Settings  | 44               |
|                        | Factory Settings<br>Menu<br>Function Settings                   | . 46<br>48<br>51 |
| Chapter 5 Descript     | ion of Knobs and Keys   | 83               |
|                        | Knobs<br>Keys   | 84<br>87         |
| Chapter 6 Option       |   | 95               |
|                        | Option List<br>Input/Output Terminals<br>Input/Output Terminals | 96<br>98         |
|                        | (PROCESSOR UNIT)<br>Remote Controller                           | 99<br>100        |
| Additions              |   | 101              |
|                        | Disposal<br>Specifications                                      | 101<br>102       |

## CHAPTER 1

## **INTRODUCTION**

Thank you for purchasing the KDS-5000BB digital sonar.

We are confident you will enjoy using your unit for many years to come.

This manual provides complete information on safely operating the

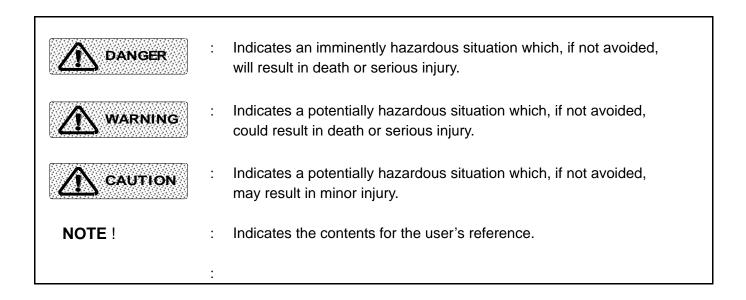
KDS-5000BB.

Please carefully read and follow the safety information so that the KDS-5000BB will perform to the utmost of its ability.

| Before Use      | Symbols3Notice3Turning the Power On/Off4Key Operation4Preventive Measure for Interference in the<br>area of ship congestion4 |
|-----------------|--|
| For Your Safety | Use Environment 5<br>Mounting Conditions 5<br>Power Supply 6<br>Handling 6   |
| Components      | Supplied Components 7  |

## **SYMBOLS**

- The following symbols are used in this manual.
- Please read this manual carefully and take note of these symbols.



## NOTICE

- This manual should be kept on hand to provide your quick reference whenever you need it.
- Any use other than that mentioned in this manual is not guaranteed.
- The contents of this manual and equipment specifications are subject to change without notice.
- No part of this manual may be copied or reproduced without written permission.

## **TURNING the POWER ON/OFF**

#### POWER ON

Press the POWER ON key on the Operation unit.

"Please wait!" appears on the screen. The Transducer unit is automatically lowered if "**TD AUTO DOWN – ON**" previously set.

In case "**TD AUTO DOWN – OFF**" is previously set, it is lowered only after pressing the Lower key (  $\downarrow$  ).

#### **POWER OFF**

Press and hold the OFF key when turning the power off. The power is turned off after "Please wait!" appears on the screen. The Transducer unit is automatically raised.

Note that slight touch of the OFF key will not turn the power off.

## **KEY OPERATION**

A beep sounds when operating key correctly. Three short beeps sound when operating wrongly or not accepting the operation.

## **PREVENTIVE MEASURE for INTERFERENCE in the AREA of**

## SHIP CONGESTION

When the fishing ground is crowded with many fishing boats, the sonar is subject to interference from ultrasonic equipment (echo sounder or sonar) on other boards as well as those on own ship. As preventive measure for interference the change of the used frequency or the reduction of the transmitting sound pressure level should be taken from the broadband sonar, the dual frequency sonar and the single frequency sonar accordingly.

## FOR YOUR SAFETY

## **USE ENVIRONMENT**



Keep the unit away from the flammable gas. Otherwise it causes a fire.

Follow the below proposed conditions for the installation. Otherwise it causes a fire or an electrical shock.

Away as much as possible from areas where the unit is likely to be exposed to direct water spray and free as much as possible from shocks and engine vibration.

Away as much as possible from areas of high temperatures or areas where the unit is likely to be exposed to direct sunlight.

## **MOUNTING CONDITIONS**



Do not install the KDS-5000BB on unstable or uneven surfaces. Installing the unit tentatively may result in dropping, toppling over or injury.

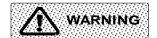
Follow the below conditions for wirings. Otherwise it causes heat, a fire or injury. Run the cables not to touch the rotary obstacles or disturb the operation. Do not use the cables bent, twisted or stretched by force. Do not put heavy objects on the cables.



Always turn off the power before connecting or disconnecting the unit. Pulling the cables may damage the cables themselves and result in fire or electrical shock.

### FOR YOUR SAFETY

## **POWER SUPPLY**



Use the proper voltage. Otherwise it will result in fire or electrical shock.

Turn on/off the power by ON/OFF keys on the Operation unit. Turning on/off the power by the switchboard may damage the unit.



Turn off the power when starting the ship engine. Otherwise it may damage the unit.

## HANDLING



Do not operate the unit while steering. Otherwise it will cause wrecks.

Do not open the case cover. There is a risk of electrical shock if you touch the high voltage conductors. Only qualified personnel should work inside the unit.

Care for sufficient reinforcement and being watertight should be taken when installing the Hull unit. Otherwise it will cause wrecks.



Use the proper fuse when changed. Otherwise it could result in serious trouble or fire.

Use the specified power supply cables. Otherwise it could result in serious trouble or fire.

The Hull unit Gears and Flange Unit need a regular lubrication with grease.

Confirm the voltage between the Flang and the minus terminal of the ship's battery does not exceed 0.65 volts after the installation completed.

Use the larger diameter cable if the voltage exceeds 0.65 volts. Otherwise the damage to the Transducer unit due to the electrolytic corrosion may results.

## SUPPLIED COMPONENTS

## PROCESSOR UNIT (DPU-510)

| Name of item | Processor unit | DC power cable   | Communication cable |
|--------------|----------------|------------------|---------------------|
|              |                | e Contraction 2m | 5m                  |
| Туре         | DPU-510        | 31524D-1         | 36213D              |
| Q'TY         | 1              | 1                | 1                   |

| Name of item | Operation manual | Audio system plug | Fuse              | Tapping screw |
|--------------|------------------|-------------------|-------------------|---------------|
|              |                  |                   | ()) <b>4</b> A )) | A COMPANY     |
| Туре         | KDS-5000BB.OM.E  | MP-105LC-RoHS     | FGBO-A-125V-4A    | M6x20         |
| Q'TY         | 1                | 1                 | 3                 | 4             |

## **OPERATION UNIT (DOU-520)**

| Name of item | Operation unit      | Mounting bracket | Tapping screw   |
|--------------|---------------------|------------------|-----------------|
|              | BOLT KG-B2<br>2 PCS |                  | Commune Commune |
| Туре         | DOU-520             | 37376C           | M4x12           |
| Q'TY         | 1                   | 1                | 4               |

## HULL UNIT (DHU-530)

| Name of item | Hull unit | Shaft guides | Gum packing<br>for flange | Crank handle | Damper |
|--------------|-----------|--------------|---------------------------|--------------|--------|
|              |           |              |                           |              |        |
| Туре         | DHU-5301  | ESR-1510     | ESR-1512                  | OB-63        | 34924D |
| Q'TY         | 1         | 3            | 1                         | 1            | 1      |

| Name of item | TD shaft  | Fixing collar | Shift cap | Bolt set             |
|--------------|---|---------------|-----------|----------------------|
|              |   |               |           | Ох в<br>Ох в<br>Ох в |
| Туре         | ESR-1504 (1411mm)<br>ESR-160 32679C-2 (1681mm)<br>ESR-160 32679C-3 (1981mm) | 32681D        | 34378D    | SUS-M16x65-<br>Assy  |
| Q'TY         | 1   | 2             | 1 set     | 1 set                |

| Name of item | Cap bolt  | Grease | Anp base | Binding band | HEX. ROD<br>wrench    |
|--------------|-----------|--------|----------|--------------|-----------------------|
|              |           |        |          |              | 1.5mm<br>2.5mm<br>3mm |
| Туре         | SUS-M4x10 | G-100  | ANP-1    | AB-100-1000  | -                     |
| Q'TY         | 4         | 1      | 2        | 2            | 1 each                |

| Name of item | Transducer<br>unit | Bath cork | HEX. ROD<br>wrench |
|--------------|--------------------|-----------|--------------------|
|              |                    |           | 3mm<br>5mm         |
| Туре         | ESR-1603           | -         | -                  |
| Q'TY         | 1                  | 1         | 1 each             |

## JUNCTION BOX (DJB-540)

| Name of item | Junction box | Fuse                                   | Tapping screw  |
|--------------|--------------|--|----------------|
|              |              | () <u>4A</u> ) x3<br>() <u>8A</u> ) x3 | For<br>DJB-540 |
| Туре         | DJB-540      | FGBO-A-125V-4A                         | SUS-M5x20      |
|              |              | FGBO-A-125V-8A                         |                |
| Q'TY         | 1            | 3 each                                 | 1              |

## CHAPTER 2

## INSTALLATION

This Chapter explains the installation of KDS-5000BB.

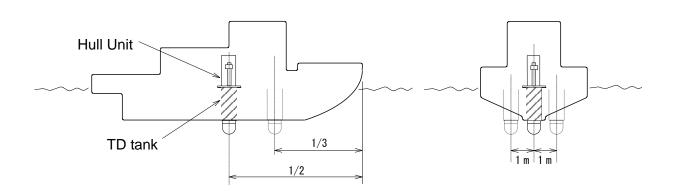
| Installation | Installation Position of Hull Unit             | 11 |
|--------------|--|----|
|              | Dimensions Processor unit (DPU-510)            | 12 |
|              | Dimensions Operation unit (DOU-520)            | 13 |
|              | Dimensions Junction box (DJB-540)              | 14 |
|              | Dimensions Hull unit (DHU-530)                 | 15 |
|              | TD tank  | 16 |
|              | Assembling and Mounting of Hull unit (DHU-530) | 20 |
|              | Mounting Junction Box (DJB-540)                | 27 |
|              | Mounting Processor unit/ Operation unit        | 28 |
|              | Processor unit (Rear Side)                     | 29 |
|              | Wiring Junction Box (DJB-540)                  | 30 |
|              | Hull unit (DHU-530)                            | 30 |
|              | Wiring Warnings                                | 31 |
|              | Wiring between Processor unit and Hull unit    |    |
|              |  | 32 |
|              | Wiring Junction Box (DJB-540)                  | 33 |

Fully discussion and agreement are required with the ship owner and dockyard in deciding the location for the Hull unit. Give careful considerations to the installations.

## **INSTALLATION POSITION of HULL UNIT**

Select an area where noise, interference and bubbles are minimal.

The point at 1/3 to 1/2 of the ship's length from the bow or near the keel is the best. If the Hull unit cannot be installed on the keel, the center of the retraction TD tank should be within 1 meter of the keel.



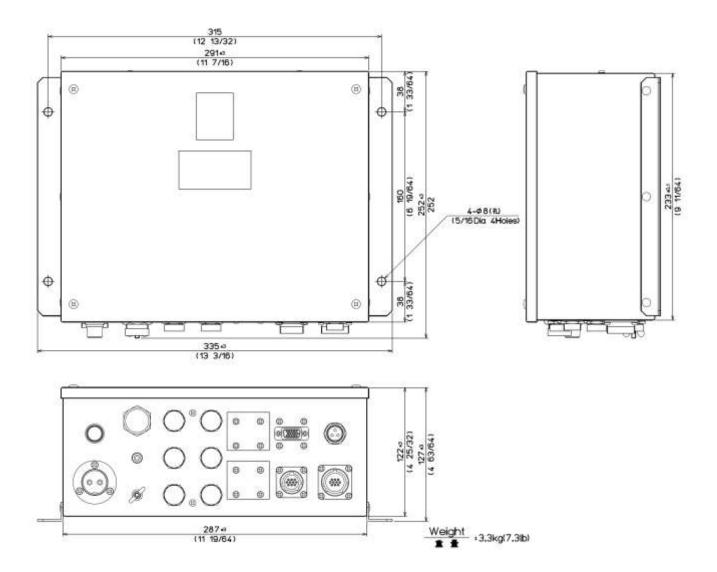


Be sure there are no obstacles to interfere the ultrasonic beam when the Transducer unit is lowered.

Provide sufficient clearance around the TD tank for maintenance and inspection work.

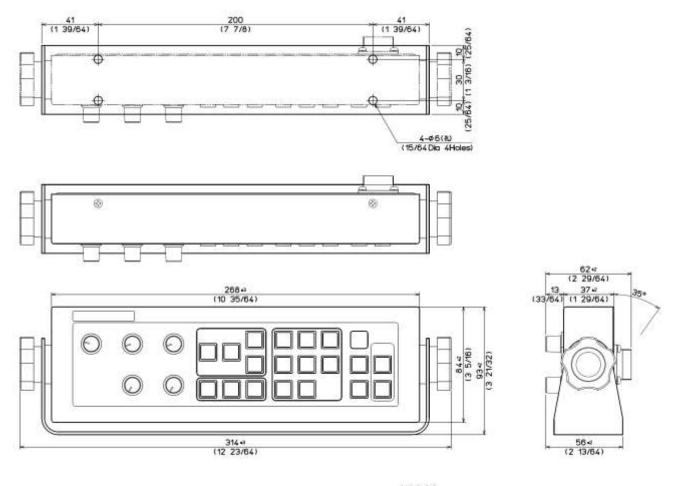
The Bow mark ( $\Delta$ ) on the Flange should be installed facing the bow. However, if this hinders maintenance or inspection, and there is no solution, direct the mark to the opposite (180°) direction, toward the stern.

## **DIMENSIONS: PROCESSOR UNIT (DPU-510)**



Unit: mm (inch)

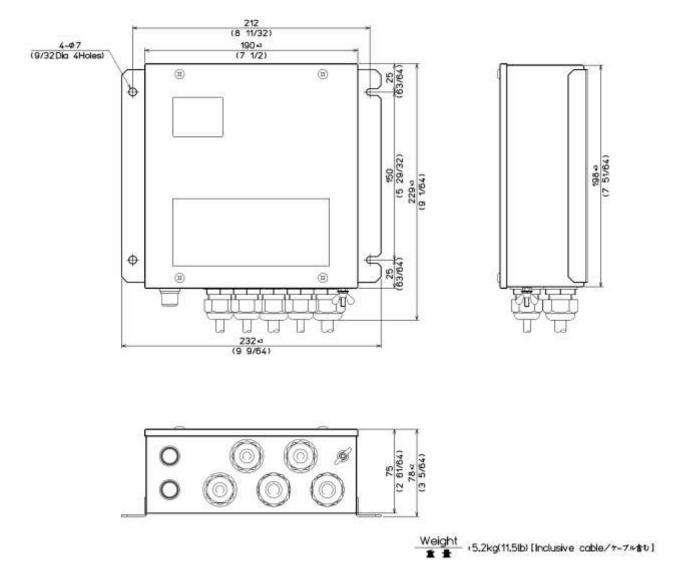
## **DIMENSIONS: OPERATION UNIT (DOU-520)**



Weight +1,1kg(2,5lb) [Inclusive base/₩0含む]

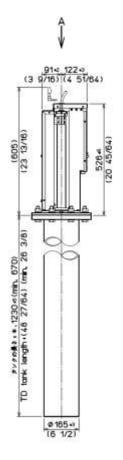
Unit: mm (inch)

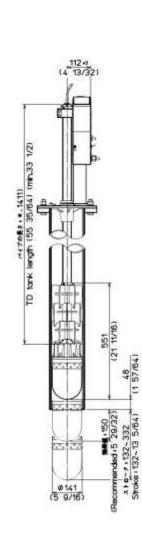
## INSTALLATION DIMENSIONS: JUNCTION BOX (DJB-540)

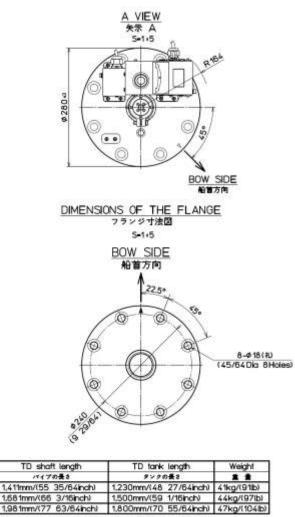


Unit: mm (inch)

## **DIMENSIONS: HULL UNIT (DHU-530)**







1,681mm/(66 3/16inch) 1,981mm/(77 63/64inch) Dimensions in the drawing show 1230 mm TD tank

and 1411 mm TD shaft specifications.

Unit: mm (inch)

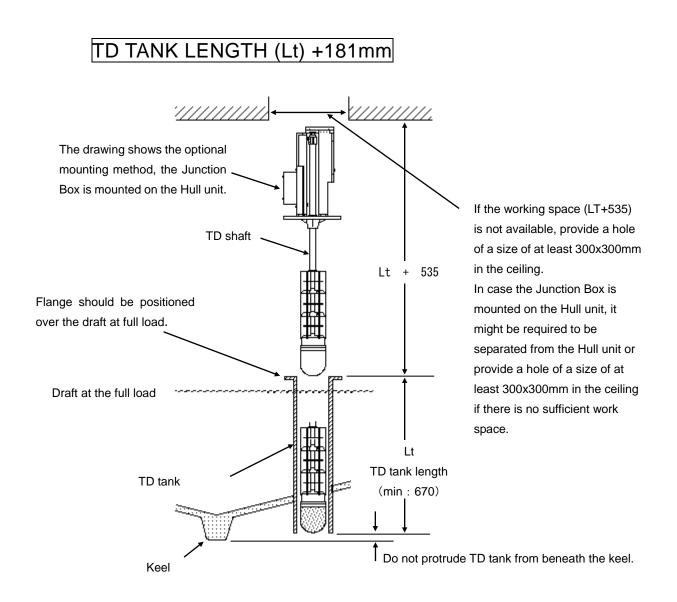
## <u>TD TANK</u>

#### **1. MAINTENANCE SPACE**

When installing the TD tank, pay full attention to the safety (strength, water-tightness, etc.). At the same time, secure a space for maintenance and inspections.

- Since the Hull unit is not a waterproof structure, keep it away from water drops and splashes.

When mounting the TD shaft to the Transducer unit, be sure not to damage the TD shaft thread or twist the Transducer unit cable

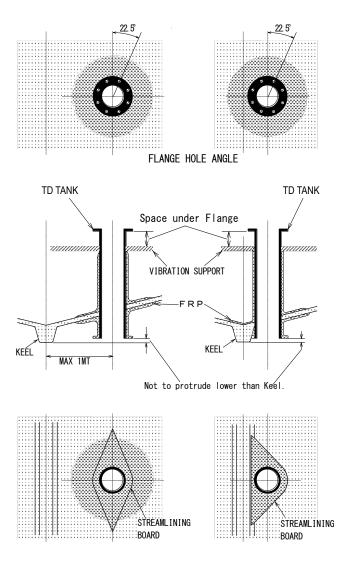


Unit: mm

#### 2. TD TANK INSTALLATION CONDITIONS

Satisfy the following installation conditions.

- Installation point should be 1/3 to 1/2 of the ship's overall length back from the bow.
- If it cannot be installed on the keel, the center of the TD tank should be within 1 meter of the keel.



-There should be no obstacles right below the flange to avoid hindering bolt clamping.

-Do not protrude the TD tank from beneath the keel.

-Flange should be positioned in parallel with the ship's draft and over the draft at full load.

-Apply FRP sufficiently to all the necessary sections to prevent water leakage.

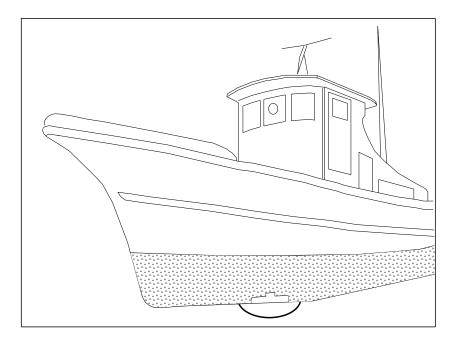
-Make the surrounding of TD tank in a streamline shape and provide a fairing plate to suppress water resistance and generation of air bubbles to the minimum.

-Attach a fin if necessary. Make sure the fin does not hinder bolt clamping for Flange.

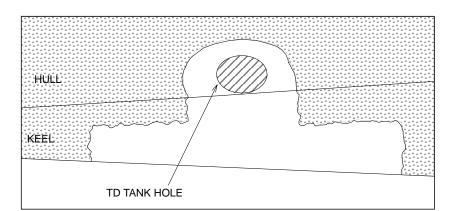


Fully discuss about the strength and water tightness with the ship owner, the engineer in the shipyard, and the installer before determining on the position, the method of installation, and necessary materials. Otherwise it causes maritime accidents.

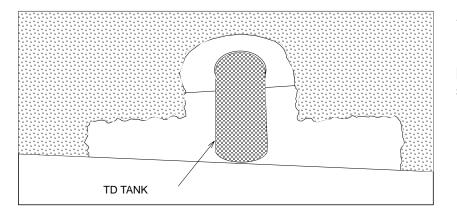
#### 3. TD TANK INSTALLATION EXAMPLES



- Select a location of TD tank. Refer to page 11

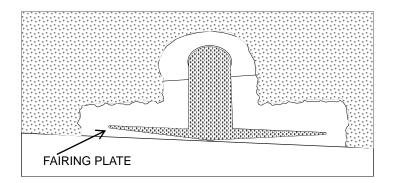


-Make a hole of TD tank diameter in the bottom of ship.

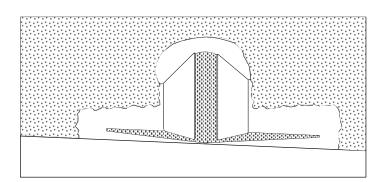


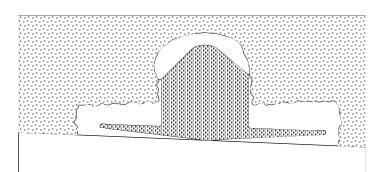
-Install the TD tank.

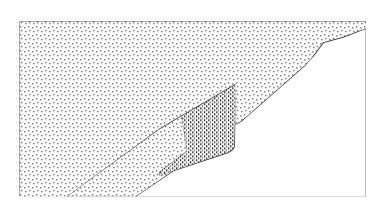
Flange should be positioned in parallel with the ship's draft in sailing.



-Make the surrounding of the TD tank projecting out from the bottom in a stream line shape and provice a fairing plate to suppress water resistance and generation of air bubbles to the minimum.







-Apply FRP sufficiently to all the necessary parts to prevent leakage of water.

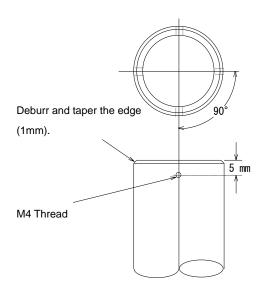
## **ASSEMBLING and MOUNTING of Hull unit (DHU-530)**

#### 1. TD SHAFT

Calculate necessary length of TD shaft (Standard length of 1681mm) from the length of TD tank (Lt) and cut off the unnecessary portion.

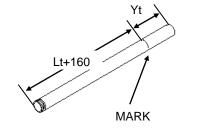
#### TD SHAFT LENGTH = TD TANK LENGTH (Lt) + 181mm

#### 2. TD SHAFT ADJUSTMENT

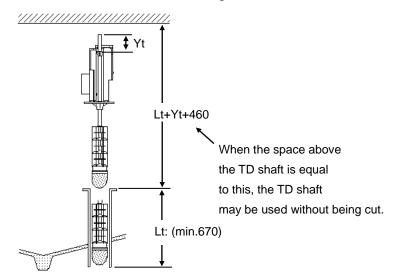


- Cut the TD shaft to the required length, TD tank length (Lt) + 181mm.
- Deburr the cut piece and taper the edge (1mm).
- 3) Bore 4 holes in the TD shaft as follows,
- every 90 degrees
- 5mm from the cut end of the pipe
- hole size of  $\phi$  3.4
- set a tapping screw (M4) on the hole each

In case of sufficient space above the TD shaft it can be used without cutting.



Mark to the point of Lt+160. The upper end of Joint Arm should be united with the Mark and tighten them.



#### 3. ASSEMBLING of the TD shaft and the Transducer unit

#### 1) Screw TD shaft into the Transducer unit.

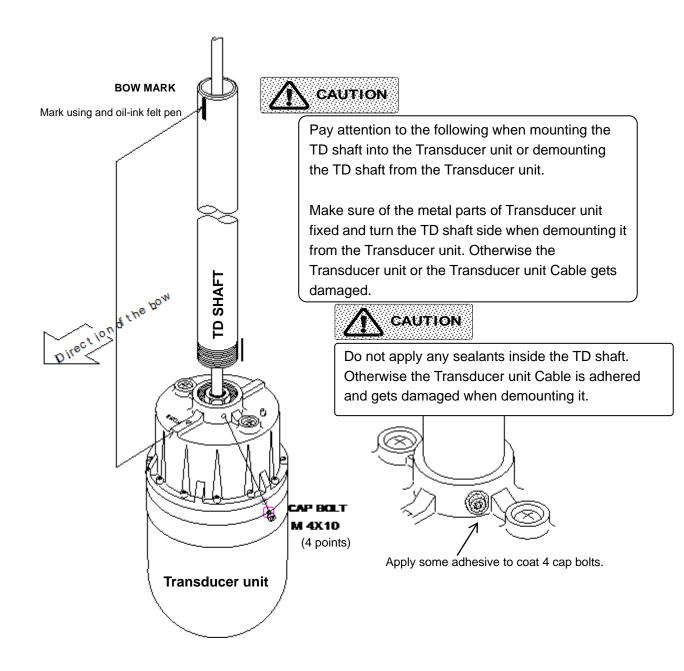
Make sure not to damge the TD shaft or twist the Transducer unit Cable.

Totally wipe dirts and grease from the threaded parts of the Transducer unit and TD shaft.

Apply adhesive, waterproof sealer (Bathcork; supplied) to the threaded parts of the TD shaft.

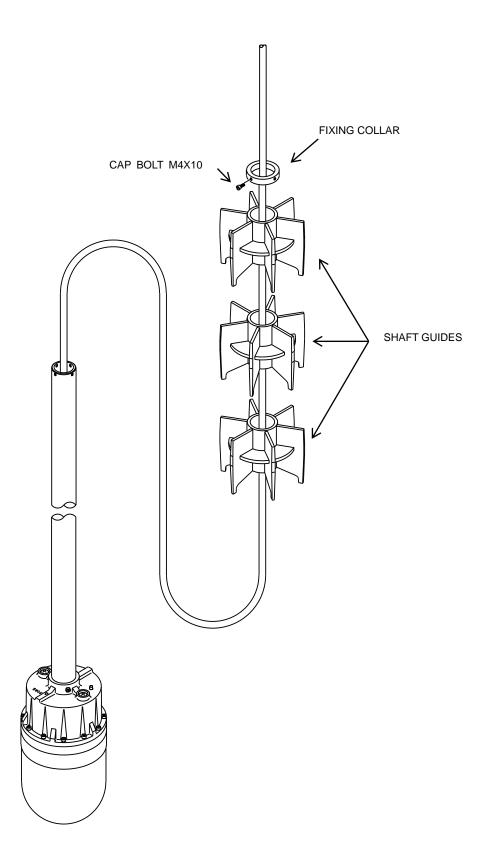
Coat the attached cap bolts with adhesive to prevent an electric corrosion after clamping the TD shaft securely with cap bolts.

Put a Bow Mark with a felt pen at the top end of the TD shaft as shown in the drawing.



### 2) Mount Shaft Guides

Instert the 3 shaft guides as shown in the drawing. Insert Fixing Collar and fix it with the Cap Bolts (2 pcs).



<To be continued>

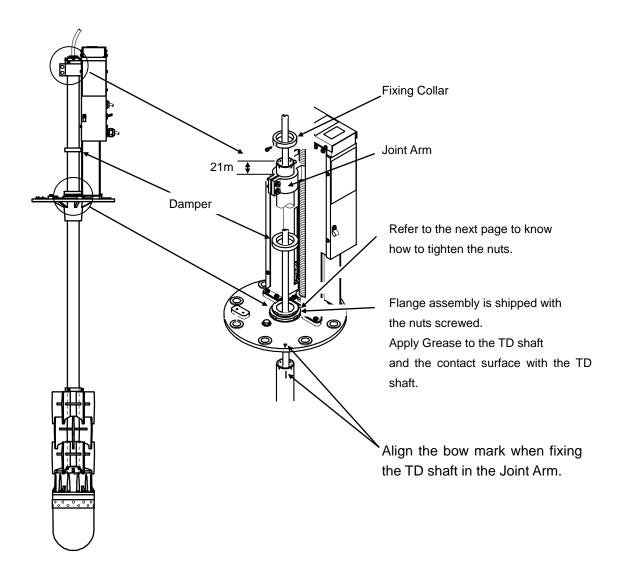
#### 3) Mount the Transducer unit on the Hull unit

-Apply Grease inside the nuts and the Flange.

-Unscrew the nuts. Pass the TD shaft through the Flange assembly. Pass the Damper through and align the bow mark on the Transducer unit with the mark on the Flange assembly. Fix the Joint Arm to the TD shaft.

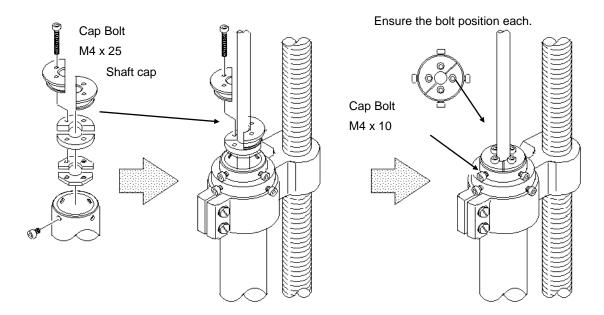
-Take care the position of the Transducer unit bottom is 48mm up from the TD tank bottom.

-Pass the Fixing Collar into the TD shaft and fasten it with the cap bolts (2 pcs).



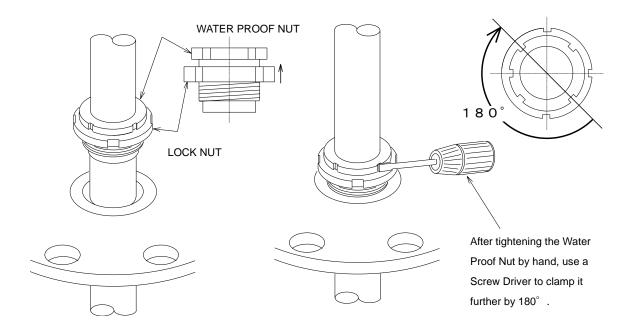
#### 4) Mount the shaft cap at the end of TD shaft

Insert the shaft cap into the TD shaft. Screw it with the cap bolts, M4x25 (4 pcs). Screw the cap bolts, M4x10 (4 pcs) to prevent slip-out of the shaft cap.



#### 5) How to tighten the nuts

Lift up the Lock Nut as shown in the drawing. Place the Waterproof Nut on the Flange opening and tighten it firmly by hand and then make a 180-degree turn with a screwdriver. Take care not to over a 180-degree. This Lock Nut is to protect loosening the Waterproof Nut. Screw the Lock Nut tightly with a screwdriver and a hammer.

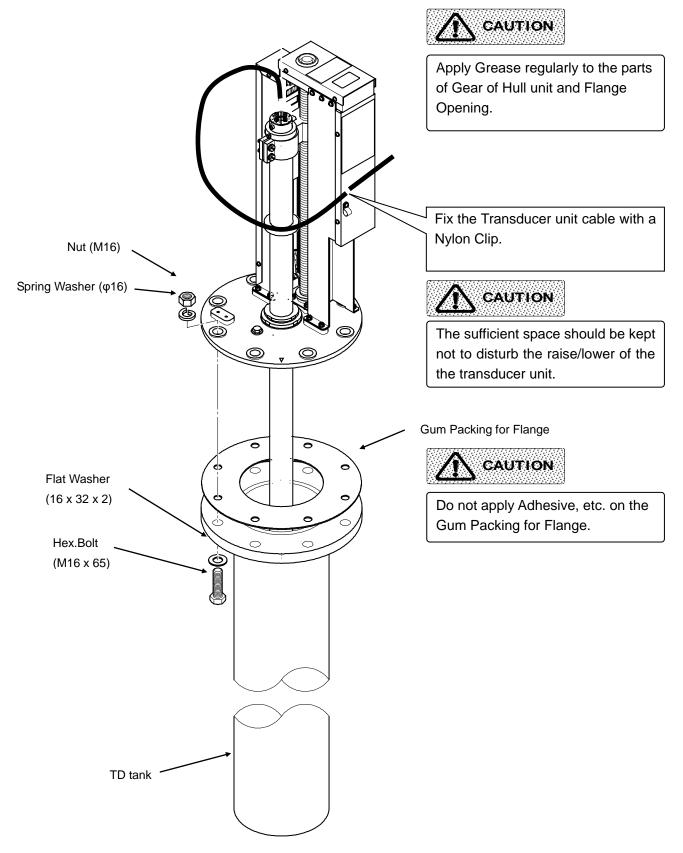


#### 6) Assemble Hull unit with TD tank

Insert Gum Packing between Hull unit and TD tank.

Use 8 Hex.Bolts (M16x65) to fit Hull unit in TD tank.

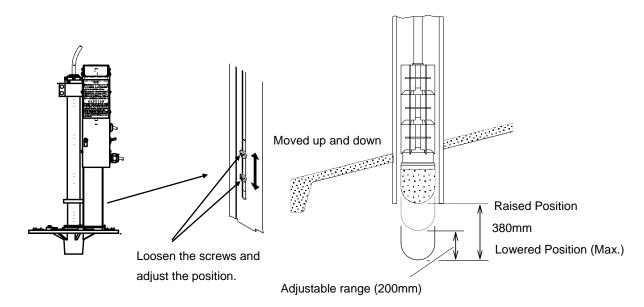
Check the performance of hoisting/lowering of the Transducer unit several times while tentatively clamping with Hex.Bolts and fasten them after the performance is confirmed.



### 4. HOW TO ADJUST HOISTING and LOWERING STROKE

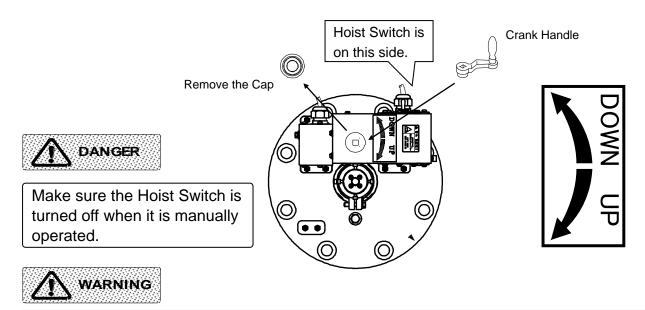
The stroke of hoisting/lowering of the Transducer unit can be adjusted from the minimum, 180mm to the maximum, 380mm by adjusting the switch shown in the drawing.

Find the proper lowering position of the Transducer unit with this Switch.



### 5. MANUAL HOISTING/LOWERING OF TRANSDUCER UNIT

When the Transducer unit cannot be hoisted due to a trouble occurrence, it is possible to raise the Transducer unit with the Crank Handle manually after removing the Cap.



Confirm the voltage between the Flang and the minus terminal of the ship's battery does not exceed 0.65 volts after the installation completed.

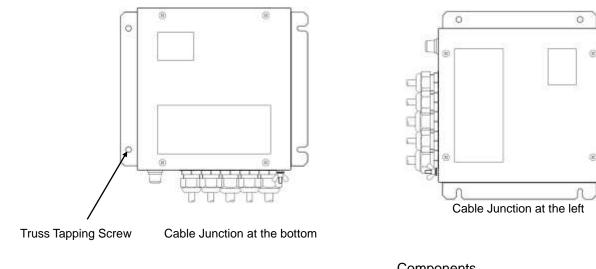
Use the larger diameter cable if the voltage exceeds 0.65 volts. Otherwise the damage to the Transducer unit due to the electrolytic corrosion may results.

## **MOUNTING of JUNCTION BOX (DJB-540)**

The mounting location should be well ventilated and dry.

Avoid locations subject to watersplash or rain. Allow enough service clearance.

The Cable Junction side should be at the bottom side or the left side.



Components Junction Box ------ 1 Truss Tapping Screw ----- 4 (M5x20)

Use the Junction Box (DJB-504) Mounting Kit to joint the Junction Box to the Hull unit if desired.

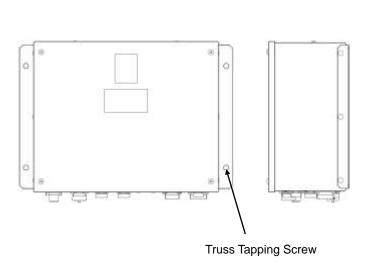
### Option

OP-700: Junction Box Mounting Kit Refer to page 96

## **MOUNTING of PROCESSOR UNIT/ OPERATION UNIT**

#### **PROCESSOR UNIT**

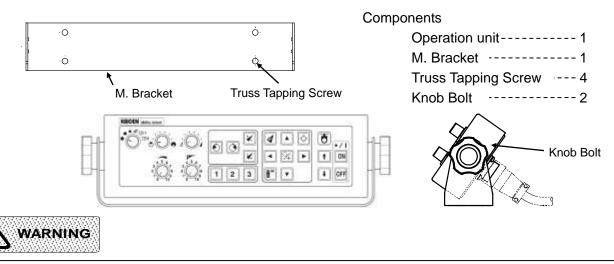
1) Fasten the Processor Unit to the mounting location with 4 Truss Tapping Screws.



Components Processor Unit ----- 1 Truss Tapping Screw ---- 4

#### **OPERATION UNIT**

- 1) Fasten the M. Bracket to the mounting location with 4 Truss Tapping Screws.
- 2) Fit the Operation unit to the M. Bracket with the Knob Bolts adjusting the comfortable viewing angle of the monitor. Fasten the both knob bolts.



The unit should be installed and fixed on a flat surface. Otherwise it may cause the trouble.



Vibration or shock in the mounting area should be minimal.

Locate the unit away from areas subject to water splash or rain.

Otherwise it may causes corrosive trouble.

Locate the unit away from areas subject to heat sources and direct sunlight.

#### Trigger Output Terminal (3P) outputs trigger signals Alarm Terminal (2P) synchronizing to an external USB Terminal for using USB relay contact for an external alarm echo sounder. VGA Output Terminal (OPTION) **Speaker Terminal** connects an external monitor connects an optional speaker. (4Ω). VGA Output Terminal connects an external monitor **Fuse Holder** Power Output Terminal (3P) Use the specified fuse conncets an external monitor Suzuki specified. Output:12VDC as follows, 24V→4A. No.2: shield No.3: -No.1: + **NMEA Output Terminal (6P)** ALARS TRIG C RATINES V 4A to out outputs the data of depth and 0 0 ŵ 0 NAV-IN Terminal (5P) 0 (335) 0 water temperature. MAY TH MEX OUT connects an external g 6 0 (R The Latitude/Longitude of the SUPPLY navigator or NMEA-0183 UCER UNI KEYBOARD 0 0 Target is output when an external SERIACHE OND. TRIG IN signal input. 0 0 495 -650-Navigator connected. 0 0 **Power Input Terminal** Communication Terminal (10P) connects the DC power Earth Terminal connects I/F cable from the supply for activating the Junction Box Display Unit. Use the voltage in the range **Operation unit Connecting Terminal (10P)** 21.6 to 31.2Volts. connects the Operation unit. Sounder Connecting Terminal **Remote Controller Terminal** (7P) connects an external Echo connects a remote controller Sounder. **Trigger Input Terminal (8P)** Input trigger signals synchronizing to an external

# PROCESSOR UNIT (REAR SIDE)

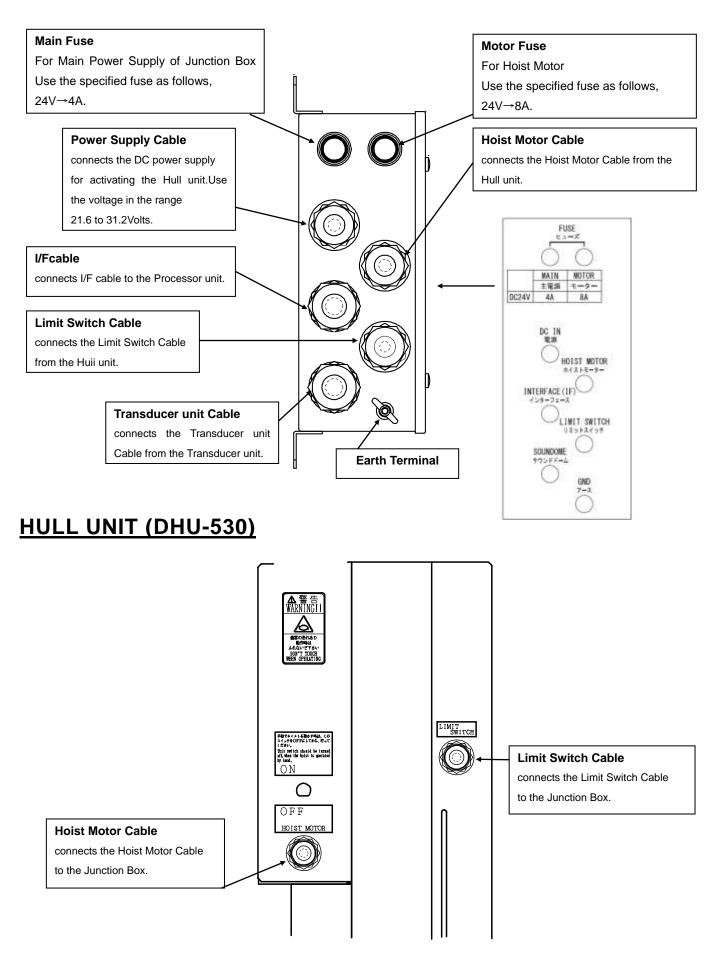
#### The following optional terminals are available.

#### OPTION

| OPTION No.   | Description                     |  |
|--------------|---------------------------------|--|
| ESR-1809-SET | Remote Controller Set           | Connects this terminal when Remote Controller used.                        |
| OP-360       | XGA Connecting Cable            | Connects this terminal when<br>External Monitor used.                      |
| OP-190       | Trigger Output Connecting Cable | Connects this terminal when<br>Trigger output to External Echo<br>Sounder. |

echo sounder.

# WIRING JUNCTION BOX (DJB-540)



## WIRING WARNINGS

Connect the cables to the Hull unit, the Junction Box, the Processor unit or the Operation unit referring to the following instructions.



- The DC Power Supply connected to the main unit each is as follows,

DPU-510Processor unit: 21.6 to 31.2 voltsDJB-540Junction Box: 21.6 to 31.2 volts

Connection of an incorrect power supply may cause fire, electrical shock or damage to the units.

- Use the specified power supply cable. Otherwise fire or generation of heat may result.

- Confirm the voltage between the Flang and the minus terminal of the ship's battery does not exceed 0.65 volts after the installation completed.

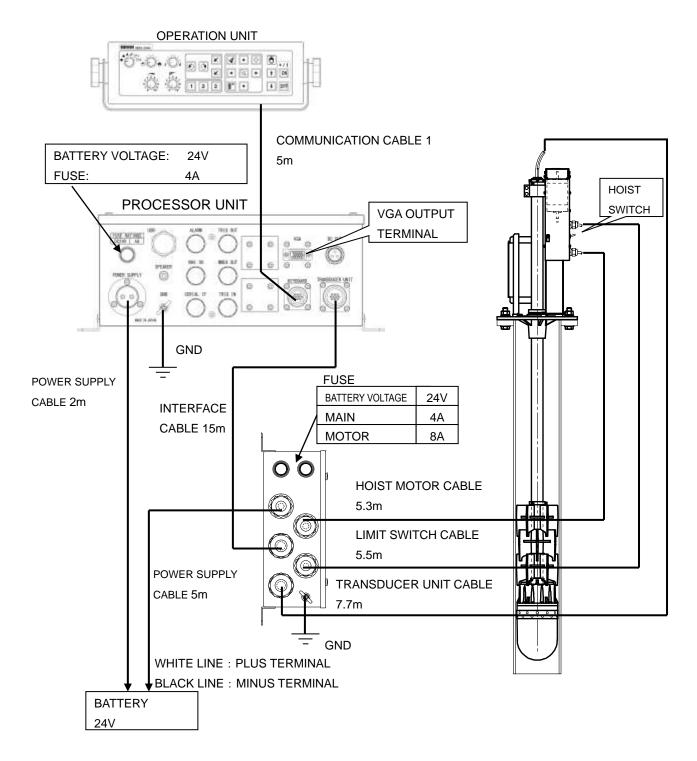
Use the larger diameter cable if the voltage exceeds 0.65 volts. Otherwise the damage to the Transducer unit due to the electrolytic corrosion may results.

-Turn off the power and hold the plug when connecting or disconnecting the cable. Otherwise the cable gets damaged and causes electrical shock or fire.

- Do not bent or twist the cables and not to put the heavy obstacles on the cable. Wiring positions should not disturb the sailing operation or interfere with walking.

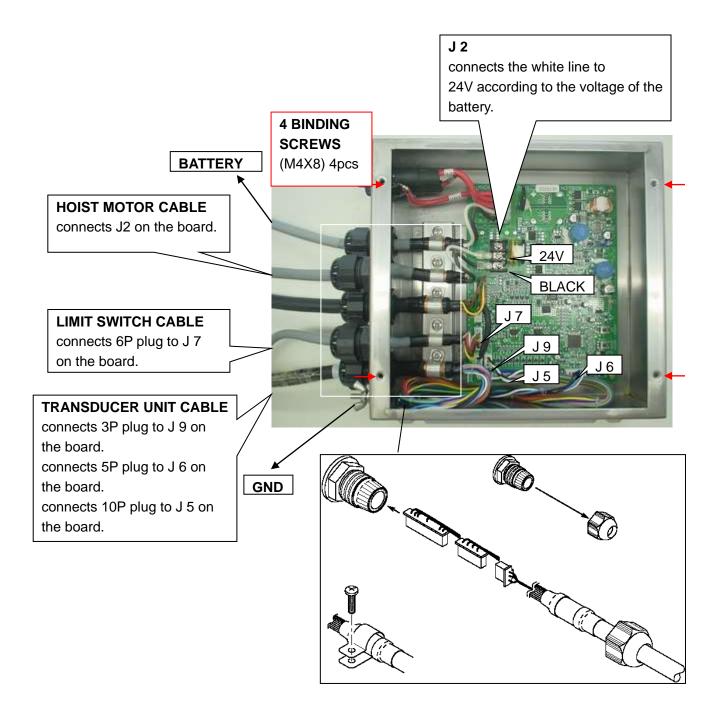
It may cause fire, generation of heat or injury.

## WIRING between DPU-510 and DHU-530



The length of each cable includes a part (up to 60 cm) for drawing inside the main unit.

# WIRING JUNCTION BOX (DJB-540)



# CHAPTER 3

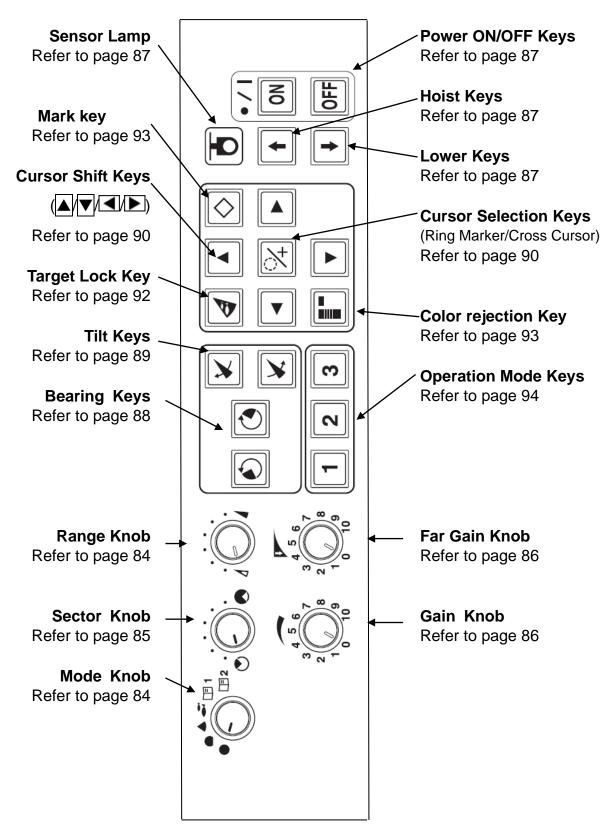
# **BASIC OPERATION**

This Chapter explains the basic operation of KDS-5000BB.

| Operation Panel 35                    |
|---------------------------------------|
| Display Description 36                |
| Sample Display of Sonar Mode 37       |
| Sonar Mode 38                         |
| Sample Display of Bottom-Scan Mode 40 |
| Bottom-Scan Mode 41                   |
| Sample Display of Sounder Mode 42     |
| Sounder Mode 43                       |
|                                       |

# BASIC OPERATION

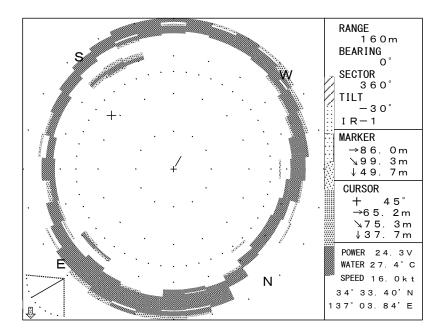
# **OPERATION PANEL**



# **DISPLAY DESCRIPTION**

The drawing below shows the typical sonar mode display.

Various combination displays are available by selecting the Sub-Display menu and the change of the Mode Knobs.



#### SCREEN LEFT

- SONAR MODE
- OFF-CENTER MODE
- BOTTOM-SCAN MODE
- SOUNDER MODE

Use the MODE KNOB to select the display mode.

### SCREEN RIGHT

- MENU 1 & SELF CHECK
- MENU 2 & SELF CHECK
- INFORMATION
- SUB-DISPLAYS

Use the MODE KNOB to select MENU 1 & 2. INFORMATION/SUB-DISPLAYS can be set via MENU 2.

#### MENU1 ( [ 1)

Select the desired 8 ranges.

#### MENU 2 (3)

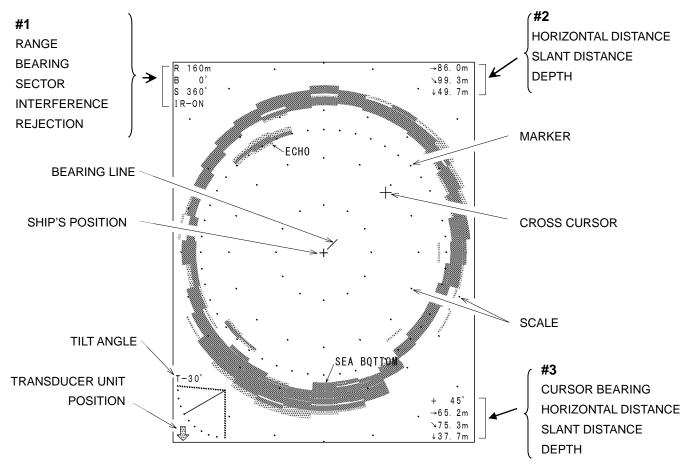
Select the desired user settings.

#### SUB-DISPLAYS

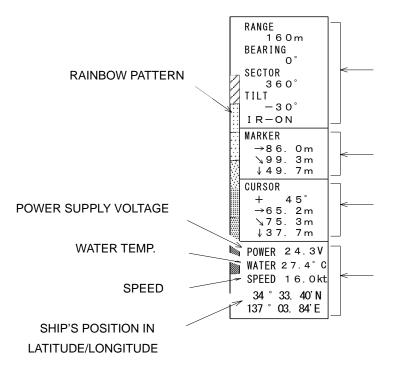
Select the desired sub-display with MENU 2 In case "SUB-DISPLAY – NO SUB DISPLAY" selected the display mode in the left side can be displayed on the whole screen. Refer to page 58

# SAMPLE DISPLAY of SONAR MODE

Select **MODE KNOB (** ) to display SONAR MODE or **MODE KNOB (** ) to display OFF-CENTER MODE.



#### INFORMATION DISPLAY



# When the Sub menus other than INFORMATION selected,

They are displayed in the upper left of the Sonar Display (#1). Tilt angle is displayed in the lower left.

"IR-ON" is not displayed when

INTERFERENCE REJECTION OFF selected. They are displayed in the upper right of Sonar Display (#2).

They are displayed in the lower right of Sonar Display (#3).

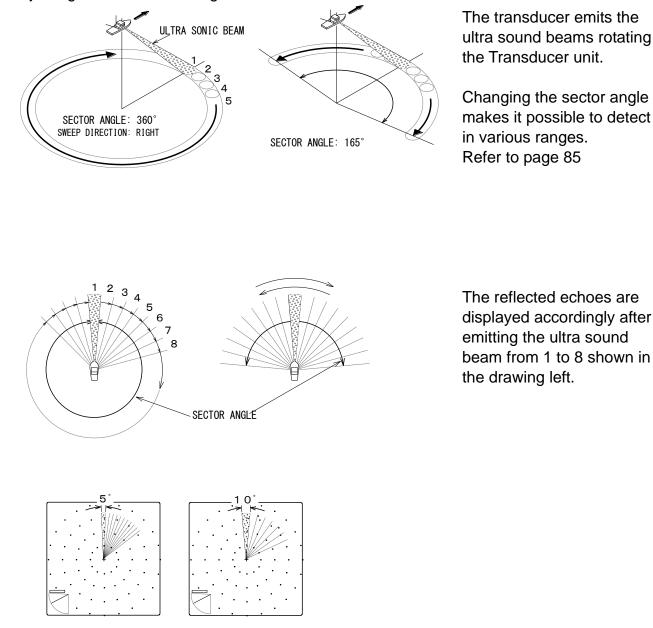
They are display in the lower right corner of Sub-Display.

An External Navigator is required to display the ship's position and the speed.

# SONAR MODE

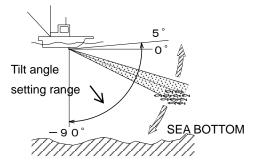
Rotating the transducer in the Transducer unit protruded from the ship's bottom, the ultra sound beams are sent out and detects the targets in accordance with the selected speed and the range (distance).

The reflected sound appears on the PPI depending on the transducer's sweep. Adjusting the Tilt and Bearing the sonar beam can be trained from the surface to the bottom.



The transducer rotates with the selected step angle.

The reflected echoes are displayed as the image every step accordingly. The step angle can be selected in **MENU 2 – "STEP (SONAR)**". Refer to page 63 A narrow step gives a more detailed image on the screen, however more sweep time is requested than a wide step The Tilt angle can be set in increments of 1° from 0° to 5° to 0° to -90°. All directions from extremely shallow waters to deep areas can be searched. Adjust the tilt angle considering the conditions such as ship's speed and water depth.

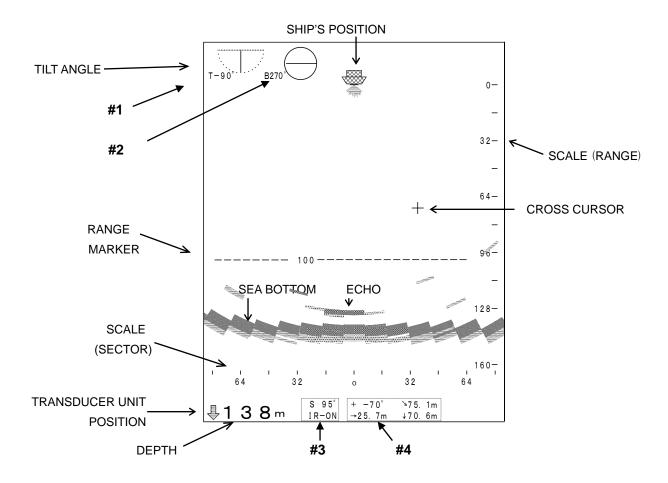


The below drawing illustrates the fish school is displayed on the screen when the ship reaches the point A, but it is not displayed at the point B even if the same tilt angles are set. Select an appropriate tilt angle in order to display the fish school at the point B.

SEA BOTTOM TIMAT INT

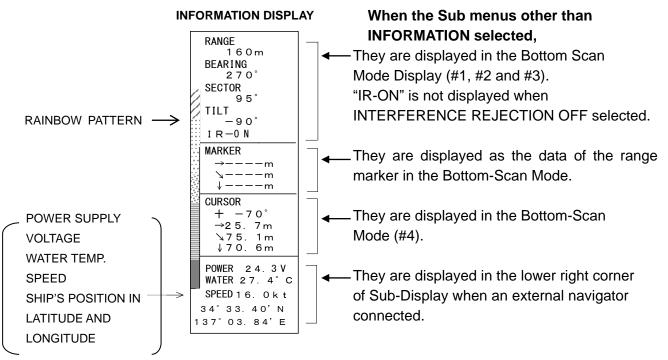
The setting of the tilt angle is available in the Sonar Mode, Bottom-Scan Mode or Sounder Mode. Refer to page 89

# SAMPLE DISPLAY of BOTTOM-SCAN MODE



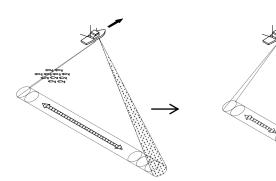
Select **MODE KNOB** ( **)** to display the BOTTOM-SCAN MODE.

The above values of #1, #2, #3 and #4 are not displayed when the Sub-Display menu, INFORMATION is active.



# **BOTTOM-SCAN MODE**

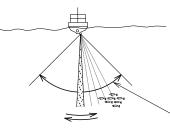
Shaking the transducer in the Transducer unit protruded from the ship's bottom right and left alternately, it sends out the ultra sound beams and displays the images of the middle layer and the sea-bottom contour.



The transducer emits the ultra sound beams sweeping the transducer right and left.

The reflected echoes are displayed accordingly after emitting the ultra sound beam.

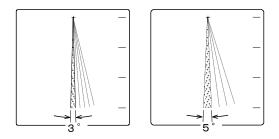
SECTOR ANGLE: 95°





Changing the sector angle makes it possible to detect both the narrow and the wide ranges. Refer to page 85

Changing the tilt angle makes it possible to detect the area of the selected sector angle centering the tilt angle. Refer to page 89



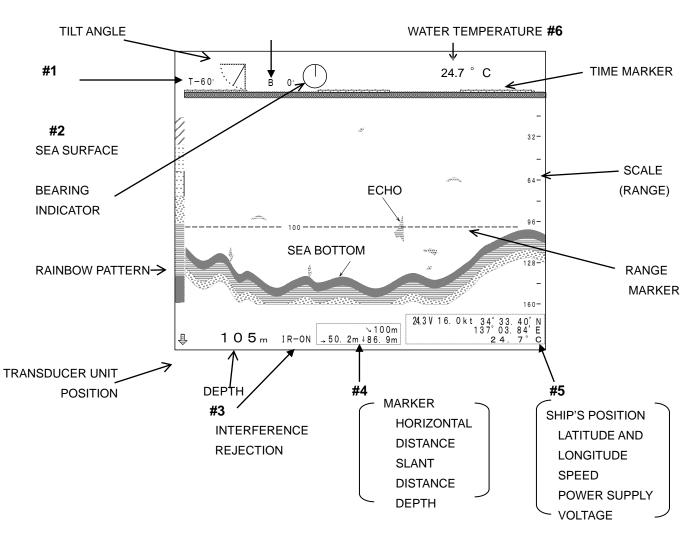
The transducer moves with the selected step angle.

The reflected echoes are displayed as the image every step accordingly.

The step angle can be selected in **MENU 2 – "STEP (BOTTOM-SCAN)**". Refer to page 63

# SAMPLE DISPLAY of SOUNDER MODE

Select MODE KNOB ( 🖨 ) to display the SOUNDER MODE.

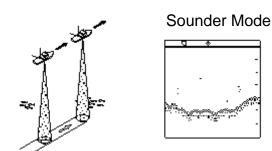


The above values of #1, #2, #3, #4, #5 and #6 are not displayed when the Sub-Display, INFORMATION display is active. The depth display is available only when the tilt angle  $-90^{\circ}$  set.

|                    | INFORMATION DISPLAY  | When the Sub menus other than                      |
|--------------------|--|--|
|                    | RANGE  | INFORMATION selected,                              |
|                    | BEARING  | They are displayed in the Sounder Mode             |
|                    | SECTOR   | Display (#1, #2 and #3).                           |
|                    | TILT   | "IR-ON" is not displayed when                      |
|                    | - 6 0 °  | INTERFERENCE REJECTION OFF selected.               |
|                    |  | They are displayed as the data of the range        |
|                    | $   MARKER  \rightarrow 100 m                                $ | marker in the Sounder Mode Display (#4).           |
| VOLTAGE            | ∖ 50.2m<br>↓ 86.9m   |  |
| WATER TEMP.        | CURSOR   | ——They are not displayed in the Sounder            |
| SPEED              | $\begin{vmatrix} + & \\ \rightarrow &m \end{vmatrix}$          | Mode Display.                                      |
| SHIP'S POSITION IN | \m   | mode Diepidy.                                      |
| LATITUDE AND       |  | —— They are displayed in the lower right corner of |
|                    | POWER 24.3V  | Sub-Display (#5). The latitude/longitude and       |
|                    | SPEED 16.0kt   |  |
|                    | 34°33.40'N<br>137°03.84'E                                      | the speed of the ship are displayed only when      |
|                    | 107 03.04 E  | an external navigator connected.                   |

# SOUNDER MODE

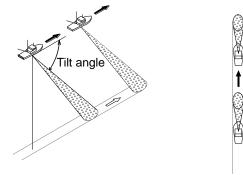
The transducer in the Transducer unit protruded from the ship's bottom sends out the ultra sound beams and displays the images of the middle layer and the sea-bottom contour, which are just beneath the ship.



Detects beneath the ship.

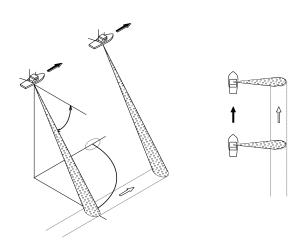
The transducer emits the ultra sound beams toward the bottom just beneath the ship and the images are displayed like the Echo Sounder. The beam width is different depending on the frequency.

Detects fore by changing the tilt angle



The images other than beneath the ship can be displayed by changing the tilt angle and the bearing. Refer to page 88/89/90

Detects starboard by changing the tilt angle and the bearing.



# CHAPTER 4

# FUNCTION SETTINGS

This Chapter explains the function settings of KDS-5000BB. Select the appropriate setting for performing to the utmost of its ability before use.

| Factory Settings       |  | 46   |
|------------------------|--|------|
| Menu                   | Menu 1                                     | 48   |
|                        | Menu 2                                     | 49   |
| Function Settings      |  | 51   |
| Function Set           | Gain Up                                    | 52   |
|                        | TVG Curve                                  | 53   |
|                        | Dynamic Range                              | 54   |
|                        | Pulse Width                                | 54   |
|                        | TX Power                                   | 55   |
|                        | RX Gain Reduction                          | 55   |
|                        | RX Bandwidth                               | 56   |
|                        | Full-Screen Gain Set                       | 56   |
| Rejection              |  | 57   |
| Display Item Selection | Sub-Display                                | 58   |
|                        | Step (Sonar)                               |      |
|                        | Step (Bottom-Scan)                         |      |
|                        | Off-Center Position                        |      |
|                        | Scale Dots                                 | -64  |
|                        | Compass Display                            |      |
|                        | Heading Display                            |      |
|                        | Track Display                              | - 65 |
|                        | Track Sub Range                            |      |
|                        | Track Mem.Interval (Track Memory Interval) | 66   |
|                        | Press Rate (Compressed Rate)               |      |
|                        | Filter                                     |      |
|                        | Sub Bottom-Scan                            | - 67 |
|                        | Cursor Direction                           | - 67 |
|                        | Cursor Position                            | - 67 |

| Others             | Audio Level<br>Target Lock<br>Trigger Signal<br>Depth Unit | - 69<br>- 70 |
|--------------------|--|--------------|
|                    | Temp. Unit (Temperature Unit)                              | 71           |
|                    | Temp. Adjust (Temperature Adjustment)                      |              |
|                    | Speed Unit   |              |
|                    | Auto Retract   |              |
|                    | Train Correct  |              |
|                    | Panel Brightness   |              |
|                    | Power Supply Frequency                                     |              |
|                    | TD Auto Down   |              |
|                    | Ope. Mode Memory   | - 75         |
| Color Palette      | Color Sel. (Color Selection)                               |              |
|                    | Color (Display Colors)                                     | - 76         |
| Remote Control Set |  | 78           |
| Frequency Setting  |  | 79           |
|                    | RX Frequency   | 79           |
| Self Check         |  | 80           |
| Maintenance        | Update   |              |
|                    | Backup   |              |
|                    | Recovery   |              |
|                    | Version  | - 82         |

# FACTORY SETTINGS

# FACTORY SETTINGS

The factory settings are shown in the below box. Select the desired settings before use.

| FUNCTION SETTINGS     | FACTORY SETTINGS (shown in AA)              | Referring page |
|-----------------------|---|----------------|
| FUNCTION SET          |   | MENU 2         |
| GAIN UP               | OFF • +10dB • +20dB • +30dB • +40dB • +50dB | PAGE 51-56     |
| TVG CURVE             | OFF · 10LOG · 20LOG · <u>30LOG</u> · 40LOG  |                |
| DYNAMIC RANGE         | 1 dB · 2 dB · 3 dB                          |                |
| PULSE WIDTH           | $\overline{X1} \cdot X1.5 \cdot x2$         |                |
| TX POWER              | A · B · C · D                               |                |
| RX GAIN RED.          |   |                |
| RX BANDWIDTH          | S. WIDE · WIDE · STANDARD                   |                |
|                       | NARROW · S. NARROW                          |                |
| FULL –SCREEN GAIN SET |   |                |
| REJECTION             |   | PAGE 57        |
| INTERFERENCE REJ      | OFF · ON                                    |                |
| DISP ITEM SEL         |   | PAGE 58-67     |
| SUB-DISPLAY           | NO SUB-DISP. • INFO • HISTORICAL • + PRESS  |                |
|                       | +A-SCOPE · BOTTOM · TRACK · EXTSOUNDER      |                |
| STEP (SONAR)          | 5°• 10° • 15°• 20°                          |                |
| STEP (BOTTOM-SCAN)    | 3° • 5°                                     |                |
| OFF-CENTER POS.       | FORE · BACK · LEFT · RIGHT                  |                |
| SCALE DOTS            | OFF · ON                                    |                |
| COMPASS DISP.         | OFF · ON                                    |                |
| HEADING DISP.         | OFF · ON                                    |                |
| TRACK DISP.           | OFF · ON                                    |                |
| TRACK SUB RANGE       | 50m (10-500 depth unit)                     |                |
| TRACK MEM. INTERVAL   | 5 SEC · 10 SEC · 30 SEC · 60 SEC            |                |
| PRESS RATE            | 1/2 · <u>1/4</u> · 1/8 · 1/16               |                |
| FILTER                | OFF · 1 · 2                                 |                |
| SUB BOTTOM-SCAN       | AUTO · MANUAL                               |                |
| CURSOR DIRECTION      | R-DIRECTION · T-DIRECTION                   |                |
| CURSOR POSITION       | DISTANCE · LAT/LONG                         |                |
| OTHERS                |   | PAGE 68-75     |
| AUDIO LEVEL           | 0 (0-31)                                    |                |
| TARGET LOCK           | MODE0 · MODE1 · MODE2 · MODE3               |                |
| TRIGGER SIGNAL        | INTERNAL · EXTERNAL                         |                |
| DEPTH UNIT            | m · ft · fm · br                            |                |
| TEMP. UNIT            | °C · °F                                     |                |
| TEMP. ADJUST          | +0.0°C ( -9.9° ~ +9.9°)                     |                |
| SPEED UNIT            | kt · km/h                                   |                |
| AUTO RETRACT          | OFF • 1kt (1~27km/h or 1kt ~15kt)           |                |
| TRAIN CORRECT         | <u>0°</u> (0°- 355°)                        |                |
| PANEL BRIGHTNESS      | <u>15</u> (0 - 15)                          |                |
| POWER S. FREQUENCY    | 120k · 125k · 130k                          |                |
| TD AUTO DOWN          | OFF · ON                                    |                |
| OPE.MODE MEMORY       | OFF · ON                                    |                |

| COLOR PALETTE     |                                   | MENU 2     |
|-------------------|-----------------------------------|------------|
| COLOR SEL.        | A-1 · A-2 · B-1 · B-2 · C-1 · C-2 | PAGE 76-77 |
| COLOR             | 8 · 16                            |            |
| FREQUENCY SETTING |                                   | PAGE 79    |
| TX FREQUENCY      | 180.0kHz (±10kHz / 0.1kHz UNIT)   |            |
| RX FREQUENCY      | 180.0kHz (±10kHz / 0.1kHz UNIT)   |            |
|                   |                                   |            |

# <u>MENU</u>

# MENU 1 " 🕒 1 " (RANGE SETTING MENU)

Select the display range in 8 settings according to the depth desired.

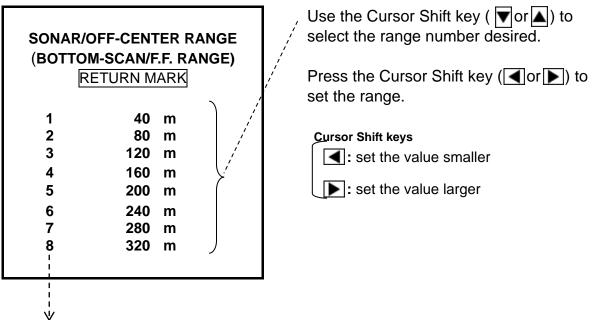
The following menu appears after selecting " **I** " with the MODE KNOB.

RANGE SET MENU SONAR/OFF-CENTER RANGE BOTTOM-SCAN/F.F. RANGE

Use the Cursor Shift key  $\bigtriangledown$  or  $\blacktriangle$  to highlight the item to change.

Press the Cursor Selection key O/+ to display the following range setting menu.

The range can be set freely as desired every 10 units of depth measurement until 2000 units in case of the units, meters, braccia, and fathoms and every 20 feet until 6000 feet in case of the unit, feet.



These numbers correspond to the Range Knob numbers.

The initial range setting values of both ranges are different each. Displayed unit of depth measurement can be set via MENU 2 -"**OTHERS**". Refer to page 71

The way of the range setting is the same for both ranges, but the values of range setting are not corresponded each other. The settings for both ranges are required.

In the range settings for SONAR/OFF-CENTER MODE, the range is changed in accordance with the value of SONAR MODE when the Cursor Shift key ( for ) pressed. However, 1.5 times of range of SONAR MODE is displayed when OFF-CENTER MODE selected.

# MENU 2 " 1 2" (FUNCTION SETTING MENU)

Customize the functions to suit individual needs before using the KDS-5000BB. The basic settings are as follows.

| FUNCTION SET             | GAIN UP                |
|--------------------------|------------------------|
|                          | TVG CURVE              |
|                          | DYNAMIC RANGE          |
|                          | PULSE WIDTH            |
|                          | TX POWER               |
|                          | RX GAIN RED.           |
|                          | RX BANDWIDTH           |
|                          | FULL-SCREEN GAIN SET   |
|                          |                        |
| REJECTION                | INTERFERENCE REJECTION |
| DISP ITEM SEL            | SUB-DISPLAY            |
| (DISPLAY ITEM SELECTION) | STEP (SONAR)           |
|                          | STEP (BOTTOM-SCAN)     |
|                          | OFF-CENTER POSITION    |
|                          | SCALE DOTS             |
|                          | COMPASS DISPLAY        |
|                          | HEADING DISPLAY        |
|                          | TRACK DISPLAY          |
|                          | TRACK SUB RANGE        |
|                          | TRACK MEMORY INTERVAL  |
|                          | PRESS RATE             |
|                          | FILTER                 |
|                          | SUB BOTTOM-SCAN        |
|                          | CURSOR DIRECTION       |
|                          | CURSOR POSITION        |
| OTHERS                   | AUDIO LEVEL            |
|                          | TARGET LOCK            |
|                          | TRIGGER SIGNAL         |
|                          | DEPTH UNIT             |
|                          | TEMPERATURE UNIT       |
|                          | TEMPERATURE ADJUST     |
|                          | SPEED UNIT             |
|                          | AUTO RETRACT           |
|                          | TRAIN CORRECT          |
|                          | PANEL BRIGHTNESS       |
|                          | POWER SUPPLY FREQUENCY |
|                          | TD AUTO DOWN           |
|                          | OPERATION MODE MEMORY  |
|                          |                        |

## MENU

| COLOR PALETTE      | COLOR SEL.   |
|--------------------|--------------|
|                    | COLOR        |
| REMOTE CONTROL     |              |
| FREQUENCY SETTINGS | TX FREQUENCY |
|                    | RX FREQUENCY |
| SELF CHECK         |              |
| MAINTENANCE        | UPDATE       |
|                    | BACK UP      |
|                    | RECOVERY     |
|                    | VERSION      |

For further details see next pages.

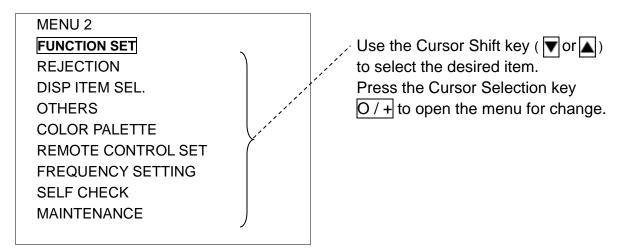
# FUNCTION SETTINGS

Turn the MODE KNOB to " T 2" to display the below menu.

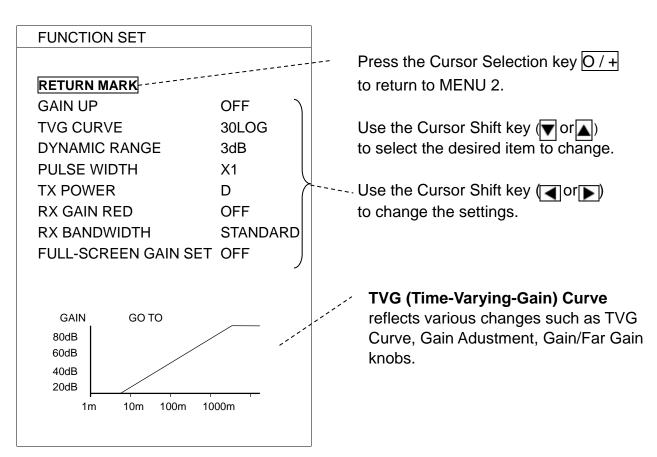
The item currently selected is highlighted.

Use the Cursor Shift key ( $\bigtriangledown$  or  $\bigtriangleup$ ) to select the desired item.

Press the Cursor Selection key O/+ to open the menu for change.



# FUNCTION SET MENU

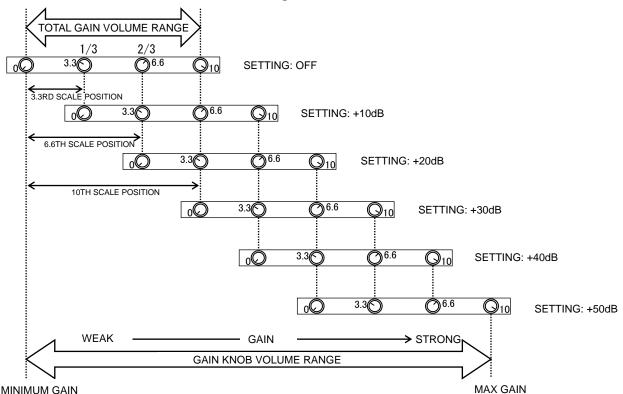


### 1. GAIN UP

This function makes it possible to display a clearer picture of the full range and control the sensitivity at various depths.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "GAIN UP". Use the Cursor Shift key ( or ) to change the setting.

GAIN UP OFF ------Use the Cursor Shift key ( [OFF, +10dB, +20dB, +30dB, +40dB, +50dB]

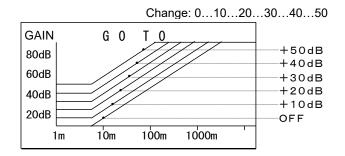


MINIMUM GAIN

The "sensitivity" or possibly "volume" is increased 3.3 times when the gain setting is changed to "+10dB" from "OFF".

The reflected image at level "3.3" in the gain setting "OFF" is the one at level "0" in the Gain setting "+10dB".

TVG Curve changes in accordance with the change of the values of GAIN UP.



The setting values shown in the above drawing are as follows, Gain Knob: 0 Far Gain Knob: 0 TVG Curve: 30LOG

## 2. TVG CURVE

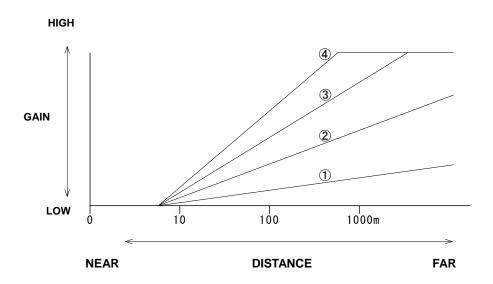
TVG (Time Variable Gain) offsets the effects of propagation loss of sound as it passes through the water. To counter this loss, the TVG curve is adjusted by correctly set.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "**TVG CURVE**". Use the Cursor Shift key (  $\checkmark$  or  $\blacktriangleright$ ) to change the setting.

**TVG CURVE** 30LOG ----- Use the Cursor Shift key ( or ) to change. [OFF, 10LOG, 20LOG, 30LOG, 40LOG]

#### TVG CURVE

OFF: No TVG curve 10LOG:(1) in the below drawing 20LOG:(2) in the below drawing 30LOG:(3) in the below drawing 40LOG:(4) in the below drawing



## NOTE!

Caution should be taken to select the TVG curve of which TVG setting is related to the Gain Knob functions.

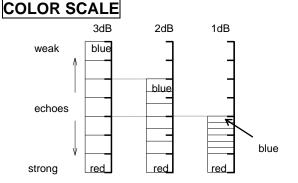
## **3. DYNAMIC RANGE**

This is the way to display the reactions with emphasis or with density discrimination.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**DYNAMIC RANGE**". Use the Cursor Shift key ( $\bigcirc$  or  $\triangleright$ ) to change the setting.

DYNAMIC RANGE 3dB ----- Use the Cursor Shift key (▲or ►) to change. [1dB, 2dB, 3dB]

#### \_\_\_\_\_



The selected level is reflected to the Color Scale as shown in the left.

The weaker reflections are eliminated and the stronger reflections are displayed when selecting rather 2dB than 3dB or 1dB than 2dB.

## 4. PULSE WIDTH

This is the way to select the transmitted pulse width.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "**PULSE WIDTH**". Use the Cursor Shift key ( $\checkmark$  or  $\blacktriangleright$ ) to change the setting.

PULSE WIDTHx1-----Use the Cursor Shift key (or ) to change.[x1, x1.5, x2]

x1 : standard (shown in the below box)

x 1.5 : 1.5 times of standard

x 2 : 2 times of standard for longer range detection

| RANGE (m) | PULSE WIDTHE (ms) |
|-----------|-------------------|
| 0 - 59    | 0.25              |
| 60 - 79   | 0.40              |
| 80 - 99   | 0.75              |
| 100 - 119 | 0.90              |
| 120 - 159 | 1.00              |

| RANGE (m) | PULSE WIDTHE (ms) |
|-----------|-------------------|
| 160 - 199 | 1.25              |
| 200 - 239 | 2.00              |
| 240 - 399 | 2.50              |
| 400 - up  | 3.75              |

### 5. TX POWER

The output power of the ultra sound wave from the transmitter can be set.

Use the Cursor Shift key (  $\blacksquare$  or  $\blacksquare$  ) to select "**TX POWER**". Use the Cursor Shift key ( $\blacksquare$  or  $\blacktriangleright$ ) to change the setting.

**TX POWER D** ----Use the Cursor Shift key ( or ) to change.

[A, B, C, D]

D is the maximum level and A is the minimum level.

#### 6. RX GAIN REDUCTION

Reduction of RX gain to weaken too strong reaction in the shallow water can be set.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "**RX GAIN REDUTION**". Use the Cursor Shift key (  $\triangleleft$  or  $\triangleright$ ) to change the setting.

**RX GAIN RD. OFF** Use the Cursor Shift key ( or ) to change. [ON, OFF]

**ON:** reduces the RX gain.

\_OFF: no change.

## 7. RX BANDWIDTH

RX bandwidth can be set.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**RX BANDWIDTH**". Use the Cursor Shift key (  $\checkmark$  or  $\blacktriangleright$ ) to change the setting.

**RX BANDWIDTH STANDARD** ----- Use the Cursor Shift key ( I or ) to change. [S. WIDE, WIDE, STANDARD, NARROW, S. NARROW]

## NOTE!

Selecting wider bandwidth makes the resolution higher, but more noise. Selecting narrower bandwidth makes the resolution lower, but less noise.

### 8. FULL-SCREEN GAIN SET

Select full gain function ON or OFF when changing the gain knob.

Use the Cursor Shift key (  $\frown$  or  $\blacktriangle$  ) to select "FULL-SCREEN GAIN SET". Use the Cursor Shift key ( $\frown$  or  $\triangleright$ ) to change the setting.

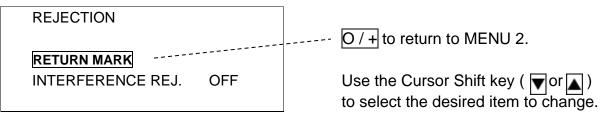
**FULL-SCREEN GAIN SET ON** ON Use the Cursor Shift key ( or ) to change. [ON, OFF]

- **ON:** the gain is changed on the full screen at the same time when changing the gain knob.

- **OFF:** the gain is changed from the point of changing the gain knob.

## **REJECTION**

#### [MODE KNOB – 1 2- REJECTION]



Use the Cursor Shift key ( I or ) to change the settings.

#### **1. INTERFERENCE REJECTION**

This function can be used to eliminate noise from other ships.

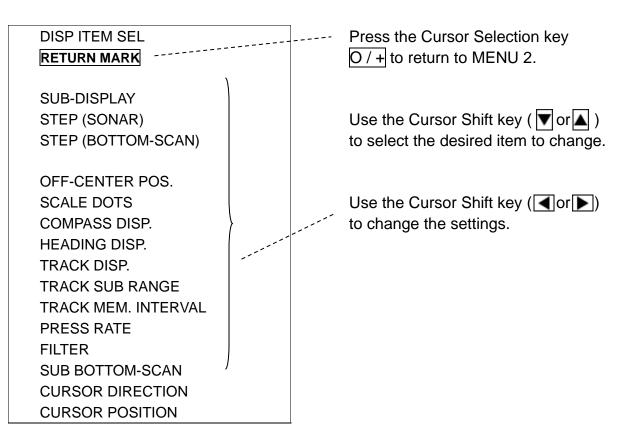
Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "**INTERFERENCE REJ.**". Use the Cursor Shift key (  $\triangleleft$  or  $\triangleright$ ) to change the setting.

**INTERFERENCE REJ OFF** ------ Use the Cursor Shift key (▲or ►) to change. [ON, OFF]

**ON:** activates this function.

**OFF:** inactivates this function.

# **DISPLAY ITEM SELECTION**



#### 1. SUB-DISPLAY

Sub menu displayed on the right half of the screen can be selected.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "**SUB-DISPLAY**". Use the Cursor Shift key (  $\triangleleft$  or  $\triangleright$ ) to change the setting.

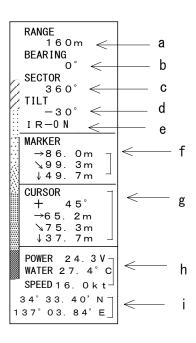
**SUB-DISPLAY INFO** ------ Use the Cursor Shift key ( I or ) to change. [NO SUB-DISP., INFO, HISTORICAL, +PRESS, + A-SCOPE, BOTTOM, TRACK, EXTSOUNDER]

#### 1) NO SUB-DISP. (NO SUB-DISPLAY)

The SUB-DISPLAY is not displayed. SONAR MODE, OFF-CENTER MODE, BOTTOM-SCAN MODE or SOUNDER MODE is displayed on the whole screen.

#### 2) INFO (INFORMATION)

This sub menu "INFO" can be displayed when one of the Mode Knobs, "• • • • •

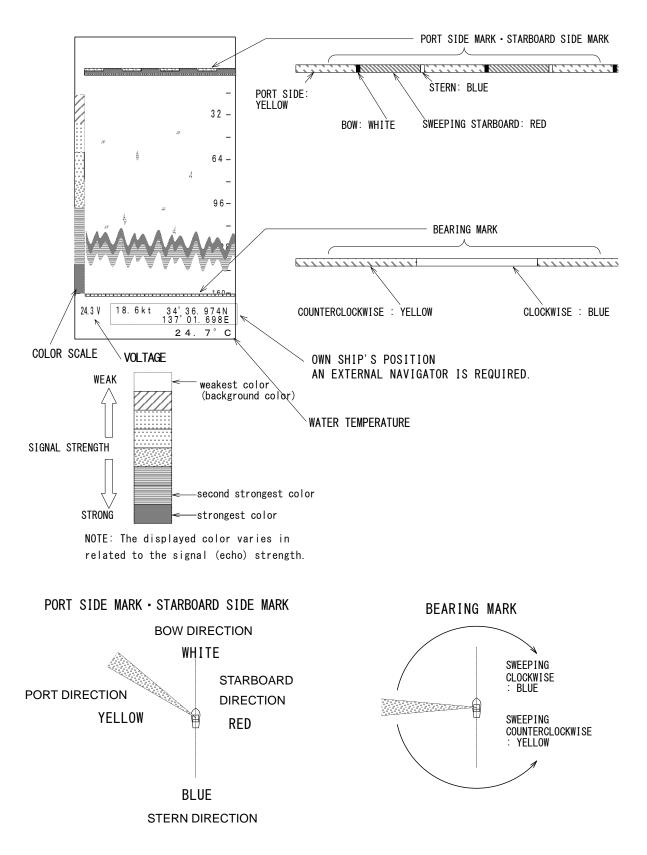


- a) Displays the selected range by using the Range Knob desired.
- b) Displays the selected bearing angle by using the Bearing Key.
- c) Displays the selected sector angle by using the Sector Knob.
- d) Displays the selected tilt angle by using the Tilt Key.
- e) It appears only when Interference Rejection-ON selected.
- f) Displays the horizontal distance, slant distance and depth to the marker. No data appears when Bottom-Scan mode set.
- g) Displays the horizontal distance, slant distance and depth to the cursor. No data appears when Sounder mode set.
- h) Displays the power supply voltage and the temperature.
- Displays the ship's speed and own ship's position in latitude/longitude. Note that an External Navigator is required to display these values.

#### 3) HISTORICAL DISPLAY

The vertical images can be displayed as sub menu when SONAR MODE or BOTTOM-SCAN MODE set.

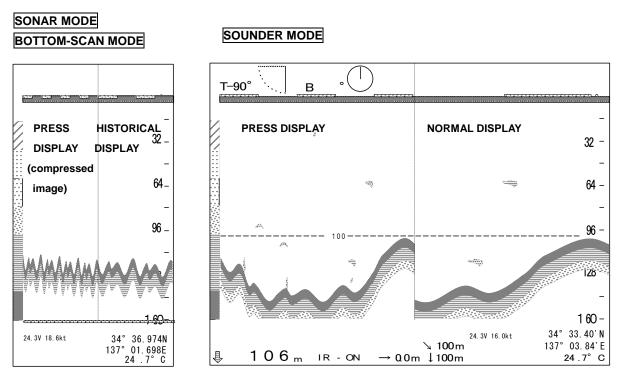
Note that the normal echo sounder images are displayed on the whole screen when SOUNDER MODE is selected.



The color shows the position/direction currently the beam passes.

#### 4) +PRESS (COMPRESSED IMAGE AND HISTORICAL DISPLAY)

The vertical images and their compressed image can be displayed when SONAR MODE or BOTTOM-SCAN MODE set. The normal echo sounder images and compressed image are displayed on the screen when SOUNDER MODE is selected.

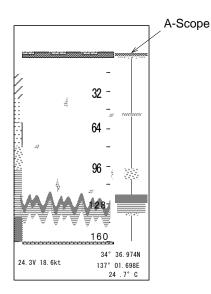


Compressed images are displayed at the selected rate [MENU-DISP ITEMSEL-PRESS RATE].

#### 5) +A-SCOPE (HISTORICAL DISPLAY+A-SCOPE)

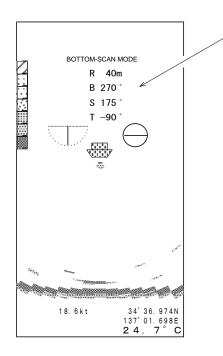
A-Scope is displayed on the right side of the historical display.

The illustration below shows when SONAR MODE/BOTTOM SCAN MODE selected. It is also displayed on the right side of the screen when SOUNDER MODE selected.



#### 6) BOTTOM-SCAN

The images of BOTTOM-SCAN MODE can be displayed in the sub-display. Note that this function is not available in Sounder Mode. Refer to page 67



-The setting values such as Range, Bearing, Sector, Tilt for the Bottom-Scan mode can be set while the Bottom-Scan mode is active.

The setting values will not be changed even if it backs to the Sonar Mode.

-The Sonar Mode display changes into the Bottom-Scan when it passes the center while clockwise rotating when "**SUB BOTTOM-SCAN / AUTO**" selected. After it updated, it will back to the Sonar Mode.

-The Sonar Mode display alternates with the

Bottom-Scan display each time the Lower  $|\downarrow|$  key

pressed when "**SUB BOTTOM-SCAN** / **MANUAL**" selected. The scanning direction is determined by the position when the Sonar Mode changes into the Bottom Scan.

#### 7) TRACK

Own ship's position can be displayed when an external navigator connected.

200m

#### **SCREEN WIDTH**

Displays the screen width selected via "TRACK SUB RANGE" selected.

#### **OWN SHIP**

Displays Own Ship's position in latitude/longitude and the speed at the bottom of the screen.

#### MARK

Displays the mark placed by a Cross Cursor in the Sonar Mode.

#### TRACK

Displays the track line. The past line is memorized every interval set via "TRACK MEM.INTERVAL".

#### 8) EXT.SOUNDER (EXTERNAL SOUNDER)

18.6kt

 $\Diamond$ 

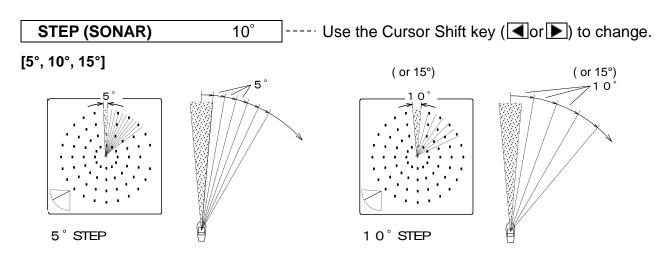
This function is only available when some Koden units connected.

34°36.974N 137°01.698E **24.7°C** 

## 2. STEP (SONAR)

The Step angle for SONAR MODE can be selected.

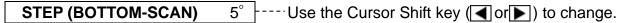
Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**STEP (SONAR)**". Use the Cursor Shift key ( $\triangleleft$  or  $\triangleright$ ) to change the setting.



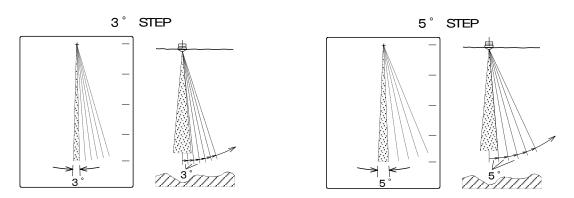
### 3. STEP (BOTTOM-SCAN)

The Step angle for SONAR MODE can be selected.

Use the Cursor Shift key (  $\bigcirc$  or  $\bigcirc$  ) to select "STEP (BOTTOM-SCAN)". Use the Cursor Shift key ( $\bigcirc$  or  $\bigcirc$ ) to change the setting.



[3° or 5°]



#### NOTE!

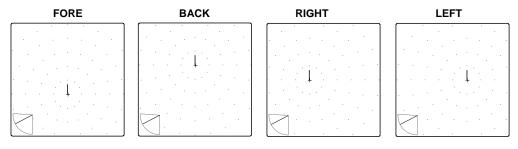
The superior detection images can be obtained when the narrower step angle selected, but the longer detection time is required.

## 4. OFF-CENTER POS. (OFF-CENTER POSITION)

The displayed position of own ship on the screen can be selected when OFF-CENTER MODE is active.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "**OFF-CENTER POS.**". Use the Cursor Shift key ( $\bigcirc$  or  $\triangleright$ ) to change the setting.

**OFF-CENTER POS. FORE** ------ Use the Cursor Shift key ( I pr ) to change. [FORE, BACK, RIGHT, LEFT]

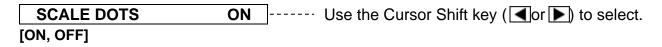


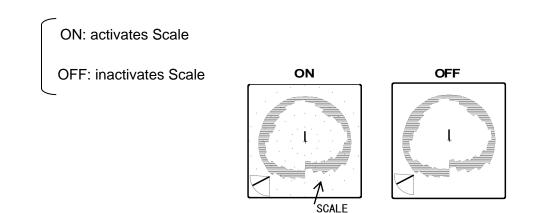
↓ shows Own Ship's Position

### 5. SCALE DOTS

The display of scale dots on the screen can be selected ON/OFF.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "SCALE DOTS". Use the Cursor Shift key (  $\triangleleft$  or  $\triangleright$ ) to change the setting.





When "OFF" set, Scale does not appear on SONAR MODE/OFF-CENTER MODE screens. However, it appears on BOTTOM-SCAN MODE/SOUNDER MODE screens even if "OFF" set.

#### 6. COMPASS DISPLAY

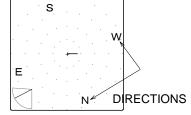
Compass can be displayed in the SONAR MODE when an External Navigator connected.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**COMPASS DISP.**". Use the Cursor Shift key ( $\triangleleft$  or  $\blacktriangleright$ ) to change the setting.

**COMPASS DISP. OFF** ------ Use the Cursor Shift key ( I or ) to change. [ON, OFF]

ON: activates Compass display

OFF: inactivates Compass display



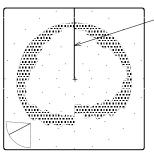
#### 7. HEADING DISPLAY

Heading line can be displayed in the SONAR MODE.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**HEADING DISP.**". Use the Cursor Shift key ( $\checkmark$  or  $\blacktriangleright$ ) to change the setting.

| HEADING DISP. OFF Use                 | OFF Use the Cursor Shift key (◀or ▶) to select. |  |  |  |  |
|---------------------------------------|---|--|--|--|--|
| [ON, OFF]                             | Heading Line                                    |  |  |  |  |
| ON: activates Heading line display    |   |  |  |  |  |
| OEE: inactivates Heading line display |   |  |  |  |  |

OFF: inactivates Heading line display



#### 8. TRACK DISPLAY

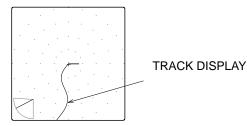
Track line can be displayed in the SONAR MODE when an external navigator connected.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "**TRACK DISP.**". Use the Cursor Shift key ( $\triangleleft$  or  $\triangleright$ ) to change the setting.

**TRACK DISP. OFF** Use the Cursor Shift key ( or ) to change. [ON, OFF]

ON: activates Track line display

OFF: inactivates Track line display



- 65 -

#### 9. TRACK SUB RANGE

The screen width for Track display in sub menu can be selected. Refer to page 62

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "**TRACK SUB RANGE**". Use the Cursor Shift key (  $\triangleleft$  or  $\triangleright$ ) to change the setting.

**TRACK SUB RANGE** 50m --- Use the Cursor Shift key ( I or ) to change. [10 – 500 depth unit]

#### Cursor Shift keys

: sets the value smaller.

: sets the value larger.

#### **10. TRACK MEM. INTERVAL (TRACK MEMORY INTERVAL)**

The tracking interval can be selected.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\checkmark$ ) to select "**TRACK MEM. INTERVAL**". Use the Cursor Shift key ( $\triangleleft$  or  $\triangleright$ ) to change the setting.

**TRACK MEM. INTERVAL 5SEC** Use the Cursor Shift key ( I or ) to change. [5 SEC, 10 SEC, 30 SEC, 60 SEC]

The short interval can provide for the display of smooth wake line, but it is the record of short term. In case of the long interval it displays the record of long term, but the zigzag line appears on the screen.

| Interval   |   | Memorized Time        |
|------------|---|-----------------------|
| 5 seconds  | : | 8 minutes 20 seconds  |
| 10 seconds | : | 16 minutes 40 seconds |
| 30 seconds | : | 50 minutes            |
| 60 seconds | : | 100 minutes           |

#### 11. PRESS RATE (COMPRESSED RATE)

The compressed rate for images on the screen can be selected. Refer to page 61

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "**PRESS RATE**". Use the Cursor Shift key ( $\bigcirc$  or  $\triangleright$ ) to change the setting.

**PRESS RATE** 1/4 ----- Use the Cursor Shift key (▲or ▶) to change. [1/2, 1/4, 1/8, 1/16]

Compress rate 1/2 shows one line for 2 sound beams and 1/4 for 4 sound beams. The information for the long time can be displayed when the higher rate selected, but the compressed image is tighter.

#### 12. FILTER

The image on the sonar can be enhanced by this function.

| Use the Cursor Shift key ( 🔽 or 🔺 ) to select "FILTER".                    |  |
|--|--|
| Use the Cursor Shift key ( $\square$ or $\square$ ) to change the setting. |  |

| FILTER      | 1 | Use the Cursor Shift key ( |
|-------------|---|----------------------------|
| [OFF, 1, 2] |   |                            |

OFF: inactivates filter function.

1: enhances the image on the sonar.

2: enhances further the image on the sonar.

#### **13. SUB BOTTOM-SCAN**

Select the SUB BOTTOM-SCAN MODE. Refer to page 61

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**SUB BOTTOM-SCAN**". Use the Cursor Shift key ( $\triangleleft$  or  $\triangleright$ ) to change the setting.

**SUB BOTTOM SCAN AUTO** ----- Use the Cursor Shift key ( I or ) to change. [AUTO, MANUAL]

AUTO: Sonar Mode changes into BOTTOM-SCAN MODE automatically . MANUAL: Sonar Mode changes into BOTTOM-SCAN MODE display manually.

#### **14. CURSOR DIRECTION**

Select the display way of the CUSOR DIRECTION when an External Navigator connected.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**CURSOR DIRECTION**". Use the Cursor Shift key ( $\triangleleft$  or  $\blacktriangleright$ ) to change the setting.

**CURSOR DIRECTION** R-DIRECTION ---- Use the Cursor Shift key ( I or ) to change. [R-DIRECTION, A-DIRECTION]

R-DIRECTION (RELATIVE DIRECTION): corresponds to the ship's heading direction T-DIRECTION (TRUE DIRECTION): corresponds to the compass direction

#### **15. CURSOR POSITION**

Select the display way of CUSOR POSITION when an External Navigator connected.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**CURSOR POSITION**". Use the Cursor Shift key ( $\lnot$  or  $\blacktriangleright$ ) to change the setting.

**CURSOR POSITION DISTANCE** ---- Use the Cursor Shift key ( or ) to change. [DISTANCE, LAT/LONG]

DISTANCE: displays the distance of the cursor position

LAT/LONG: displays the cursor position in latitude/longtude.

# **OTHERS**

[MODE KNOB – 1 2 – OTHERS]

| OTHERS            |          |   |
|-------------------|----------|---|
| RETURN MARK       |          |   |
| AUDIO LEVEL       | 0        |   |
| TARGET LOCK       | MODE0    |   |
| TRIGGER SIGNAL    | INTERNAL |   |
| DEPTH UNIT        | m        |   |
| TEMP. UNIT        | °C       |   |
| TEMP. ADJUST      | +0.0°C   |   |
| SPEED UNIT        | kt       |   |
| AUTO RETRACT      | OFF      |   |
| TRAIN CORRECT     | 0°       |   |
| PANEL BRIGHTNESS  | 15       |   |
| POWER S.FREQUENCY | 120k     |   |
| TD AUTO DOWN      | OFF      |   |
| OPE. MODE MEMORY  | OFF ,    | ) |
|                   |          |   |

Press the Cursor Selection key O/+ to return to MENU 2.

Use the Cursor Shift key ( Tor () to select the desired item to change.

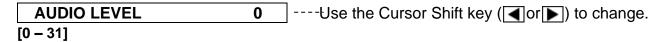
Use the Cursor Shift key ( <a>or</a> <a>)</a> to change the settings.

Note that the value of Train Correct cannot be set here. Refer to page 73

#### **1. AUDIO LEVEL**

The audio volume can be selected when connecting an external speaker.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\checkmark$ ) to select "AUDIO LEVEL". Use the Cursor Shift key ( or ) to change the setting.



#### **Cursor Shift keys**

sets the value smaller.sets the value larger.

#### NOTE!

A speaker device  $(4\Omega)$  is required. Refer to page 29

#### 2. TARGET LOCK

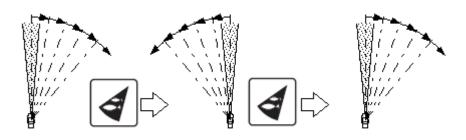
The desired target lock function can be selected, which is activated by pressing the Target Lock key ( ) while SONAR MODE or BOTTOM-SCAN MODE (only in case of MODE0) operated. It can change the rotary direction, trackthe target or the position specified with a cursor automatically.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**TARGET LOCK**". Use the Cursor Shift key ( $\bigcirc$  or  $\bigcirc$ ) to change the setting.

**TARGET LOCK MODE0** ----- Use the Cursor Shift key ( I or ) to change. [MODE0, MODE1, MODE2, MODE3]

#### MODE 0 (REVERSE)

Each press of the Target Lock key reverses the sector rotary direction. Note that the automatic tracking is not available in this MODE 0.



#### MODE 1 (RIGHT - LEFT)

Press the Target Lock key to track the reaction automatically.

**"TARGET LOCK**" sign appears on the upper left corner of the screen or on the display position of **BEARING** and **SECTOR** in the INFORMATION display. MODE 1 reverses the Transducer unit train direction only right and left and track the target automatically.



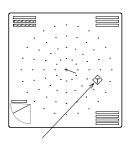
If it should have lost the target after a 60° reverse sweep, this function is released.

#### MODE 2 (UP-DOWN, RIGHT-LEFT)

One time of up and down detection is added after 3 times of MODE1 detection. Other actions are the same with MODE 1.

#### MODE 3

Target mark appears on the screen and tracks the target automatically after placing the Cross cursor on the target and press the Target Lock key.



Target mark moves along with the own ship on the screen.

Target mark also appears on the sub menu if TRACK is selected.

TARGET MARK

#### NOTE!

Tilt and Bearing keys are inoperative while Target lock function is active. Target lock function is released when Range, Sector and Display mode changed.

Bearing and Sector angles will back to the original values when Target Lock function is released. The value of Tilt angle of activating Target lock remains. Target lock function is inoperative while SOUNDER MODE is active. It is only operative in case of [Bottom-Scan mode - MODE0] selected.

It is inoperative other than MODE0.

#### **3. TRIGGER SIGNAL**

Select which Trigger signal to use.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**TRIGGER SIGNAL**". Use the Cursor Shift key ( $\checkmark$  or  $\blacktriangleright$ ) to change the setting.

**TRIGGER SIGNAL INTERNAL** ---- Use the Cursor Shift key ( I or ) to change. [INTERNAL, EXTERNAL]

- INTERNAL: activates the internal trigger signal of KDS-5000BB.

EXTERNAL: activates the signal from an external unit. (when another echo sounder synchronized)

#### NOTE!

The sweeping speed might be slower depending on the depth whe the KDS-5000BB is synchronizing with an external echo sounder.

Using the internal trigger signal of KDS-5000BB is recommended for synchronizing with an external echo sounder.

The output terminal for trigger signal has prepared in the unit. Refer to page 98

#### 4. DEPTH UNIT

The unit of depth measurement can be selected.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**DEPTH UNIT**". Use the Cursor Shift key ( $\checkmark$  or  $\blacktriangleright$ ) to change the setting.

DEPTH UNIT m ---- Use the Cursor Shift key (▲or ►) to change. [m, ft, fm, br]

#### **5. TEMPERATURE UNIT**

The unit of temperature measurement can be selected.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**TEMP. UNIT**". Use the Cursor Shift key ( $\checkmark$  or  $\blacktriangleright$ ) to change the setting.

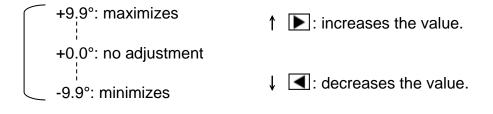
**TEMPERATURE UNIT** °C <sup>---</sup>Use the Cursor Shift key (▲or▶) to change. [°C, °F]

#### 6. TEMPERATURE ADJUSTMENT

The water temperature displayed on the screen can be adjusted.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**TEMP. ADJUST**". Use the Cursor Shift key ( $\checkmark$  or  $\triangleright$ ) to change the setting.

**TEMP. ADJUST** +0.0°C ---- Use the Cursor Shift key (▲or ►) to change. [-9.9°C to +9.9°C , every 0.1 unit ]



#### 7. SPEED UNIT

The unit of the ship's speed displayed on the screen can be selected when an external navigator connected.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**SPEED UNIT**". Use the Cursor Shift key (  $\checkmark$  or  $\blacktriangleright$ ) to change the setting.

**SPEED UNIT kt** ---- Use the Cursor Shift key ( or ) to change. [kt, km/h]

kt: displays the speed in knots.

km/h: displays the speed in km/h.

#### 8. AUTO RETRACT

The Transducer unit can be raised automatically when the ship's speed exceeds the speed previously set. The preset speed can be set.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "AUTO RETRACT". Use the Cursor Shift key (  $\checkmark$  or  $\blacktriangleright$ ) to change the setting.

AUTO RETRACTOFF----Use the Cursor Shift key ( or ) to change.[OFF, 10kt (18km/h)]Available setting ranges: 1 to 15kt (1km/h to 27km/h)

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to set the speed after selecting the initial value.



: increases the value.

: decreases the value.

With the speed input the Transducer unit can be raised automatically when the ship's speed exceeds a preset speed. The down arrow appears at the down left corner of the screen

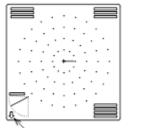
when the Transducer unit is being lowered.

lamp on the control panel is turned off.

: Sensor lamp on the Operation unit

When this function is activated, the arrow changes into the up

arrow. When the Transducer unit is retracted completely, the sensor



Transducer unit status indicator



The ship's speed should not exceed 15 knots (27km/h) while retracting the Transducer unit. The recommended setting speed is less 12kt (22km/h) considering the case that it speeds up without retracting the Transducer unit.

- 72 -

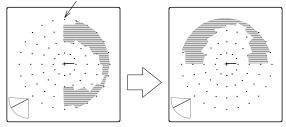
#### 9. TRAIN CORRECT

This changes the center direction of the detection range into the bow direction (0°). Select the SONAR MODE and set the desired position by using the Bearing keys

Open "MENU 2" and use the Cursor Shift key ( $\bigtriangledown$  or  $\blacktriangle$ ) to select "**OTHERS-TRAIN CORRECT**". Press the Cursor Selection ( $\bigcirc / +$ ) so that the confirmation sign appears on the screen. Selecting "**OK**" displays the value for adjustment and the displayt of the current center direction is changed into the bow direction (0°). Selecting "**CANCEL**" cancel the current operation.

**TRAIN CORRECT** 90° ---- After pressing the Cursor Shift key ( or ), the angle of the center direction set at the menu of SONAR MODE appears.

BOW DIRECTION (0°)



display rotated 90° counterclockwise

To release this function, setting the current bearing at 0° and the procedure "**TRAIN CORRECT**" above again are required.

#### **10. PANEL BRIGHTNESS**

The backlight brightness of operation panel can be changed.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**PANEL BIRHGTNESS**". Use the Cursor Shift key ( $\triangleleft$  or  $\blacktriangleright$ ) to change the setting.

PANEL BRIGHTNESS 15 ----- Use the Cursor Shift key (▲or ►) to change. [0 - 15]



: increases the value and sets brighter.



: decreases the value and sets darker.

### **11. POWER SUPPLY FREQUENCY**

The switching frequency of the power supply is changed.

The switching currents can cause electrical noise problems.

The noise produced by the SMPS itself can be suppressed changing the frequency.

It is usually not required to change the frequency other than noise problem.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\land$  ) to select "**POWER FREQUENCY**". Use the Cursor Shift key ( or ) to change the setting.

**120k** ----- Use the Cursor Shift key ( **I**or **)** to change. **POWER S. FREQUENCY** [120k, 125k, 130k]



Select "120k" for normal use.

#### **12. TD AUTO DOWN**

With the function "TD AUTO DOWN ON" selected, the Transducer unit is automatically lowered when the power turned on.

Use the Cursor Shift key (  $\nabla$  or  $\blacktriangle$  ) to select "TD AUTO DOWN". Use the Cursor Shift key ( or ) to change the setting.

TD AUTO DOWN OFF [OFF, ON]

Use the Gursor Shift key ( ) to (Ing) or

OFF: This function is inactive. The Transducer unit is not automatically lowered.

ON: This function is active. The Transducer unit is automatically lowered.

#### NOTE !

\*\*\*\*\*\*\*\*\*\*\*\*\*

..... It takes time (some seconds) to lower the Transducer unit even if the POWER ON key on the monitor or the key board pressed. If "TD AUTO DOWN ON" selected, the Transducer unit starts to lower the Transducer unit just before the unit starts working.

. . . . . . . . . . . . . . . .

#### **13. OPERATION MODE MEMORY**

The memory of Operation Mode is restricted. Refer to page 94 It can avoid memorizing the operation accidentally by selecting OFF.

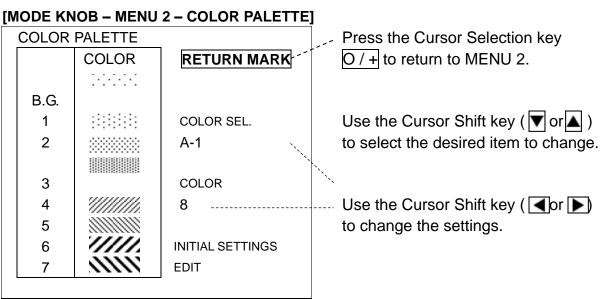
Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**OPE. MODE MEMORY**". Use the Cursor Shift key ( $\frown$  or  $\blacktriangleright$ ) to change the setting.

**OPE. MODE MEMORY OFF** ----- Use the Cursor Shift key ( or ) to change. [OFF, ON]

OFF: The new settings for Operation Mode are not overwritten.

\_ON: The new settings for Operation Mode are overwritten.

# COLOR PALETTE



#### 1. COLOR SEL.

The color of echoes and background (A-1, A-2, B-1 or B-2) can be set as desired. C-1 / C-2 can set the colors freely with Color palette function.

Use the Cursor Shift key ( $\bigtriangledown$  or  $\blacktriangle$ ) to select "**COLOR SEL.**". Use the Cursor Shift key ( $\checkmark$  or  $\blacktriangleright$ ) to change the setting.

#### 2. COLOR

The display colors can be select.

C-1 / C-2 can set the colors freely with Color palette function.

Use the Cursor Shift key ( $\square$  or  $\square$ ) to select "**COLOR**". Use the Cursor Shift key ( $\square$  or  $\square$ ) to change the setting.

**COLOR** 8 ----- Use the Cursor Shift key ( ▲ or ▶) to change. [8, 16]

#### HOW TO SET COLOR PALLETTE

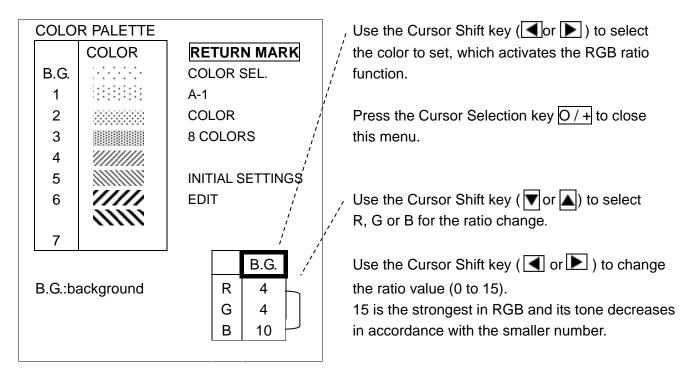
Color palette can provide 2 color patterns (C-1 & C-2) freely.

The initial color pattern of C-1 is the same with A-1 and C-2 are is the same with A-2.

Use the Cursor Shift key ( or ) to select "C-1" or "C-2", which activates the "INITIAL SETTINGS" and "EIDT" functions.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "**INITIAL SETTINGS**" and press the Cursor Selection key O / + to back to the "**INITIAL SETTINGS**".

Use the Cursor Shift key ( $\blacksquare$  or  $\blacktriangleright$ ) to select "EDIT" and press the Cursor Selection key O / +. Color palette appears on the screen.



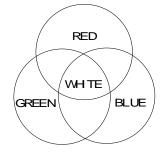
Move the Frame to the top after the RGB setting. Press the Cursor Selection key O/+ to close this menu and the desired settings are memorized in C-1 or C-2.

#### COLOR PALETTE!

Various desired colors can be created from changing RGB ratio.

Color palette function provides the creation of desired colors.

Utilize this Color palette function to set the most visible display for the reaction of fish schools.



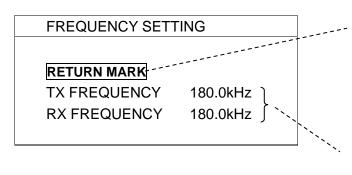
# REMOTE CONTROL SET (OPTION)

Previously set the key each on the remote controller before use.

#### [MODE KNOB – [] 2 – REMOTE CONTROL SET]

Refer to page 100 for the settings in details.

# FREQUENCY SETTING



Press the Cursor Selection key O/+ to return to MENU 2.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select the desired item to change.

Use the Cursor Shift key ( dor ) to change the settings.

#### **1. TX FREQUENCY**

Adjust the transmitting frequency of the KDS-5000BB and the receiving frequency changes in conjunction with the transmitting frequency.

It can be changed from the basic frequency to  $\pm 10$ kHz every 0.1kHz unit.

Use the Cursor Shift key ( $\bigtriangledown$  or  $\blacktriangle$ ) to select "**TX FREQUENCY**". Use the Cursor Shift key ( $\checkmark$  or  $\triangleright$ ) to change the setting.

TX FREQUENCY 180.0kHz ----- Use the Cursor Shift key ( or ) to change. [BASIC FREQUENCY to ±10kHz]

I decreases every 0.1kHz of the values of the frequencies for TX FREQUENCY and RX FREQUENCY.

I: increases every 0.1kHz of the values of the frequencies for TX FREQUENCY and RX FREQUENCY.

#### 2. RX FREQUENCY

Adjust the receiving frequency of the KDS-5000BB, but the transmitting frequency does <u>not</u> change in conjunction with the receiving frequency.

It can be changed from the basic frequency to  $\pm 10$ kHz every 0.1kHz unit.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**RX FREQUENCY**". Use the Cursor Shift key ( $\blacksquare$  or  $\blacktriangleright$ ) to change the setting.

**RX FEQUENCY** 180.0kHz Use the Cursor Shift key ( or ) to change. [BASIC FREQUENCY to ±10kHz]

I decreases every 0.1kHz of the values of the frequencies for RX FREQUENCY.

▶ : increases every 0.1kHz of the values of the frequencies for RX FREQUENCY.

# SELF CHECK

The following messages appear on the display.

This function checks the battery voltage, the internal voltage, the hoist up and down or the conditions of the stepping motor in the Transducer unit.

#### SELF CHECK

RETURN MARK

SAVE REPORT

Use the Cursor Shift key ( or ) to select "RETURN MARK" and press the Cursor Selection key ( O / + ) to close this menu.

Select "**SAVE REPORT**" to store the report of Self Check in the USB memory.

#### NO PROBLEM:

appears when the system has no problem.

#### MB (Main Board): ABNORMAL POWER SUPPLY VOLTAGE:

appears when the abnormal voltage detection of the battery is suspected.

#### HB (Hull Board): NO RESPONSE:

appears when the disconnection of the wiring between Hull Unit and the communication line is suspected.

#### TRANSDUCER UNIT: BLOWN FUSE:

appears when the blown fuse in the hoist is suspected.

#### TRANSDUCER UNIT: UP (DOWN) LIMIT NOT DETECTED:

appears when the abnormal upper (down) limit switch is suspected.

#### TRAIN MOTOR: DISCONNECTION

appears when the abnormal train motor is suspected.

#### TILT MOTOR: DISCONNECTION

appears when the abnormal tilt motor is suspected.

#### TRAIN MOTOR: ABNORMAL DETECTION OF ORIGIN

appears when the abnormal train motor or the abnormal detection of training position inside the Transducer unit is suspected.

#### TRAIN MOTOR: STEP OUT

appears when the abnormal train motor or the abnormal detection of training position inside the Transducer unit is suspected.

#### NOTE!

Both **TRAIN MOTOR: ABNORMAL DETECTION OF ORIGIN** and **TRAIN MOTOR: STEP OUT** appear when the Hall IC board in the Transducer unit is abnormal.

TRAIN MOTOR: DISCONNECTION, TRAIN MOTOR: ABNORMAL DETECTION OF ORIGIN and TRAIN MOTOR: STEP OUT appear all when the Transducer unit is total breakdown.

#### **MAINTENANCE**

| [MODE KNOB – [ 2 | – MAINTENANCE]      |                                       |
|------------------|---------------------|---------------------------------------|
| MAINTENANCE      |                     | Press the Cursor Selection key        |
| RETURN MARK      |                     | (O / +) to return to MENU 2.          |
| LANGUAGE         | ENGLISH (en)        |                                       |
| TIME             | 2013-06-05 17:36:22 |                                       |
| ELAPSED TIME     | 24H                 |                                       |
| UPDATE           |                     | Use the Cursor Shift key ( 🔽 or 🔺 )   |
| BACKUP           |                     | to select the desired item to change. |
| RECOVERY         |                     | Each menu appears after the Cursor    |
| VERSION          |                     | Selection key $(O / +)$ pressed.      |
| KDS-5000BB       |                     |                                       |

#### LANGUAGE

Use the Cursor Shift key (  $\bigcirc$  or  $\triangle$  ) to select "LANGUAGE". Use the Cursor Shift key ( $\bigcirc$  or  $\bigcirc$ ) to to select the desired language. It is required to turn the power off once to determine the language. Hold the **OFF** key for a while and then turn the **ON** key.

#### ELAPSED TIME

It indicates the total time that elapses while the KDS-5000BB operating and can be reset. Use the Cursor Shift key (  $\bigtriangledown$  or  $\land$  ) to select "**ELAPSED TIME**".

The following menu appears on the bottom of the screen after pressing the Cursor Selection key (O / +).

| ELAPSED TIME RESET           |        |
|------------------------------|--------|
| ? Do you reset elapsed time? |        |
| OK                           | CANCEL |

**CANCEL:** Use the Cursor Shift key ( $\blacksquare$  or  $\blacktriangleright$ ) to to select "**CANCEL**" and press the Cursor Selection key (O / +) to finish this menu.

**OK:** Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**OK**" and press the Cursor Selection key ( $\bigcirc / +$ ) to reset the elapsed time. OH appears on the screen.

#### 1. UPDATE

This is the way to update the version of the program.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "UPDATE".

The following menu appears on the bottom of the screen after pressing the Cursor Selection key (O / +). Use the Cursor Shift key ( $\blacksquare$  or  $\blacktriangleright$ ) to select

| UPDATE<br> | JSB stick contains updated files |
|------------|----------------------------------|
| NEXT       | CANCEL                           |

Use the Cursor Shift key ( $\checkmark$  or  $\triangleright$ ) to select "**CANCEL**" and press the Cursor Selection key ( $\bigcirc / +$ ) to close this menu.

<To be continued>

#### [HOW TO UPDATE VERSION]

Insert the USB stick contains the upgraded files. Use the Cursor Shift key ( $\bigcirc$  or  $\bigcirc$ ) to select "**NEXT**". Pressing the Cursor Selection key O/+ updates the program. After rebooting the unit, it is operated with the updated version.

#### 2. BACKUP

This is the way to back up the settings.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\bigtriangleup$ ) to select "**BACKUP**".

The following menu appears on the bottom of the screen after pressing the Cursor Selection key (O / +). Use the Cursor Shift key  $(\blacksquare or \blacktriangleright)$  to select.

| BACKUP   |            |  |  |
|--|------------|--|--|
| ? Where to back                                  | up?        |  |  |
| <b>!</b> Plug in Memory stick now in case of USB |            |  |  |
| work.  |            |  |  |
| INTERNAL   | MEMORY USB |  |  |
|  | CANCEL     |  |  |

Use the Cursor Shift key ( or ) to select "CANCEL" and press the Cursor Selection key (O / +) to close this menu.

#### [HOW TO BACK UP THE SETTINGS]

Use the Cursor Shift key ( $\blacksquare$  or  $\blacktriangleright$ ) to select where to back up (**INTERNAL** or **MEMORY USB**) and press the Cursor Selection key (O / +) to backup the settings.

#### 3. RECOVERY

This is the way to recover the settings.

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$ ) to select "**RECOVERY**".

The following menu appears on the screen after pressing the Cursor Selection key (O / +). Use the Cursor Shift key (  $\blacksquare$  or  $\blacktriangleright$ ) to select.

| RECOVERY   |            |  |  |  |
|--|------------|--|--|--|
| ? Which item do you store?                       |            |  |  |  |
| <b>!</b> Plug in Memory stick now in case of USB |            |  |  |  |
| work.  |            |  |  |  |
| INTERNAL   | MEMORY USB |  |  |  |
| FACTORY SETTTINGS                                | CANCEL     |  |  |  |

Use the Cursor Shift key ( $\blacksquare$  or  $\blacktriangleright$  to select "**CANCEL**" and press the Cursor Selection key ( $\bigcirc / +$ ) to close this menu.

#### [HOW TO RECOVER THE SETTINGS]

Use the Cursor Shift key ( $\blacksquare$  or  $\blacktriangleright$ ) to select what to recover (**INTERNAL**, **MEMORY USB** or **FACTORY SETTINGS**) and press the Cursor Selection key ( $\bigcirc / +$ ) to recover the settings. Selecting the factory settings will back to the factory settings.

#### 4. VERSION

Use the Cursor Shift key (  $\bigtriangledown$  or  $\blacktriangle$  ) to select "**VERSION**" to know the version of the program in this unit.

# CHAPTER 5

# DESCRIPTIONS of KNOBS and KEYS

This Chapter explains how to use the knobs and keys.

| Knobs | Mode Knob           | 84 |
|-------|---------------------|----|
|       | Range Knob          | 84 |
|       | Sector Knob         | 85 |
|       | Gain Knob           | 86 |
|       | Far Gain Knob       | 86 |
| Keys  | Power ON/OFF Key    | 87 |
|       | Hoist/Lower Key     | 87 |
|       | Sensor Lamp         | 87 |
|       | Bearing Key         | 88 |
|       | Tilt Key            | 89 |
|       | Cursor key          | 90 |
|       | Target Lock Key     | 92 |
|       | Mark Key            | 92 |
|       | Coloe rejection Key |    |
|       | Operation Mode Key  |    |
|       |                     |    |

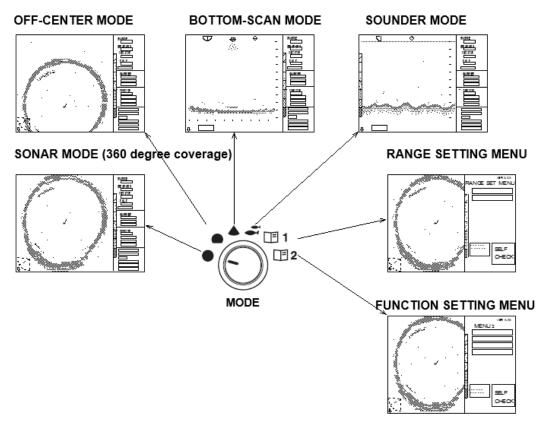
# <u>KNOBS</u>

# MODE KNOB

The display mode is selected.

The Sub-Display menu displayed in the right split screen can be set via "  $\square 2$ ". Refer to page 58

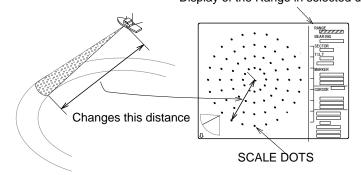
The own ship's position in the Off-Center Mode can be set via "  $\square 2$ ". Refer to page 64



# RANGE KNOB

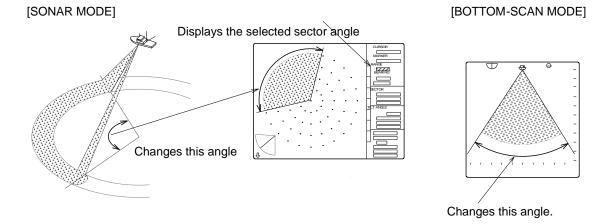
The basic ranges can be changed.

8 ranges can be set via " 🖃 1". Refer to page 48 The unit of range measurement can be selected via " 🖃 2". Refer to page 71 The display (ON/OFF) of Scale dots can be selected via " 🗐 2". Refer to page 64 Display of the Range in selected unit



# SECTROR KNOB

The horizontal training angle can be changed when SONAR MODE selected. The vertical training angle can be changed when BOTTOM-SCAN MODE selected.



Clockwise rotation ( $\bigcirc$ ) increases the sector width and counterclockwise rotation ( $\bigcirc$ ) decreases it. The desired step can be selected via " $\boxdot 2$ ". Refer to page 63

#### SONAR MODE

| 5° STEP  | 5°  | 25° | 45° | 85°  | 125° | 165° | 205° | 360° |
|----------|-----|-----|-----|------|------|------|------|------|
| 10° STEP | 10° | 30° | 50° | 90°  | 130° | 170° | 210° | 360° |
| 15° STEP | 15° | 45° | 75° | 105° | 135° | 165° | 225° | 360° |

#### **BOTTOM-SCAN MODE**

| 3° STEP | 3° | 27° | 45° | 63° | 93° | 117° | 147° | 177° |
|---------|----|-----|-----|-----|-----|------|------|------|
| 5° STEP | 5° | 25° | 45° | 65° | 95° | 115° | 145° | 175° |

# **GAIN KNOB**



Rotating this knob clockwise can adjust or increase the sensitivity of the sonar display.

The gain value can be set via "MENU 2 - GAIN UP". Refer to page 52

### FAR GAIN KNOB



Rotating this knob clockwise increases sensitivity of the sonar for the last half of the displayed range and adjusts the TVG curve. Refer to page 53

# POWER ON/OFF KEYS

#### ON key

Press this key to turn on the power. The Transducer unit is automatically lowered. The sensor lamp on the Operation unit lights while the Transducer unit is being lowered. The sign "**Please wait**" appears on the bottom of the screen. The sonar operation starts after the sign disappears.

#### OFF key

Press this key to turn off the power. The Transducer unit is automatically raised. The sign "**Please wait**" appears on the bottom of the screen. The power is turned off after the sign disappears.

The sensor lamp ( ) is off after the Transducer unit is retracted into the TD tank. Do not turn off the power on the Hull unit until the sensor lamp is off.

### HOIST/LOWER KEYS

↑ : HOIST KEY / ↓ : LOWER KEY

The Hoist and Lower keys raises and lowers the Transducer unit while operating the KDS-5000BB.

Pressing the Hoist key raises the Transducer unit and the mark on the lower left screen changes into the up arrow ( † ). The sensor lamp is off after the retraction of the Transducer unit is completed.

Pressing the Lower key lowers the Transducer unit, the mark changes into the down arrow ( $\downarrow$ ) and the sensor lamp lights.

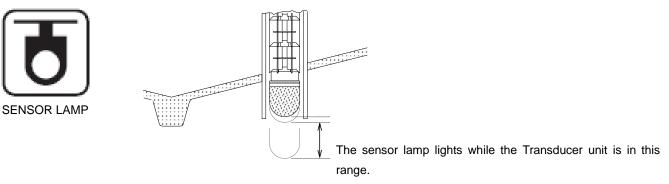
Down the ship's speed and press the Lower key in case the Transducer unit is retracted by the function "AUTO RETRACT".

#### NOTE!

[X] in red appears on the left corner of the screen in case of the malfunction of hoisting/lowering of the Transducer unit.

### SENSOR LAMP

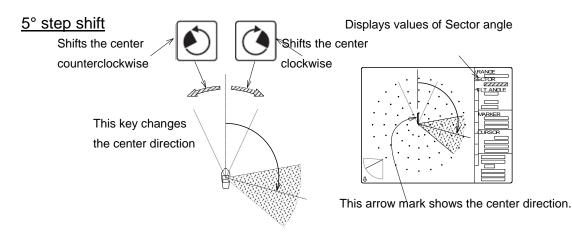
The sensor lamp lights while the Transducer unit is being lowered. **Do not turn off the power on the Hull unit until the sensor lamp is off.** 



# **BEARING KEY**

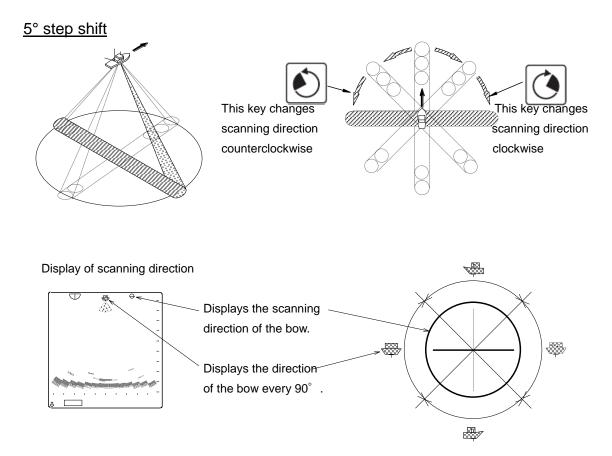
#### [SONAR MODE]

The center direction of the detection range can be shifted as follows.



#### [BOTTOM-SCAN MODE]

The direction of the detection range can be shifted.



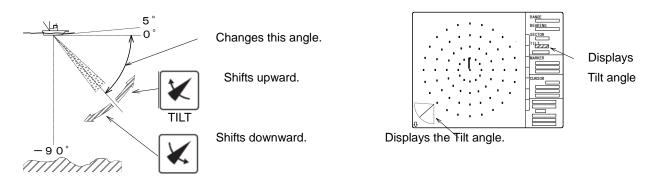
#### [SOUNDER MODE]

The direction of the detection range can be shifted together with "TILT KEY". The shifted angle is the same with BOTTOM-SCAN MODE. Refer to page 90

# <u>TILT KEY</u>

[SONAR MODE]

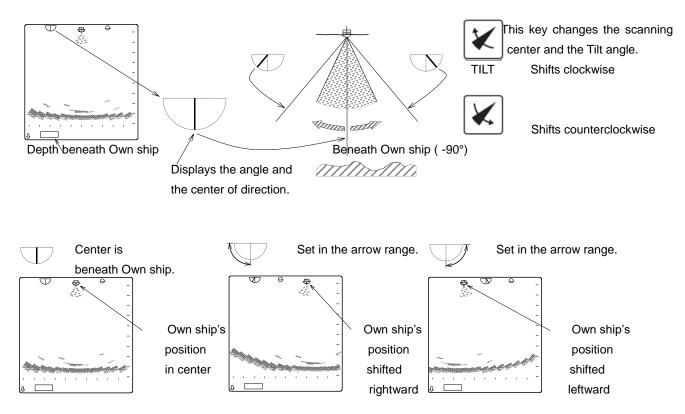
The tilt angle can be changed.



Variable Tilt angle: in increments of 1° from -5° (0°) to -90°

#### [BOTTOM-SCAN MODE]

The scanning center can be shifted.

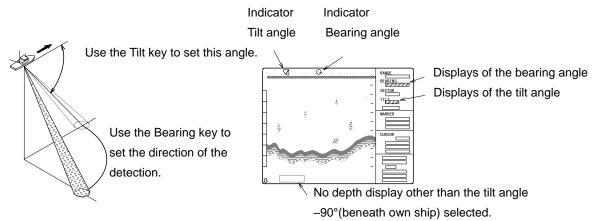


Variable Tilt angle (Refer to the page 63 for the setting of step.)

- 3° step: in increments of 3° from -3° to -90°
- $5^\circ$  step: in increments of  $5^\circ$  from  $-5^\circ$  to  $-90^\circ$

#### [SOUNDER MODE]

The direction of emitting the sound wave and the bearing of the detection can be shifted together with "BEARING KEY".



Variable Tilt angle: in increments of  $1^{\circ}$  from  $-5^{\circ}$  (0°) to  $-90^{\circ}$ Use the Depth marker to measure the depth other than the tilt angle  $-90^{\circ}$ .

# **CURSOR KEY**

Use 2 types (one type in case of SOUNDER MODE) of Cursor to display the range from own ship to the cursor location.

Use the Cursor selection key to select the cursor.

Use the Cursor shift keys to move the cursor.

| 0/+ ke | ey | [SONAR MODE] Ring marker and Cross cursor ON/OFF available<br>[BOTTOM-SCAN MODE] Depth scale and Cross cursor ON/OFF available<br>[SOUNDER MODE] Depth scale ON/OFF available |
|--------|----|---|
| 🔺 ke   | ey | Ring marker enlarged, Cross cursor shifted upward,<br>Depth scale shifted to the shallower range  |
| ▼ ke   | ey | Ring marker reduced, Cross cursor shifted downward,<br>Depth scale shifted to the deeper range  |
| 🔳 ke   | еу | Cross cursor shifted leftward   |
| ► ke   | ev | Cross cursor shifted rightward  |

[when the power turned on]

No cursors appear on the screen when the power turned on. Press the Cursor selection key (O / +) to activate the function.

Press the Cursor shift keys (  $\bigtriangledown$  or  $\bigtriangleup$ ) to display the Marker. Press the Cursor selection key again to activate this function.

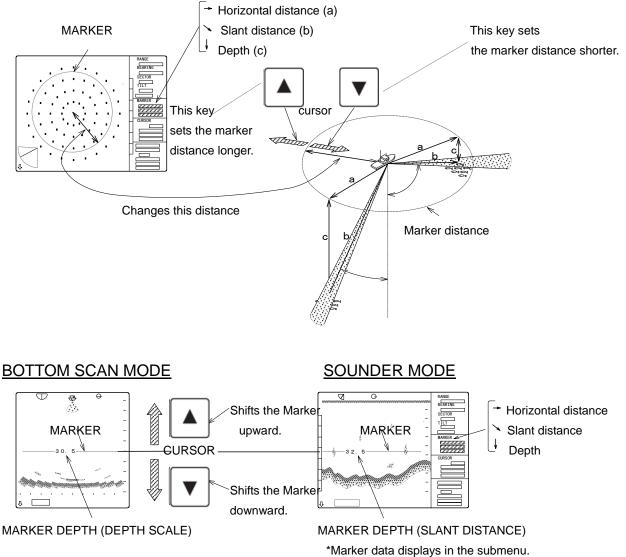
(In case of SOUNDER MODE, this function is off.)

Inactive functions are displayed in yellow.

The Marker and the Cursor disappear after pressing the Cursor selection key again.

[when the Marker selected] (Cross cursor displayed in yellow or no display)

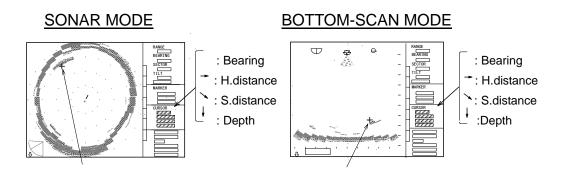
#### SONAR MODE



KEYS

[when the Cross cursor selected] (Marker displayed in yellow or no display) In case of SOUNDER MODE this function is inactive.

Use the Cursor shift keys to place the cursor where desired. The data of the "Cross Cursor" is displayed in the submenu.



This Cross cursor is also used for placing the event mark (Refer to page 93) and target mark (Refer to page 80).

# TARGET LOCK KEY (

The following Target lock key actions are available in the SONAR MODE and in the BOTTOM-SCAN MODE – MODE 0 only and it is different action depending on the selected menu via "MENU 2 – TARGET LOCK.

-Setting MODE 0: the train direction is reversed.

-Setting MODE 1 & 2: it tracks the target automatically.

-Setting MODE 3 (an external navigator should be connected):

Place the Cross cursor on the target and press the Target lock key. A target mark is inscribed at the Cross cursor location and tracks the target automatically. Refer to the page 69 **"TARGET LOCK**" for details.

NOTE!

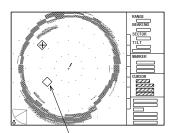
This Target lock key is not available other than the above Modes.

# <u>MARK KEY (🔿 )</u>

The Mark key functions to mark desired locations on the screen, and 5 marks can be inscribed at the Cross cursor locations desired.

Move the Cross cursor to the desired locations and press the Mark key.

The Mark ( $\langle \rangle$ ) appears at the Cross cursor location and moves with ship's movement.

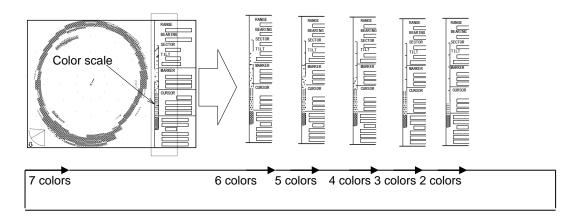


This mark also appears on the screen when the sub-display, WAKE display is active.

MARK

# COLOR REJECTION KEY (

This key can eliminate the appearance of unwanted week colors. It can eliminate small fish and unidentified objects and display the clearer images. Each time this key is pressed, one of the weakest display colors is eliminated.



# **OPERATION MODE KEY**

3 different types of customized operation settings can be registered previously. Press one of the Operation mode keys to operate the units with the desired settings soon after pressing it.

Open MENU 2 display and press one of the Operation mode keys. The following "OPERATION MODE" menu appears on the screen. Use the Cursor Shift key ( $\bigcirc$  or  $\blacktriangle$ ) to highlight the item to change. Use the Cursor Shift key ( $\bigcirc$  or  $\blacktriangleright$ ) to change the setting values.

| OPERATION MODE 1 | (2, or 3)   |
|------------------|-------------|
| DISPLAY MODE     | ر SET VALUE |
| RANGE            | SET VALUE   |
| STEP             | SET VALUE   |
| SECTOR           | SET VALUE   |
| BEARING          | SET VALUE   |
| TILT             | SET VALUE   |
| GAIN UP          | SET VALUE 丿 |
| TVG CURVE        | SET VALUE   |
|                  |             |

Each time the Cursor shift key ( or )
 Pressed, the value changes

Use the Mode knob to back to the desired mode after the settings completed. Press one of the desired keys (1, 2 or 3) to activate the memorized operation menu.

Even if the settings are changed via MENU 2 or Operation unit, the settings in the Operation mode (1, 2 or 3) remain.

In case the settings are changed via MENU 2 or Operation unit while the Operation mode is used, the action will follow the changed settings, but it back to the Operation mode by pressing one of the Operation mode keys again.

#### NOTE!

This is the way to register the Operation mode being used without opening the "OPERATION MODE" menu.

Hold one of the operation mode keys (1, 2 or 3) for 3 seconds after the first buzzer. The desired setting is registered in the selected Operation mode key after the buzzer sounds again.

Do not release the key until the second buzzer sounds. Otherwise the new settings cannot be registered.

Selecting [MODE KNOB - **1 2** – OTHERS – OPE.MODE MEMORY OFF] can protect overwriting the new settings of the operation. Refer to page 75

# CHAPTER 6

# OPTION

This chaper provides you the explanation related to the optional input/output terminals and the remote controller.

| Option | Option List 96                             |
|--------|--|
|        | Input/Output Terminals 98                  |
|        | Input/Output Terminals (Processor unit) 99 |
|        | Remote Controller100                       |

# **OPTION LIST**

#### For Processor unit

| P. No.       | Description                        |                                  |
|--------------|------------------------------------|----------------------------------|
| ESR-1809-SET | Remote Controller Set              | With 4m cable and cable for      |
|              |                                    | connecting remote controller     |
|              |                                    | with OP-287 connecter.           |
| OP-360       | XGA Connect Cable Assy             | Terminal for XGA Output          |
|              |                                    | (to connect an external monitor) |
| OP-190       | Trigger Output Cable 36981D        | To connect Trigger Output to the |
|              | (one side of the cable is chopped) | Sounders of other companies      |
|              |                                    | (5m)                             |

#### For DHU-530

| P. No.           | Description  |   |
|------------------|--|---|
| OP-700           | DJB-540<br>Junction Box Mounting Kit   | For mounting Junction Box on the<br>Hull Unit<br>Junction Box |
| ESR-1506         | PVC, 1230mm / 9.0kg  | Junction Box Mounting Kit<br>TD tank                          |
| 30927C-2         | (For 1411mm of TD shaft)<br>PVC, 1500mm / 11.0kg<br>(For 1681mm of TD shaft) |   |
| 30927C-3         | PVC,1800mm / 13.0kg<br>(For 1981mm of TD shaft)                              |   |
| ESR-1507         | FRP,1500mm / 12.0kg  |   |
| FRP TD tank set  | (Including Shaft guide)<br>(ESR-1507x1, ESR-1510x2,<br>ESR-1511x2)           |   |
| ESR-1504         | 1411mm   | TD shaft  |
| ESR-160 32679C-2 | 1681mm   |   |
| ESR-160 32679C-3 | 1981mm   |   |

#### OPTION

| P. No.    | Description                |              |
|-----------|----------------------------|--------------|
| ESR-1510  | Shaft guides               | <b>A</b>     |
| ESR-1511  | Shaft guides with adjuster | Same Barrier |
| G-100     | Grease                     |              |
| Bath cork |                            |              |

# **INPUT/OUTPUT TERMINALS**

The following optional terminals are required to connect a remote controller and an External monitor.

This is to indicate the settings for the interface setups.

Note that the connection cables between the KDS-5000BB and the external units to be connected are not supplied as standard.

| P. No.   | NAMES of TERMINALS                | TERMINAL C          | ONNECTIONS             |
|----------|-----------------------------------|---------------------|------------------------|
| OP-360   | VGA OUTPUT                        | No1: RED OUTPUT     | No7: GREEN GND         |
|          | (TERMINAL for                     | No2: GREEN OUTPUT   | No8: BLUE GND          |
|          | EXTERNAL MONITOR)                 | No3: BLUE OUTPUT    | No10: GND              |
|          |                                   | No5: GND            | No13: H-SYNC           |
|          |                                   | No6: RED GND        | No14: V-SYNC           |
|          |                                   |                     | OTHER Nos: NC          |
| STANDARD | ALARM                             | No1: ALARM          | *not used currently    |
| SUPPLY   | (TERMINAL for<br>EXTERNAL BUZZER) | No2: ALARM          | *normally open contact |
| STANDARD | TRIG - OUT                        | No1: TRIGGER        | No3: TRIGER OUTPUT-    |
| SUPPLY   | (TERMINAL for                     | OUTPUT+             |                        |
|          | TRIGGER OUTPUT)                   | No2: SHIELD         |                        |
| STANDARD | NAV - IN                          | No1: SIGNAL INPUT+  | No4: SIGNAL OUTPUT+    |
| SUPPLY   | (TERMINAL for                     | No2: SIGNAL INPUT-  | No5: SIGNAL OUTPUT-    |
|          | NAVIGATOR)                        | No3: SHIELD         |                        |
| STANDARD | NMEA - OUT                        | No1: SIGNAL INPUT+  | No4: SIGNAL OUTPUT+    |
| SUPPLY   | (TERMINAL for                     | No2: SIGNAL INPUT-  | No5: SIGNAL OUTPUT-    |
|          | NAVIGATOR or                      | No3: SHIELD         | No6: NC                |
|          | Something else)                   |                     |                        |
| STANDARD | SERIAL - IF                       | No1: SIGNAL INPUT+  | No5: SIGNAL OUTPUT-    |
| SUPPLY   | (TERMINAL for                     | No2: SIGNAL INPUT-  | No6: NC                |
|          | EXTERNAL SOUNDER)                 | No3: SHIELD         | No7: NC                |
|          |                                   | No4: SIGNAL OUTPUT+ |                        |
| STANDARD | TRIG - IN                         | No1: TRIGGER INPUT  | No5: GND               |
| SUPPLY   | (TERMINAL for                     | No2: NC             | No6: NC                |
|          | TRIGGER INPUT)                    | No3: NC             | No7: NC                |
|          |                                   | No4: NC             | No8: SHIELD            |

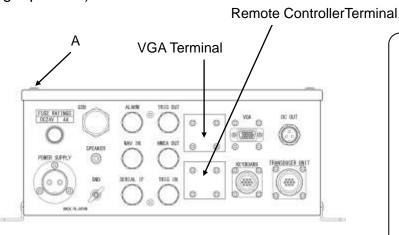
\* Note that nothing should be connected to the above NC.

A navigator can be connected to NMEA-OUT terminal (No.1 and No.2), but the data of NAV-IN terminal will prior to NMEA-OUT terminal (No.1 and No.2).

# **INPUT/OUTPUT TERMINALS (PROCESSOR UNIT)**

Remove all cables connected to the Processor unit before mounting any terminals.

1) Remove 4 Binding Screws holding the Lid of the Processor unit and remove the Lid (Drawing A position).



Do not open the Case Cover thoughtlessly.

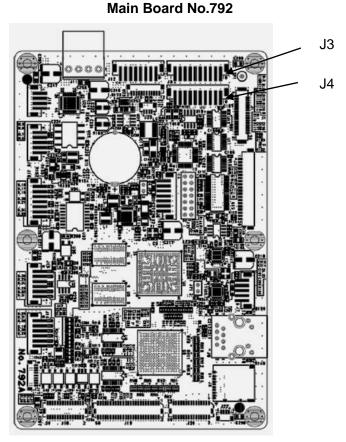
There might be some high voltage potion inside the unit which sometimes causes death or injury.

Only qualified personnel should work on mounting terminals.

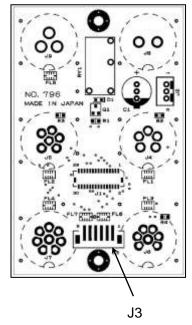
- 2) Remove the Blind Lid or the Cap to mount the terminal. Mount it referring to the above drawing.
- 3) Insert the connector of the terminal into the specified terminal of the Main Board or the External Connecting Board.

-VGA OUTPUT Terminal  $\rightarrow$  J3 or J4 on the Main Board No.792 -REMOTE CONTROLLER TERMINAL  $\rightarrow$  J3 on the External Connecting board No.796

4) Put the Lid of the MBB back to its original place after finishing the mounting work.

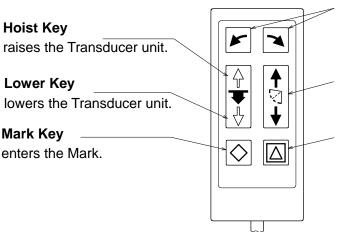


#### **External Connecting Board No.796**



# **REMOTE CONTROLLER**

Connect the terminal of the Remote Controller to the specified port.



#### **Bearing Key**

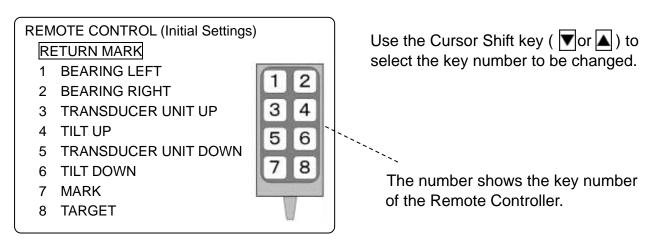
changes the center direction right or left.

Tilt Key adjusts the Tilt Angle.

#### **Target Lock Key** reverses the sector rotary direction or the track the reaction automatically.

#### [MODE KNOB – 1 2 – REMOTE CONTROL]

- 1) Select the Mode Knob ( 12)
- Use the Cursor Shift key ( ▼or ▲) to select "REMOTE CONTROL" and press the Cursor Selection key (O / +) so that the following menu appears on the screen.



Each time the Cursor Shift key ( or ) pressed, the item appears in the following orders

[OPE. MODE 1, OPE. MODE 2, OPE.MODE3, TARGET, MARK, COLOR REJECTION, CURSOR SEL, CURSOR UP, CURSOR DOWN, CURSOR RIGHT, CURSOR LEFT, RANGE SHALLOW, RANGE DEEP, TRANSDUCER UNIT UP, TRANSDUCER UNIT DOWN, TILT UP, TILT DOWN, BEARING RIGHT, BEARING LEFT, OPE.MODE 1.......]

All ranges of the range setting menu can be controlled by the remote control keys unitl the Range Knob operated.

# ADDITIONS DISPOSAL



The KDS-5000BB contains the lithium battery of high-density energy. Careless disposal of the lithium battery causes electric shorts, impact, heat, electrical shock, explosion, injury, fire and so on.

### DISPOSAL OF KDS-5000BB

Dispose of the KDS-5000BB in accordance with local regulations.

# DISPOSAL OF LITHIUM BATTERY

Place a piece of adhesive tape across the plus and minus terminals before disposing of the lithium battery. Dispose of the lithium battery in accordance with local regulations.

| Itom                         |                               |   | Content   |   |  |   |                                 |           |       |      |      |      |
|------------------------------|-------------------------------|---|---|---|--|---|---------------------------------|-----------|-------|------|------|------|
| Item<br>Model                |                               | Content<br>KDS-5000BB   |   |   |  |   |                                 |           |       |      |      |      |
|                              |                               | DPU-510   |   |   |  |   |                                 |           |       |      |      |      |
|                              |                               | DPU-510<br>DOU-520  |   |   |  |   |                                 |           |       |      |      |      |
| ·                            |                               | DHU-53  |   |   |  |   |                                 |           |       |      |      |      |
| Output power (RMS)           |                               | 1.5kW   |   |   |  |   |                                 |           |       |      |      |      |
| Output frequency             |                               | 180kHz  |   |   |  |   |                                 |           |       |      |      |      |
| Tilt angle                   |                               |   | 90° (1°   | sten)   |  |   |                                 |           |       |      |      |      |
| Beam angle                   |                               | 10°   | 30 (1   | step)   |  |   |                                 |           |       |      |      |      |
| TD stroke                    |                               |   | 380 mm (  | Recom   | mended   | value 18                                      | 30 mm)                          |           |       |      |      |      |
| Display size and type        |                               |   |   |   |  |   |                                 |           |       |      |      |      |
| Display resolution           |                               | -   | 768 (XG   |   | Solution                                       |   | Supplied)                       |           |       |      |      |      |
| Basic ranges                 |                               |   | s freely s  |   |  |   |                                 |           |       |      |      |      |
| Range units                  |                               | m, ft, fm   |   |   |  |   |                                 |           |       |      |      |      |
| Scanning<br>sector<br>angles | Sonar mode                    | 5°step:<br>10°step<br>15°step<br>20°step<br>3°step:   | 5°, 25°,<br>: 10°, 30<br>: 15°,45°<br>: 20°,60°<br>3°, 27°, 4 | °, 50°, 9<br>°,75°,10<br>°,100°,14<br>45°, 63°, | 0°, 130°<br>5°,135°,′<br>40°,180°<br>, 93°, 11 | , 170°, 2<br>165°,229<br>,220°,20<br>7°, 147° | 210°,360<br>5°,360°<br>60°,360° |           |       |      |      |      |
|                              | Bottom scan mode              | 5°step:   | 5°, 25°, 4  | 45°, 65°  | 95°, 11  | 5°, 145°                                      | , 175°                          | r         |       |      |      |      |
|                              | Scanning range (m)            | 20  | 40  | 60  | 80   | 100   | 120                             | 160       | 180   | 200  | 240  | 400  |
| 360° Scanning time           | Scanning time (sec.) 5° step  | 5.7   | 7.6   | 9.5   | 11.4   | 13.3  | 15.3                            | 19.1      | 21.0  | 23.0 | 26.8 | 42.2 |
| (extracts)                   | Scanning time (sec.) 10° step | 4.1   | 5.0   | 6.0   | 7.0  | 8.0   | 8.9                             | 10.8      | 11.8  | 12.7 | 14.7 | 22.3 |
|                              | Scanning time (sec.) 15º step | 3.5   | 4.1   | 4.8   | 5.4  | 6.1   | 6.7                             | 8.0       | 8.6   | 9.3  | 10.6 | 15.7 |
|                              | Scanning time (sec.) 20° step | 3.2   | 3.7   | 4.2   | 4.6  | 5.1   | 5.6                             | 6.6       | 7.1   | 7.5  | 8.5  | 12.3 |
| Bearing center               |                               | ,   | °step sel   |   |  |   |                                 |           |       |      |      |      |
| Presentation modes           |                               | Sonar mode + Data display, Off-center mode + Data display<br>Off-center on the whole screen, Bottom scan mode + Data display,Sounder Mode + Data<br>display   |   |   |  |   |                                 |           |       |      |      |      |
| Data display                 |                               | Secter center angle, Tilt angle, Tilt angle indicator, Ring marker, Cross Cursor Compass (option), Navigation (option)  |   |   |  |   |                                 |           |       |      |      |      |
| Off-Center                   |                               | Fore, Ba  | ack, Left   | , Right   |  |   |                                 |           |       |      |      |      |
| Target lock                  |                               | Reverse   | e, Horizo   | ntal, Hoi                                       | izontal +                                      | Vertica                                       | l, Marker                       | · + Horiz | ontal |      |      |      |
| Presentation colors          |                               | 8/16 co   | lors  |   |  |   |                                 |           |       |      |      |      |
| Functions                    |                               | Operation mode (3 modes), Off-center (4 changes), Train correct, Power rejection<br>Gain adjust, Temperature adjust, Pulse width control, TVG change, Target lock<br>Color change (4 types + 2 types of color palette settings), Dynamic range<br>Interference rejection, Color rejection, Filter (OFF/1/2), Gain control, Far gain control<br>External trigger synchronization, Trigger signal output<br>Hoist sensor lamp, Audio (optional speaker required), Stabilizer (up to 25° controllable)<br>Transducer unit automatic retract (Navigator connect required), Full-screen gain control |   |   |  |   |                                 |           |       |      |      |      |
| Language                     |                               | English, Japanese   |   |   |  |   |                                 |           |       |      |      |      |
| External Input               |                               | Trigger input, Navigator input, External sounder input, Remote controller input   |   |   |  |   |                                 |           |       |      |      |      |
| External Output              |                               | External buzzer, Trigger output, NMEA output, XGA output, Audio output<br>USB terminal (memory for setting values)  |   |   |  |   |                                 |           |       |      |      |      |
| NMEA ports                   |                               | Total 1 : input / output  |   |   |  |   |                                 |           |       |      |      |      |
| Power supply                 | Processor unit                | 21.6 to 31.2 VDC  |   |   |  |   |                                 |           |       |      |      |      |
| Power supply                 | Hull unit                     | 21.6 to 31.2 VDC  |   |   |  |   |                                 |           |       |      |      |      |
| Dowor concurrentia-          | Processor unit                | 70 W or less (24 VDC)   |   |   |  |   |                                 |           |       |      |      |      |
| Power consumption Hull unit  |                               | 70 W or   | less (24  | VDC)  |  |   |                                 |           |       |      |      |      |
| Operating temperature        |                               | -15 °C to + 55 °C   |   |   |  |   |                                 |           |       |      |      |      |
| Operating temperature        |                               | 10 01   | <u> </u>  | <u> </u>  |  |   |                                 |           |       |      |      |      |

# KODEN

#### Koden Electronics Co., Ltd.

Tamagawa Office: 2-13-24 Tamagawa, Ota-ku, Tokyo, 146-0095 Japan Tel: +81-3-3756-6501 Fax: +81-3-3756-6509 Uenohara Office: 5278 Uenohara, Uenohara-shi, Yamanashi, 409-0112 Japan Tel: +81-554-20-5860 Fax: +81-554-20-5875

#### www.koden-electronics.co.jp