



KODEN

OPERATION MANUAL

GPS Compass

KGC-222

This product is specifically designed to be installed on boats and other means of maritime transport. If your country forms part to the EU, please contact your dealer for advice before attempting to install elsewhere.



Declaration of Conformity

(As required by Article 6.3 of Directive 1999/5/EC-RTTE Directive)

Declares under his sole responsibility that the Marine GPS receiver manufactured by
Koden Electronics Co., Ltd.

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Intended for Worldwide use as a Marine GPS Compass for use aboard non-SOLAS
vessels and Identified by the type number **KGC-222** to which this declaration refers is
in conformity with the EMC, Health and Safety standards of

EN60945: 2002

**and complies with the essential requirements of Directive
1999/5/EC**

Conformity assessment under Annex II of 1999/5/EC (internal production control) has
been undertaken.

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2			
3			
4			
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9			
10			

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For Your Safe Operation



Pictograms used in this Operation Manual

The following pictograms are used in this manual. The meaning of each symbols shall be well understood and the maintenance and inspection shall be carried out.



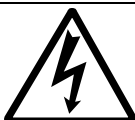



Symbol	Meaning
 Warning	Mark for warning This mark denotes that there is a risk of death or serious injury when dealt with incorrectly.
	Mark for danger of high voltage This mark denotes that there is a risk of death or serious injury due to electric shock when dealt with incorrectly.
 Caution	Mark for caution This mark denotes that there is a risk of slight injury or damages of devices when dealt with incorrectly.
	Mark for prohibition This mark denotes prohibition of specified conducts. Description of the prohibition is displayed near the mark.

Precautions on equipment

	Be careful of high voltage inside High voltage, which may risk you life, is used. This high voltage may remain in the circuit even after the power is switched off. To prevent contact with the high voltage circuits accidentally, a protective cover or the label with this mark is provided on the high voltage circuit. When the inside is to be checked, ensure to switch off the power and to discharge the residual voltage for safety. An engineer authorized by Kodan shall carry out the inspection and maintenance works.
 Warning	Power off in the boat An accidental power-on during works may result in worker's electrification. To prevent such accident in advance, ensure that power in the boat and on the equipment are switched off. Furthermore, it is safer to hang a caution tag saying "Under work" near the power switch of equipment.
 Warning	Be careful of dust Inhaled dust may cause respiratory affection. At the time of cleaning the inside of equipment, be careful not to inhale dust. Wearing a safety mask is recommended.
 Caution	Caution on location of installment The equipment shall not be installed at locations which are excessively damp and suffers from water drops. Otherwise, dew condensation may occur inside the display screen, and corrosion may occur inside the unit box.

 Caution	Measures against static electricity Static electricity may be generated from the carpet on the floor in the cabin or clothes made of synthetic fiber, and it may destroy the electronic components on circuit boards. The circuit boards shall be handled with appropriate measures against static electricity.
 Caution	Caution at installation of transducer Transducer shall be installed at locations where there is no effect by bubble and noise. Bubble and noise may seriously degrade the performance of this equipment.

Precautions on handling

 Warning	No disassembly or modification of this equipment is allowed. It may lead to failure, firing, smoking or electric shock. In case of failure, please contact Koden's dealers or Koden.
 Warning	In case of smoking or firing, switch off the power in the boat and of this equipment. It may lead to firing, electric shock or damages.
	Be careful of residual high voltage High voltage may remain in capacitors for several minutes after switching off the power. Before inspection of the inside, please wait at least 5 minutes after switching off or discharge the residual electricity in an appropriate manner. Then, start the work.
 Caution	The information displayed on this equipment is not intended to use for your navigation. For your navigation, be sure to see the specified materials.
 Caution	Please use the specified fuses. If un-specified fuses are used, they may cause firing, smoking or damages.
 Caution	Be sure to submerge the transducer in water before transmission. If not, it may be damaged.

Contents

Document Revision History.....	i
Important Notice.....	ii
For Your Safe Operation	iii
Contents	v
Introduction	vii
System Configuration.....	viii
System Configuration (with Junction box).....	ix
Configuration of Equipment	x
Chapter 1 Basic Operation	1-1
1.1 The name and function of each part.....	1-1
1.2 The name and function of each part.....	1-2
Power ON (When the power is switched on for the first time after installation)	
.....	1-2
Power ON (Ordinary)	1-2
Power OFF	1-2
1.3 Adjusting display/keyboards brightness and contrast.....	1-3
Adjusting display/keyboards brightness	1-3
Adjusting LCD contrast	1-3
1.4 Selecting the screen	1-3
1.5 Using MOB (Man Over Board) key.....	1-5
1.6 How to operate the Menu	1-6
Menu Operation	1-6
Menu 1: GPS.....	1-6
Menu 2: DGPS	1-7
Menu 3: Compensation	1-9
Menu 4: Initial setting	1-12
Menu 5: Interface	1-15
Explanation of sentence (Refer to “Chapter 4 Detail of the serial output data”)	
.....	1-18
Chapter 2 Maintenance and Inspection.....	2-1
Inspection.....	2-1
Cleaning	2-1
Display unit.....	2-1
If you suspect a trouble.....	2-1
Error Message	2-2
2.1 Initialize	2-3
Initialization of KGC-222 is performed.	2-3
Chapter 3 Installation	3-1
3.1 Items of Caution on Installation	3-1
Unpacking the components.....	3-1
Appearance varification of each unit and accessories	3-1
Selection of location for installation	3-1
Laying and Connection of Cable	3-3
Confirmation after Installation.....	3-4
3.2 Installation of Display unit.....	3-5
Table mounting.....	3-5

	Flush mounting	3-6
3.3	Installation of GPS antenna GA-12	3-7
	Antenna cable layout method	3-7
	Installation of GPS antenna	3-8
	Angle compensation of Antenna	3-9
	Connecting and waterproofing the connector	3-9
	Connecting the 60m antenna cable kit CW-394.KIT to GPS antenna	3-10
	Installing the bird protector to Antenna unit	3-11
3.4	Wiring	3-12
	Pin Assignment of Rear Connector	3-14
	Connection with Junction box (JB-35)	3-14
Chapter 4	Detail of the serial output data	4-1
4.1	Output data format	4-1
4.2	Details of the output data format	4-1
4.3	Output data specification	4-1
4.4	Details of output sentences	4-1
Chapter 5	Attached table	5-1
5.1	Menu Configuration	5-1
5.2	Specifications	5-2
5.3	Local geodetic system list	5-3
5.4	External view and dimensions	5-5
Chapter 6	INDEX	6-1

Introduction

KGC-222 is a GPS compass.

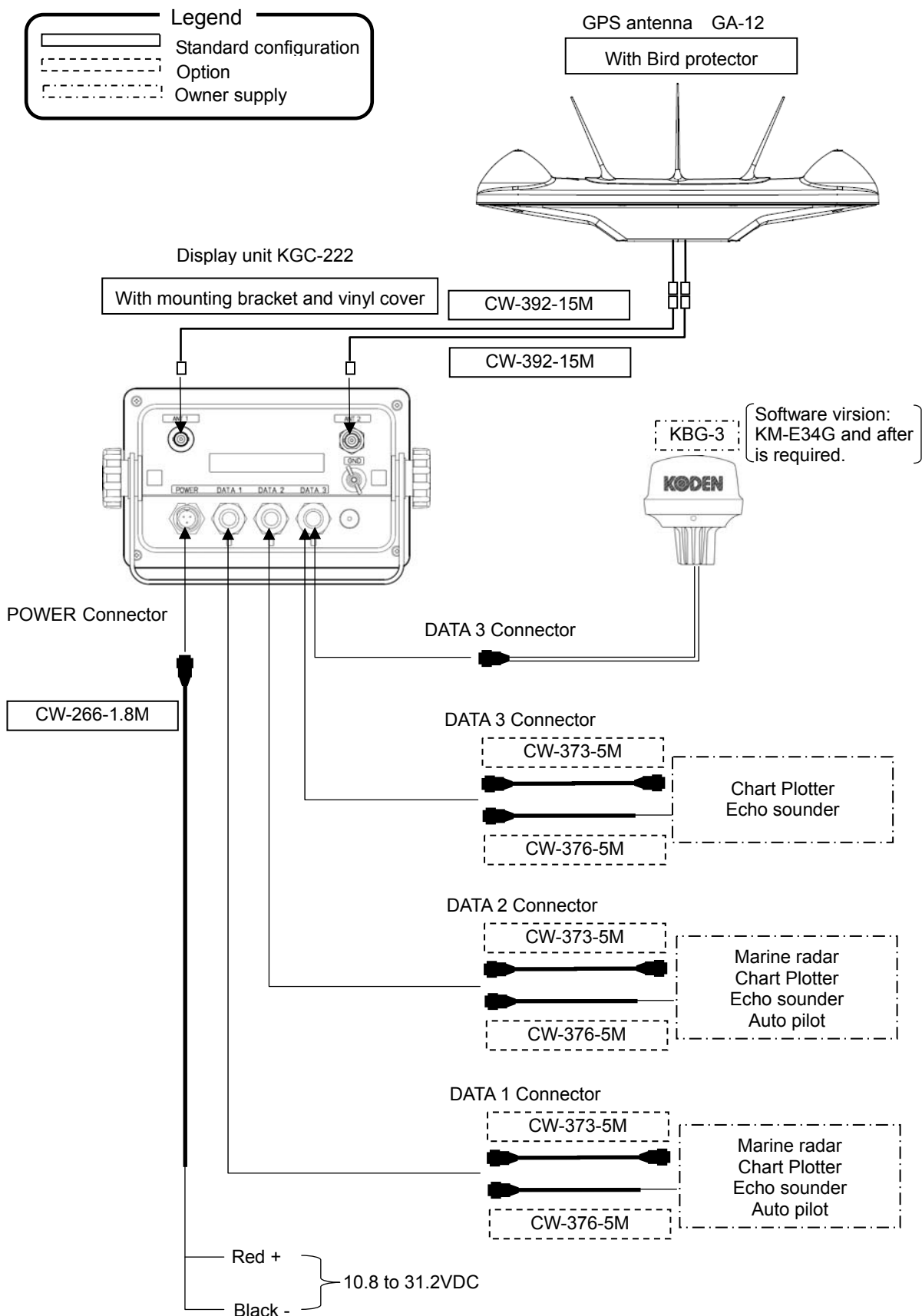
Through the use of GPS satellites, it outputs the heading of vessel with a high degree of accuracy by calibrating the phase difference of two GPS antennas.

The main features of this unit are as follows:

- KGC-222 consists of two main components, Display and Antenna.
Display unit has processor, receiver and LCD display built-in.
- KGC-222 has internal electronic compass as backup sensor.
This enables the backup sensor to output heading even if the GPS signals are interrupted in such case as the vessel passing under a bridge.
- KGC-222 can also output pitch / roll and heaving data.
When KGC-222 is used with an echo sounder with heaving compensation function, you can obtain stable sea bottom without effect from heaves and waves.
- It has 3 heading data output ports. Up to 5 ports will be available with connecting an optional junction box.
- It can be equipped at flying bridge with its high water protection capability.

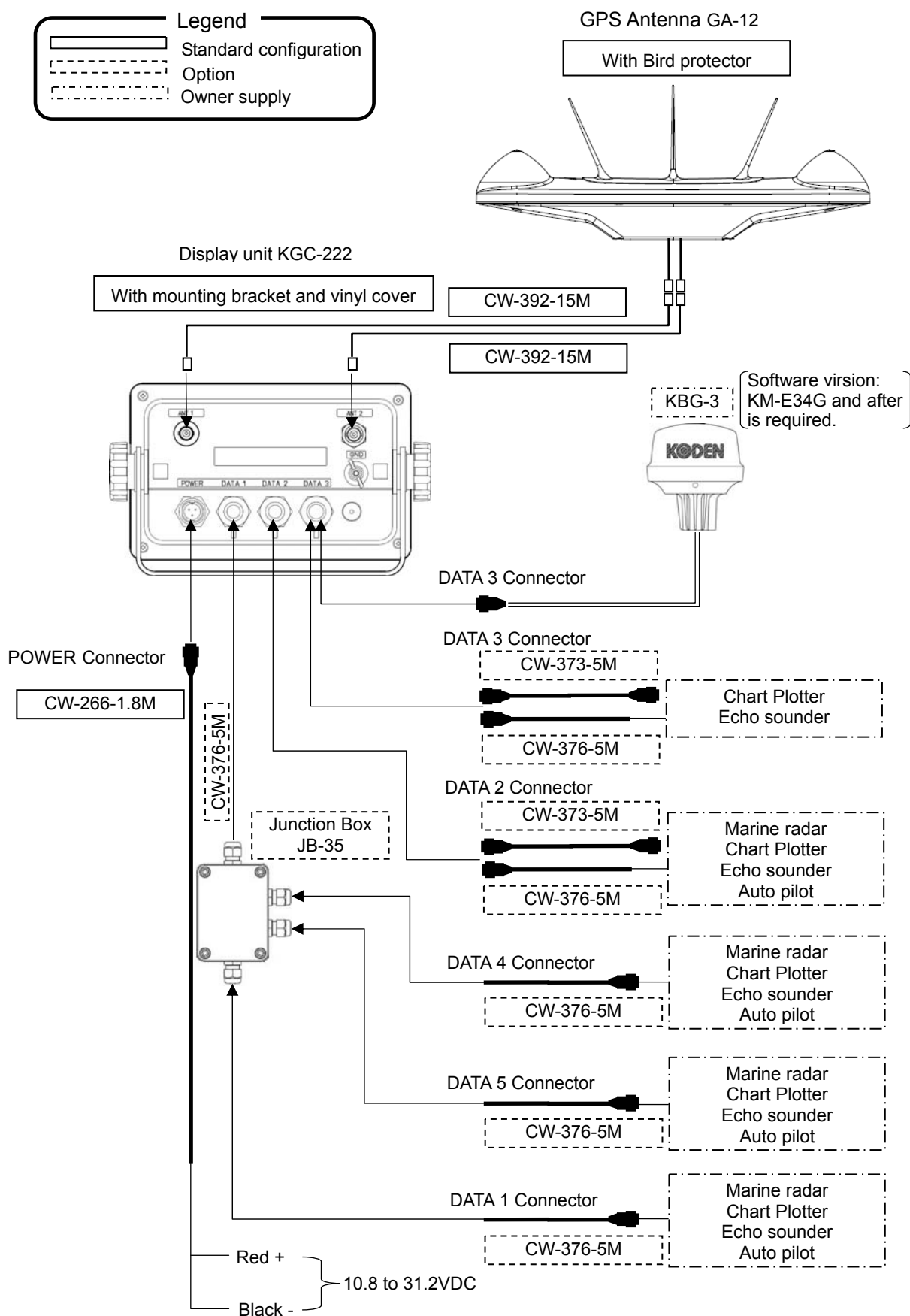
System Configuration

Connection diagram



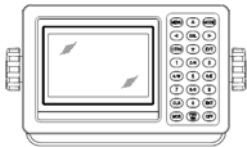


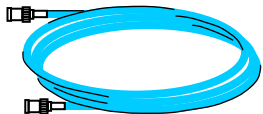
System Configuration (with Junction box)

Connection diagram

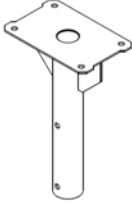
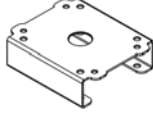


Configuration of Equipment

Standard Equipment Configuration List

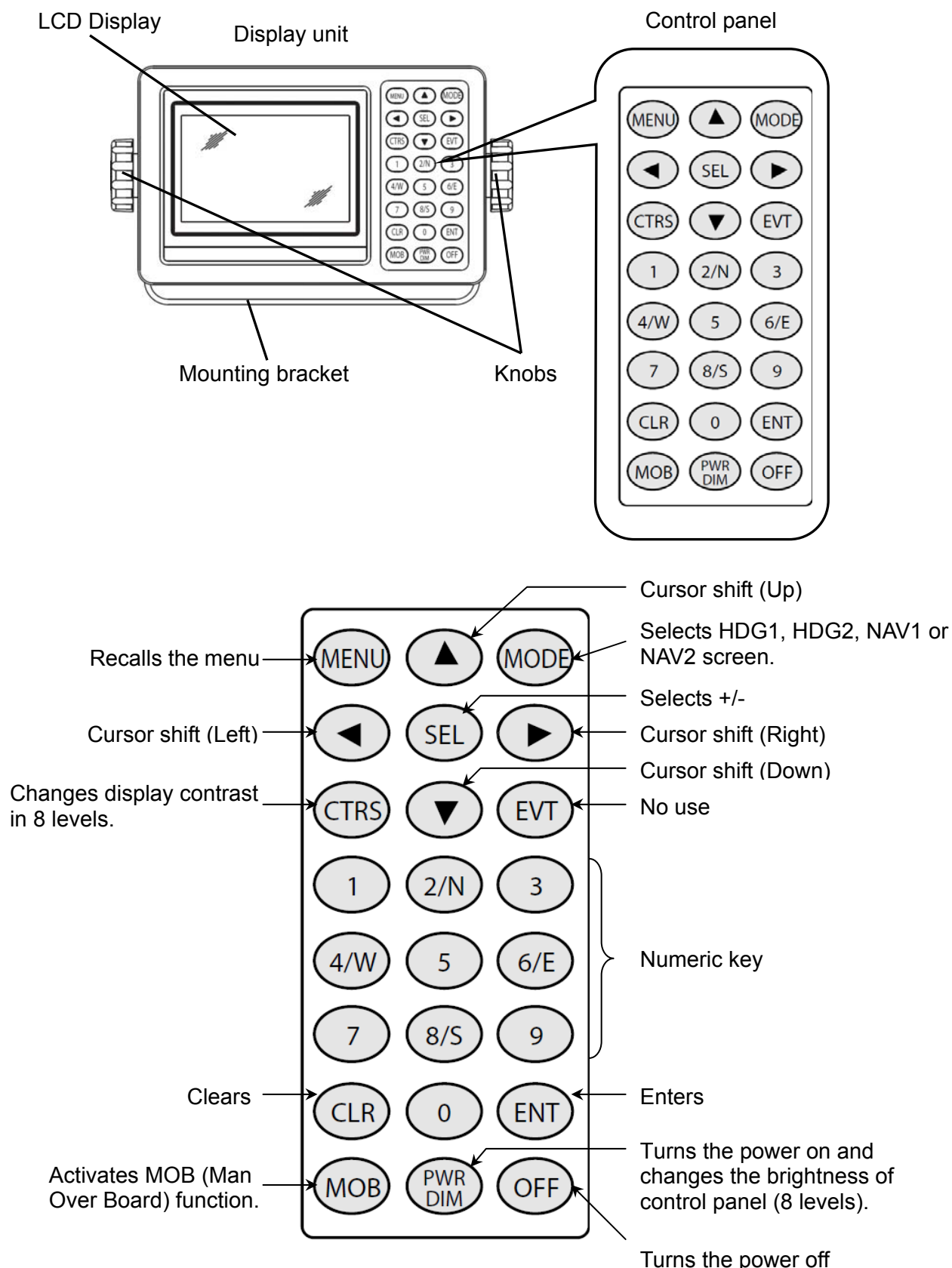
No.	Name of item	Type	Remark	Weight/ Length	Qty
1	Display unit 	KGC-222.MU	With mounting bracket and vinyl cover	0.87 kg	1
2	DC power cable 	CW-266-1.8M	With a 3-pin connector and one end plain	1.8m	1
3	GPS antenna 	GA-12	With bird protector		1
4	Antenna cable 	CW-392-15M	3D-2V With BNC connectors on the both sides	15m	2
5	Installation material	TPT5 X 20U T.5X20MMX10M 10M [gray] B8X25U	Truss tapping screw (2) Self-bonding tape (1) PVC tape (1) Hexagon bolt for antenna installation (4)		1 set
6	Operation Manual	KGC-222.OM.E	English		1
7	Cautionary Note	KGC-222.RM.E	English		1

Option List

No.	Name of Item	Specification	Remark	Weight/ Length
1	Connecting cable	CW-373-5M	6P water resistant connectors at both ends	5m
2		CW-376-5M	With 6P water resistant connector and one end plain	5m
3	Junction box	JB-35	1 input, 3 outputs with CW-376-5M	
4	Power rectifier	PS-010	With 5A fuses 2pcs	3.5kg
5	AC power cable	VV-2D8-3M	Without connectors on the both sides (cable for PS-010)	3m
6	Flush mount kit	FMK-1	Flush mount frame with bolts, washers and screws	
7	Antenna cable extension kit	CW-393-30M	5D-FB cable with BNC connectors at both ends (2cables/1 unit)	30m
8		CW-394-60M KIT	8D-SFA cable with N connector and other end plain, N connector, and CW-826-0.5M (2sets/1 unit)	60m
9	Connector	LTWBD-06BFFA-L1 80	6P water resistant connector	
10	Mount base 	D86MB21110	For Antenna (GA-12)	1
11	Attachment 	D86MB21120	Conversion metal attachment (Switching the mounting holes of GA11 to GA12)	1

Chapter 1 Basic Operation

1.1 The name and function of each part

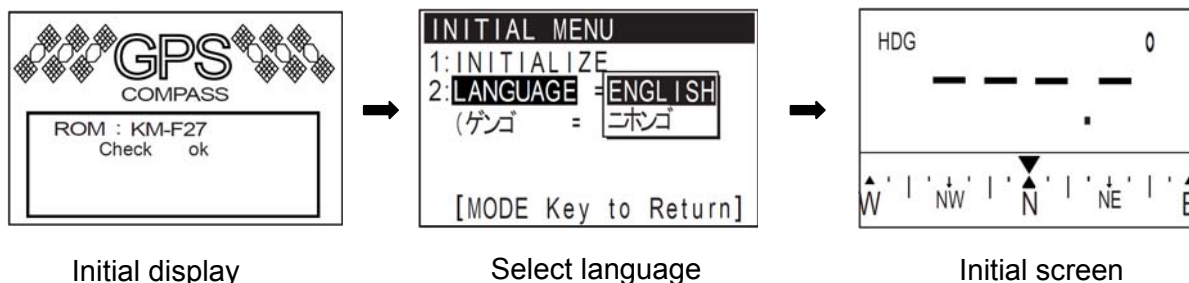


1.2 The name and function of each part


Power ON (When the power is switched on for the first time after installation)

1. Press  to power on.

When the power is on, the below screens are displayed in order.



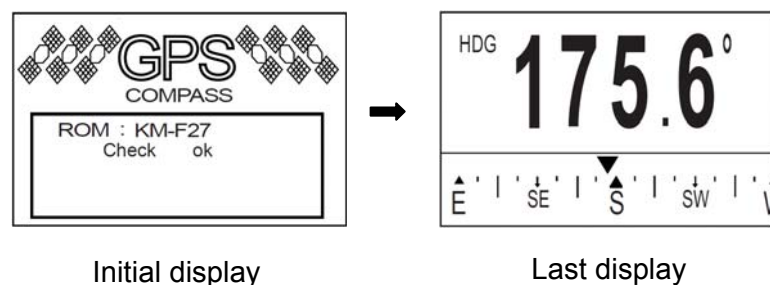
Initially, select the language with  /  key and press  in the LANGUAGE menu.

After that, press  key to display the initial screen.

Power ON (Ordinary)

1. Press  to power on.

When the power is on, the below screens are displayed in order.



Power OFF

1. Keep pressing  for 3 seconds for power off.

1.3 Adjusting display/keyboards brightness and contrast


Adjusting display/keyboards brightness

The brightness of display/keyboards can be adjusted.

1. Press  to change the display/keyboards brightness in 8 levels.

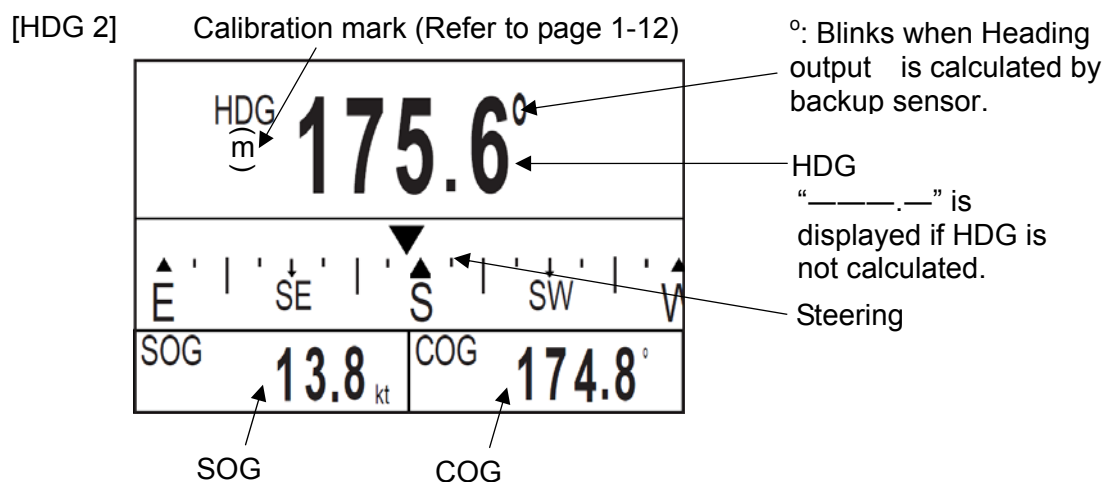
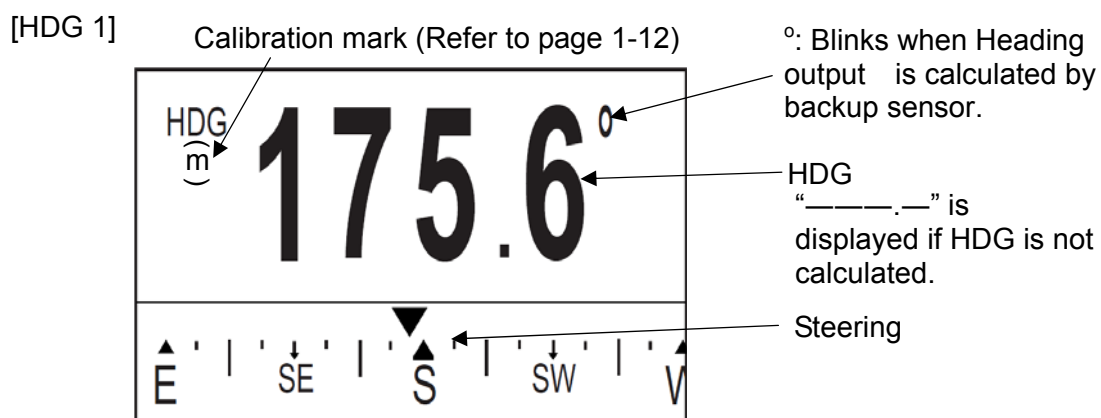
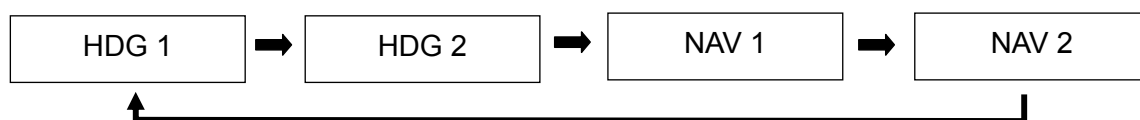
Adjusting LCD contrast

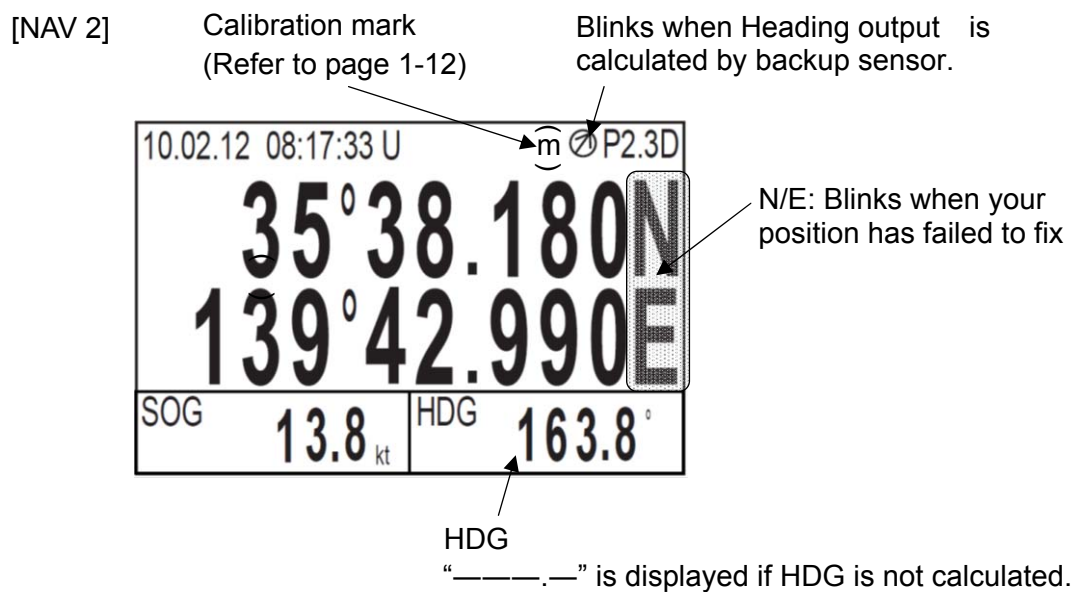
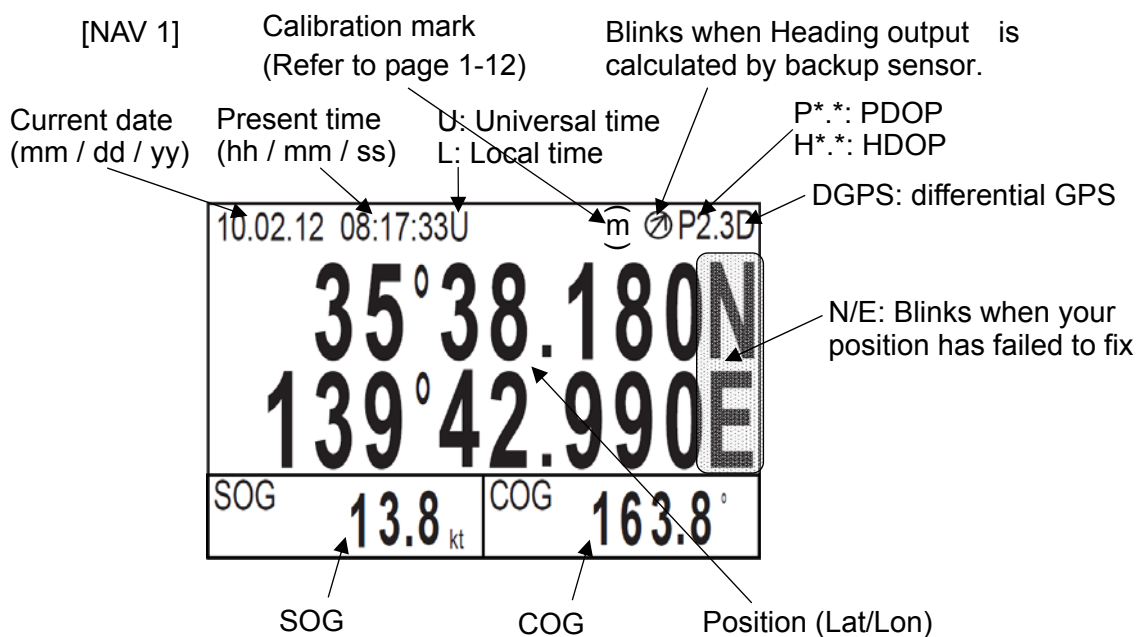
The contrast of the LCD can be adjusted.

1. Press  to change the LCD contrast in 8 levels.

1.4 Selecting the screen

There are four screen modes. Press  key to switch the screen sequentially.





1.5 Using MOB (Man Over Board) key

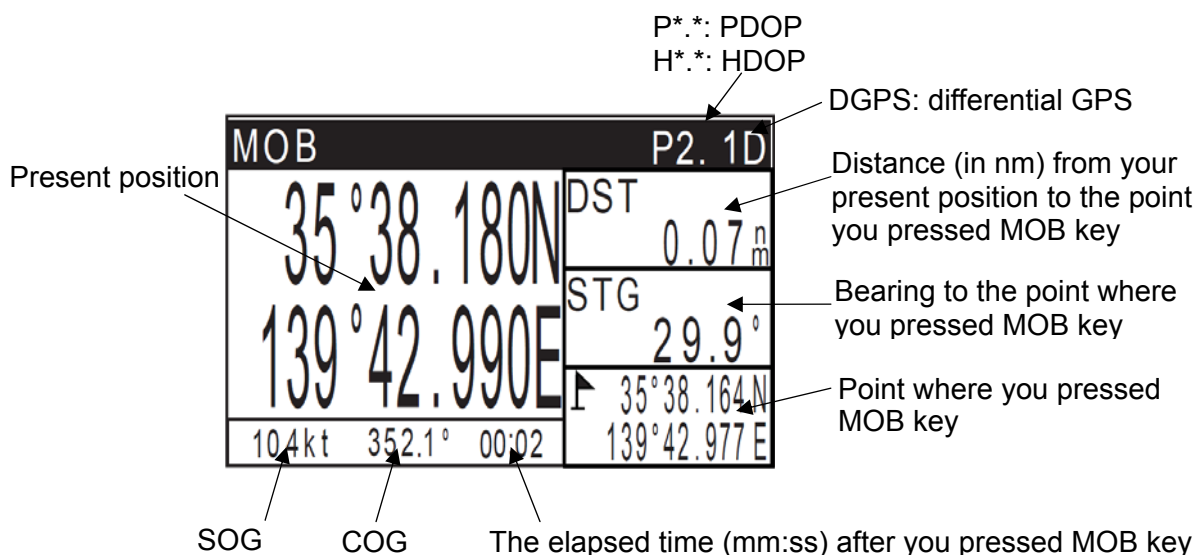
MOB function is provided for an emergency situation (if a person falls into the water) to make it easier to return to MOB point.

Press **MOB** key, and your position is stored immediately and MOB screen appears.

You can see the distance and bearing from your present position to the point you pressed MOB key.




Caution: MOB key does not function when positioning is invalid



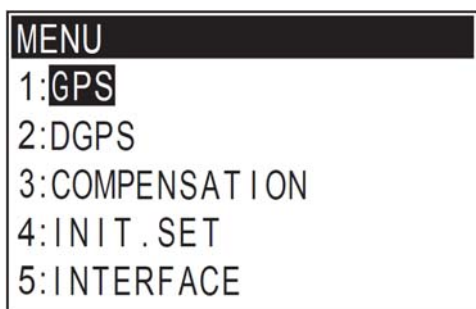
1.6 How to operate the Menu

Menu is used to set up and change items in display mode. Menu operation is provided in following manner.




Menu Operation

1. Press  to be displayed the menu.




KGC-222 has five sub menus.

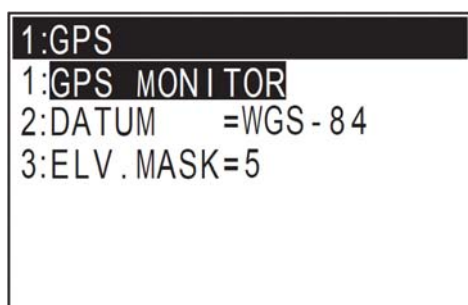


- 1: GPS
- 2: DGPS
- 3: Correction
- 4: Initialize
- 5: Interface

2. Press  /  key to move cursor and press  key to select a page, or press a numeric key directly.

Menu 1: GPS

Press  /  key to move cursor and press  key to select a page, or press a numeric key directly.

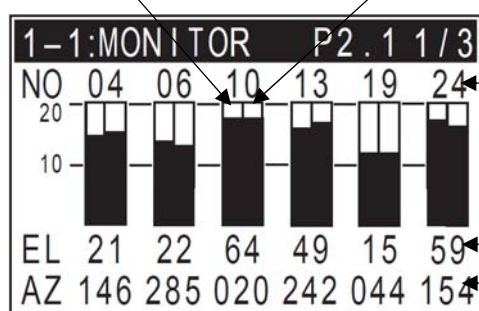


- 1: GPS MONITOR
- 2: DATUM
- 3: ELV.MASK (Elevation mask)

1. Monitoring GPS satellite signal reception

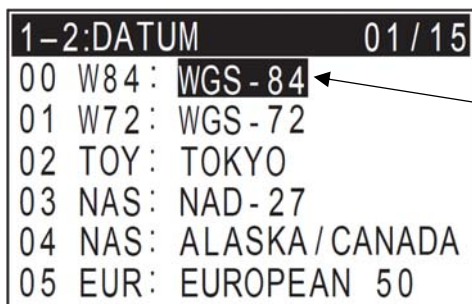
Elevation angle of satellite, Azimuth angle of satellite and Satellite signal S/N can be monitored.

Satellite signal S/N of ANT2 Satellite signal S/N of ANT1



2. Selecting a geodetic datum (Initial setup: WGS-84)

Geodetic datum of present position (Lat/Lon) can be selected.

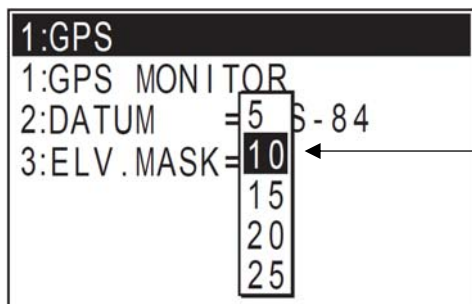


Press / to move cursor onto the desired geodetic datum.

Press .

3. Masking satellite elevation angle (Initial setup: 5degrees)

Positioning accuracy can be improved by masking the elevation angle.



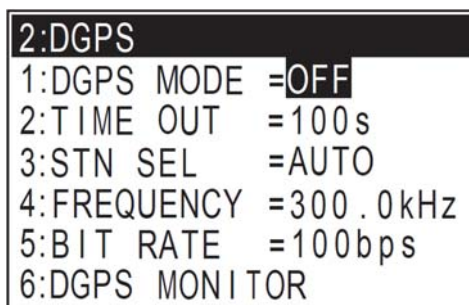
Press / to move cursor onto elevation angle masking.

Press .

Menu 2: DGPS

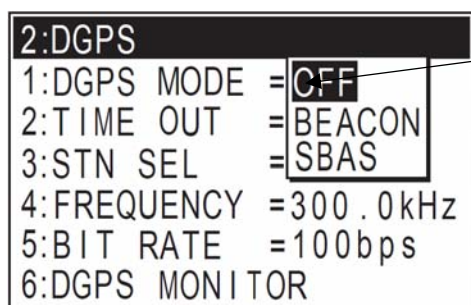
Select a Differential GPS type.

Press / key to move cursor and press key to select a page, or press a numeric key directly.



- 1: DGPS MODE
- 2: TIME OUT
- 3: STN SEL (Station select)
- 4: FREQUENCY
- 5: BIT RATE
- 6: DGPS MONITOR

1. DGPS type (Initial setup: OFF)



Press / to move cursor onto OFF, BEACON or SBAS.

Press .

- OFF: Canceled DGPS positioning
- BEACON: DGPS MODE by MF beacon
(Effective only when connected KBG-3)
- SBAS: Satellite information
(MSAS, WAAS, EGNOS)

2. Setting a DGPS timeout (Initial setup: 100 sec)

If the correction data from beacon receiver is interrupted or has errors, NAVIGATOR holds the last differential correction for the duration of timeout. You can set TIMEOUT to 010 to 180 seconds. However, the position accuracy is reduced as TIMEOUT lengthens.

```
2:DGPS
1:DGPS MODE =OFF
2:TIME OUT  =100s
3:STN SEL   =AUTO
4:FREQUENCY =300.0kHz
5:BIT RATE  =100bps
6:DGPS MONITOR
```

Enter a timeout (010 to 180 seconds) using numeric keys.

Press **ENT**.

3. Selecting a beacon station (Initial setup: MANUAL)

A beacon station can be selected in both the manual or auto mode. In auto mode, an optimal reference station is selected automatically. (Effective only when connected to KBG-3)

```
2:DGPS
1:DGPS MODE =OFF
2:TIME OUT  =100s
3:STN SEL   =AUTO
4:FREQUENCY =MAN. kHz
5:BIT RATE  =100bps
6:DGPS MONITOR
```

4. Setting receiving frequency of beacon station

When MAN. is selected in STN SEL nemu, a frequency of a beacon station must be entered. (Effective only when connected to KBG-3)

```
2:DGPS
1:DGPS MODE =OFF
2:TIME OUT  =100s
3:STN SEL   =MAN.
4:FREQUENCY =300.0kHz
5:BIT RATE  =100bps
6:DGPS MONITOR
```

Enter receiving frequency (283.5 to 325.0 kHz) of beacon station using numeric keys.

Press **ENT**.

5. Setting bit rate of beacon station

When MAN mode is selected in STN SEL, bit rate of the beacon station must be entered.
(Effective only when connected to KBG-3)

```

2:DGPS
1:DGPS MODE =OFF
2:TIME OUT  =100s
3:STN SEL   =MAN.
4:FREQUENCY =50.0kHz
5:BIT RATE  =100bps
6:DGPS MONITOR 200
  
```

Press  /  to move cursor onto bit rate.

Press .

6. DGPS monitor

DGPS monitor provides information on the DGPS beacon receiver interface and receiving status. (Frequency being received, bit rate, S/N ratio, ID No. and age of DGPS data)

```

2-6:DGPS MONITOR
FREQUENCY=000.0kHz
BIT RATE  =000bps
S/N       =00dB
ID NO     =0000
DATA AGE  =000
  
```

← Frequency being received

← Bit rate




← S/N ratio

← ID No. (beacon station number)

← Age of DGPS data

Menu 3: Compensation

The below items can be compensated.

Press  /  key to move cursor and press  key to select a page, or press a numeric key directly.

```

3:COMPENSATION
1:HDG      =+000.0°
2:DISPLAY  =+000.0°
3:MAG.V    =MAN. +000.0°
4:TIME     =+00:00
  
```

1: HDG (Bearing)

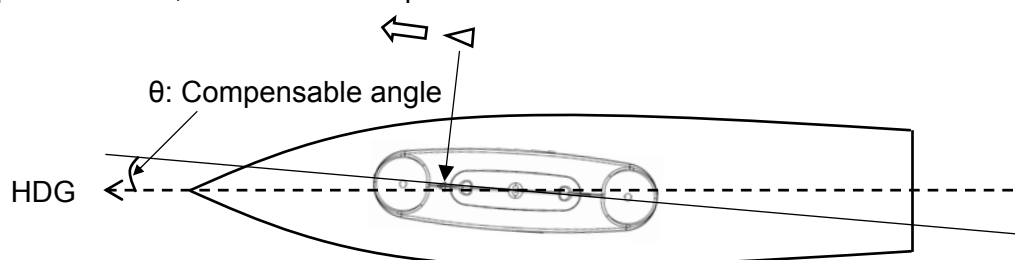
2: installation angle of DISPLAY

3: MAG.V (Magnetic variation)

4: TIME (Time difference)

1. HDG (Initial setup: +000.0°)

The GPS antenna should be installed on the keel line with the BOW mark oriented to the ship's bow. If not, it should be compensated.



When it is installed with 5° clockwise, enter a compensation value [-005.0°] using numeric keys.

When it is installed with 5° counterclockwise, enter a compensation value [+005.0°] using numeric keys.

3:COMPENSATION	
1:HDG	=+000.0°
2:DISPLAY	=+045.0°
3:MAG.V	=MAN. +000.0°
4:TIME	=+00:00

Press **SEL** to move cursor onto [+] or [-].

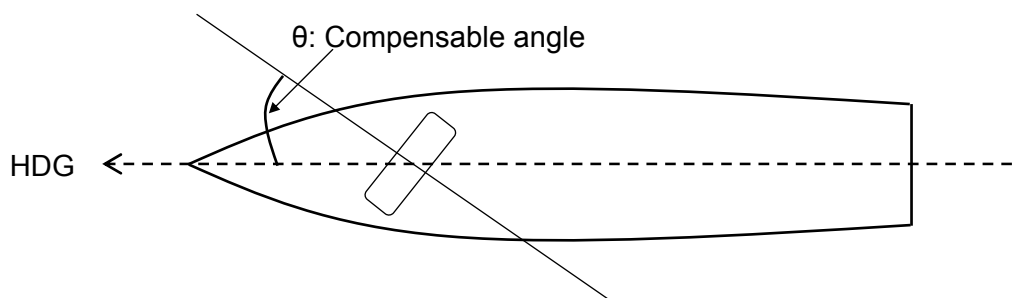
Enter a compensation value using numeric keys.

Press **ENT**.

To release HDG compensation, press **CLR** to move cursor onto [+] or [-].

2. Setting angle of Display unit (Initial setup: +000.0°)

When Pitch/Roll and Heaving data used with other equipment, it may be necessary to enter compensated value of displays installation. However, when the install position of the display unit is fit to the Heading line, it is not necessary to compensate.



When it is installed with 45° clockwise, enter a compensation value [+045.0°] using numeric keys.

3:COMPENSATION	
1:HDG	=+000.0°
2:DISPLAY	=+045.0°
3:MAG.V	=MAN. +000.0°
4:TIME	=+00:00

Press **SEL** to move cursor onto [+] or [-].

Enter a compensation value using numeric keys.

Press **ENT**.

To cancel DISPLAY compensation, press **CLR** to move cursor onto [+] or [-].

When Pitch/Roll and Heaving data are not used with other equipment, it is not necessary to compensate.

3. Magnetic variation (Initial setup: MANUAL +000.0°)

When MAG. V is set to AUTO, the magnetic heading will be compensated at the current Latitude/ Longitude.

3:COMPENSATION	
1:HDG	=+000.0°
2:DISPLAY	=+000.0°
3:MAG.V	= AUTO +000.0°
4:TIME	= MAN. 0

Press ∇ / \blacktriangle to move cursor onto AUTO or MANUAL.

Press **ENT**.

(Manual compensation)

3:COMPENSATION	
1:HDG	=+000.0°
2:DISPLAY	=+000.0°
3:MAG.V	=MAN. + 006.8°
4:TIME	=+00:00

Press **SEL** to move cursor onto [+] or [-].
Enter a deviation value using numeric keys.

Press **ENT**.

To cancel MAG.V compensation, press **CLR** to move cursor onto [+] or [-].

4. Time (Initial setup: +00:00)

A local time can be displayed by entering a time difference from the Greenwich standard time (GMT).

Enter the time difference using numeric keys.

3:COMPENSATION	
1:HDG	=+000.0°
2:DISPLAY	=+000.0°
3:MAG.V	=MAN. +000.0°
4:TIME	= + 09:00

Press **SEL** to move cursor onto [+] or [-].
Enter a time difference using numeric keys.

Press **ENT**.

To cancel TIME compensation, press **CLR** to move cursor onto [+] or [-].

NAV 1 Display: Before entering the time difference




10.02.12 08:17:33U		P2.3D	
35°38.180N			
139°42.990E			
SOG	13.8 _{kt}	COG	163.8°

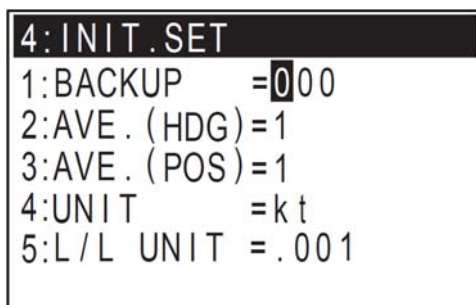
: After entering the time difference
Display "L": Local time
"U": Universal time

10.02.12 08:17:33U		P2.3D	
35°38.180N			
139°42.990E			
SOG	13.8 _{kt}	HDG	163.8°

Menu 4: Initial setting

Initial settings setup

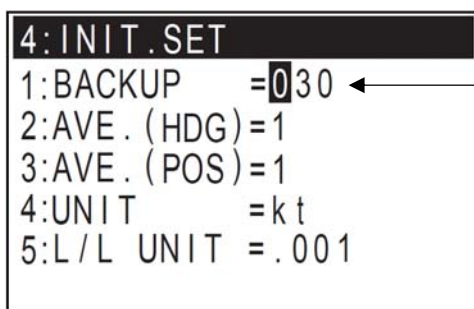
Press  /  key to move cursor and press  key to select a page, or press a numeric key directly.



- 1: BACKUP
- 2: AVE. (Heading Average)
- 3: AVE. (Position Average)
- 4: UNIT (Range)
- 5: Lat/Lon UNIT

1. BACKUP time (Initial setup: 000 sec)

If heading becomes temporarily unavailable due to signal blocking or other reason, HDG can be provided by the internal auxiliary backup sensor. The backup duration time can be set from 1sec to 600 sec ("000" means no backup.)

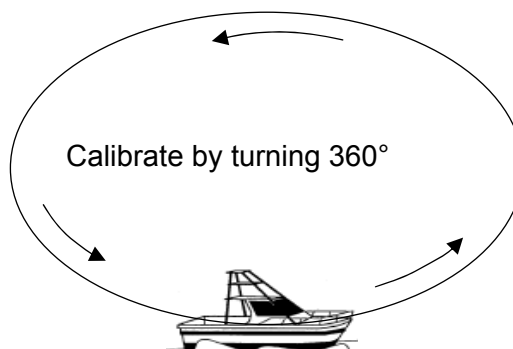
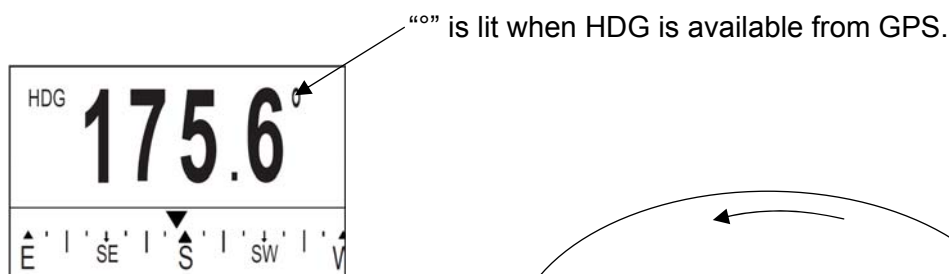


Enter a backup time (0 to 600 seconds) using numeric keys.

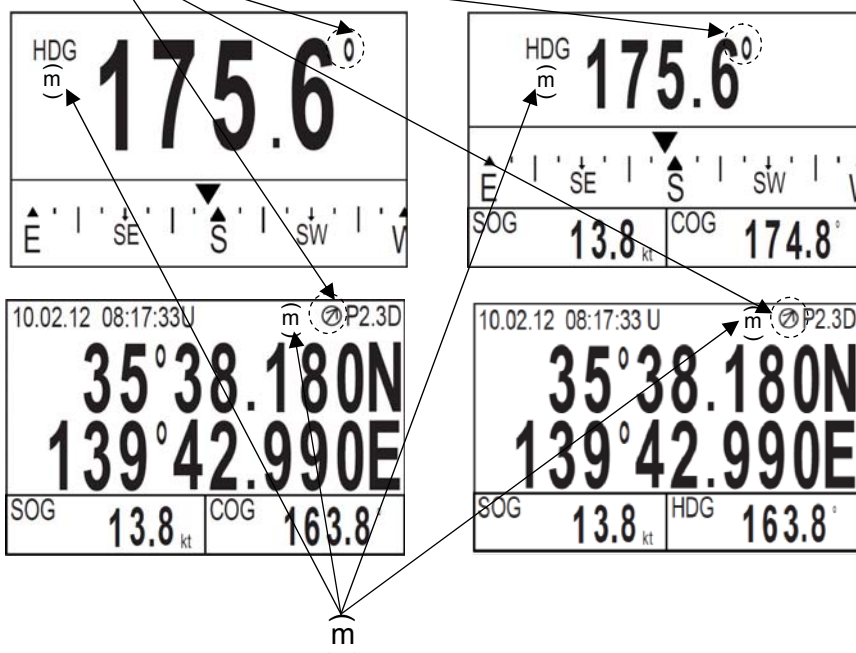
Press .

 **Caution: Heading accuracy is reduced during the backup.**

If you choose to use the internal backup sensor and set the backup duration other than 000sec, internal sensor calibration must be completed by turning the vessel 360° at less than 5 knots. When the calibration is completed, the calibration mark turns off from blinking. (For calibration information refer to page 1-13)



Blinks when Heading output is provided by the backup sensor.



[Calibration mark]: This is displayed during backup ON.

Blinking: Calibration is not completed.

Off: Calibration is completed.

Lit: Heading output is provided by the backup sensor.



Caution: When calibration is not finished, a calibration mark is blinking and Heading output is not provided by the backup sensor built in.

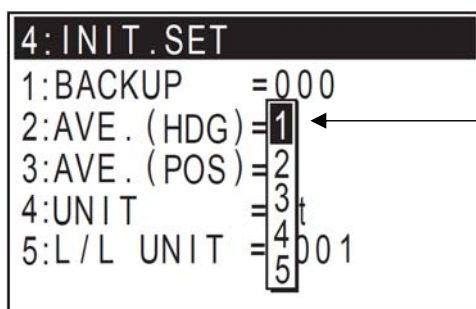


Caution: During system backup from internal backup sensor do not tilt or rotate the display as it will cause HDG to provide incorrect data.

2. Setting average constants of HDG (Initial setup: 3)

This setting is used to the averaging of the Heading to stabilize the HDG.

The maximum averaging rate is "5" and the minimum averaging rate is "1". When a higher value is selected, heading data is averaged more often and more stable, but the averaged HDG will be far from the actual Heading. When a lower value is selected, heading data is averaged less, but HDG will not be far from the actual Heading and react quickly.



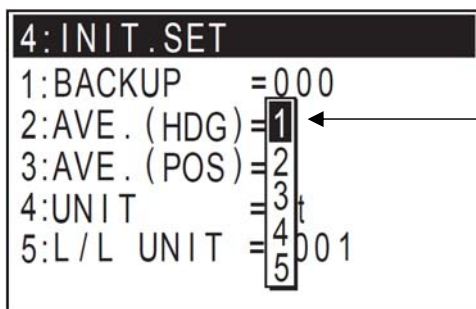
Press / to move cursor onto numeric value (1 to 5).

Press .

3. Setting average constants of GPS position (Lat/Lon) (Initial setup: 1)

Use the averaging function to compare GPS sensor signals several times and get their average. This setting is used to the averaging of the positioning to stabilize the position.

The maximum averaging rate is "5" and the minimum averaging rate is "1". When a higher value is selected, position data is averaged more often and stable more, but the averaged position will be far from the actual position. When a lower value is selected, a position data is averaged less but a position data will not be far from the actual position and react quickly.

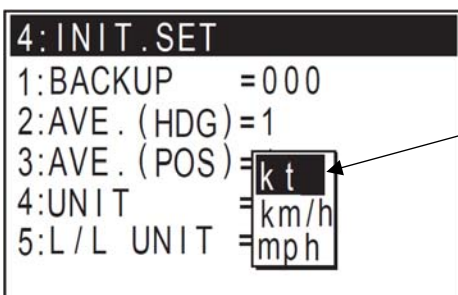


Press / to move cursor onto numeric value (1 to 5).

Press .

4. UNIT of range (Initial setup: nm)

The measuring unit of distance (to WPT or final destination) and speed on MOB screen. (kt, km/h, mph) can be changed



Press / to move cursor onto unit (kt, km/h, or mph).

Press .

5. Lat/Lon UNIT (Initial setup: 0.001)

The following operations enable to display the latitude and longitude of present position up to 0.0001 minute. If you select .0001', the latitude and longitude data of GGA/RMC sentence will also be output in 0.0001'.

```

4: INIT.SET
1: BACKUP      =000
2: AVE. (HDG) =1
3: AVE. (POS) =1
4: UNIT        =.001
5: L/L UNIT    =.0001
  
```

Press / to move cursor onto unit (.001 or .0001).

Press .

Menu 5: Interface

The following menu is used to setup output for optimal connection with external equipment.

Press / key to move cursor and press key to select a page, or press a numeric key directly.

```

5: INTERFACE
1: CONNECTOR =DATA1
2: INITIALIZE=COMPASS
3: BAUD RATE =4800
4: TALKER ID =GP
5: SENTENCE EDIT
  
```

1: CONNECTOR

2: INITIALIZE

3: BAUD RATE

4: TALKER ID

5: SENTENCE EDIT

1. CONNECTOR (Initial setup: DATA 1)

Select the DATA connector to set up. (DATA1, DATA2 or DATA3)

```

5: INTERFACE
1: CONNECTOR =DATA1
2: INITIALIZE=DATA2SS
3: BAUD RATE =DATA3
4: TALKER ID =GP
5: SENTENCE EDIT
  
```

Press / to move cursor onto DATA1, DATA2 or DATA3.

Press .

```

5: INTERFACE
1: CONNECTOR =DATA1
2: INITIALIZE=DATA2SS
3: BAUD RATE =DATA3
4: TALKER ID =DATA4
5: SENTENCE EDIT
  
```

DATA4 and DATA5 are added to the list when Junction box JB-35 is connected.

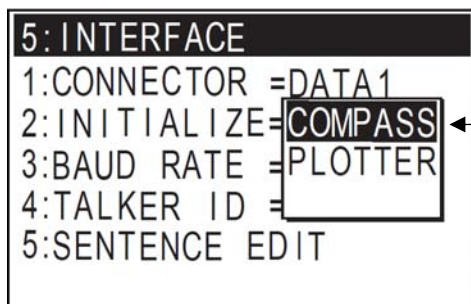
Refer to page 3-12

2. INITIALIZE

One touch optimal output sentence setup based on equipment connected.

COMPASS: Should be selected when connected to marine radar and requires high rate HDG.

PLOTTER: Should be selected when connecting to plotter and no need for a high speed HDG.



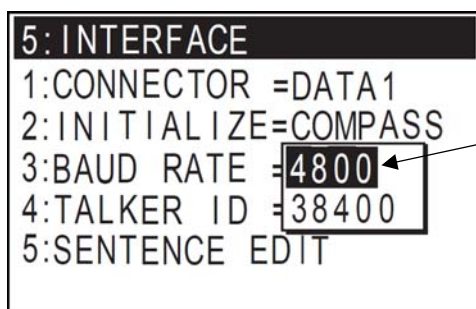
```
5: INTERFACE
1:CONNECTOR =DATA1
2:INITIALIZE=COMPASS
3:BAUD RATE =PLOTTER
4:TALKER ID =
5:SENTENCE EDIT
```

Press  /  to move cursor onto compass or plotter.

Press .

3. BAUD RATE (Initial setup: 4800)

Select the baud rate output (4800 or 38400 baud) for proper connection with external equipment.



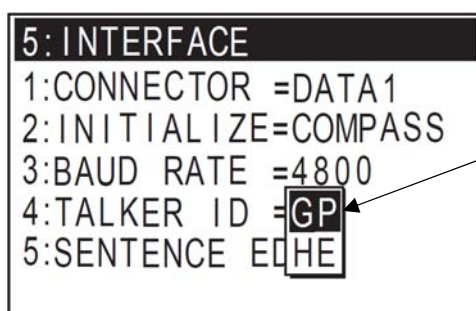
```
5: INTERFACE
1:CONNECTOR =DATA1
2:INITIALIZE=COMPASS
3:BAUD RATE =4800
4:TALKER ID =38400
5:SENTENCE EDIT
```

Press  /  to move cursor onto baud rate (4800 or 38400).

Press .


4. TALKER ID (Initial setup: GP)

Select the TALKER ID (GP/HE) to fit a connected equipment.



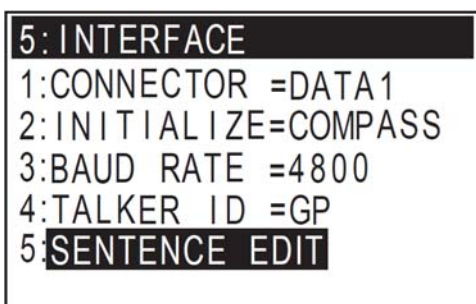
```
5: INTERFACE
1:CONNECTOR =DATA1
2:INITIALIZE=COMPASS
3:BAUD RATE =4800
4:TALKER ID =GP
5:SENTENCE EDIT
```

Press  /  to move cursor onto talker ID (GP or HE).


Press .

5. SENTENCE EDIT

Output sentences of the data port selected by [1: CONNECTOR] can be edited.



```
5: INTERFACE
1:CONNECTOR =DATA1
2:INITIALIZE=COMPASS
3:BAUD RATE =4800
4:TALKER ID =GP
5:SENTENCE EDIT
```

Press  to move SENTENCE EDIT 1/2 or 2/2.

SENTENCE EDIT 1/2

5-5:SENTENCE EDIT 1/2

GGA=1	VTG=1	HDT=10
GLL=0	ZDA=1	HDM=00
RMC=0	GSA=0	ROT=00
DTM=1	GSV=0	MSS=0

0% 100%

Press / / / to move cursor onto sentence.

Press .

5-5:SENTENCE 00/IT 1/2

GGA=1	VTG=	01	HDT=10
GLL=0	ZDA=	05	HDM=00
RMC=0	GSA=	10	ROT=00
DTM=1	GSV=	20	MSS=0
		25	
		50	

0% 100%

Press / to move cursor onto output interval.

Press .

00: No output		
01: 1s	05: 200ms	10: 100ms
20: 50ms	25: 40ms	50: 20ms

SENTENCE EDIT 2/2

5-6:SENTENCE EDIT 2/2

PKODA	=0	PKODQ=0
PKODG, 1	=0	ATT=00
PKODG, 7	=0	HVE=00
PKODG, 21	=00	

0% 100%

Press / / / to move cursor onto sentence.

Press .

5-6:SENTENCE EDIT 2/2

PKODA	=0	PKODQ=0
PKODG, 1	=1	ATT=00
PKODG, 7	=0	HVE=00
PKODG, 21	=00	

0% 100%

Press / to move cursor onto output interval.

Press .

0: No output
1: 1sec

Chapter 2 Maintenance and Inspection

Inspection

The daily maintenance and inspection extends the life of equipment. To always keep the equipment in the best condition, implement periodically the inspection shown in the table below.

Item	Content of Inspection
Connector at the rear of Display unit	Check the looseness.
Wiring of cables	Check the wiring of cables connecting the equipment and the damage of cable.
Grounding of display unit	Scrape the rust off the ground terminal and make its contact well.

Cleaning

Display unit

Contamination on the screen may cause faint images. For cleaning the screen, wipe the screen with soft and clean cloth dipped with diluted neutral detergent. Pay full attention as the screen is easily getting scratched. No thinner shall be used.



**Caution: Do not use a solvent such as paint thinner, acetone, alcohol, and benzene, etc.
Strong rubbing may cause bruising and scratching.**

For cleaning the housing, do not use a solvent such as thinner or alcohol. Painting on the surface and characters at the operating portion may melt. After wiping with soft and clean cloth dipped with diluted neutral detergent, wipe away with dry soft and clean cloth.

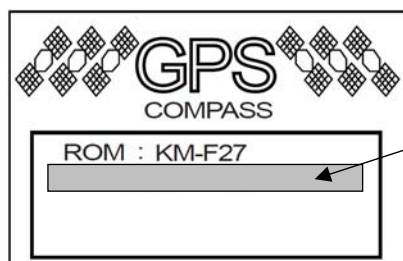
If you suspect a trouble

Symptom	Possible cause of trouble	Measure
Even with power on, nothing is displayed.	<ul style="list-style-type: none"> Power connector may be loose. The power supply voltage is out of specification (10.8 to 31.2 VDC). Poor connection between power cable and battery. Defect of LCD display block. 	<ul style="list-style-type: none"> Connect the connector securely. Use a proper power as per specification. Check the connection between power cable and battery. Consult a repair shop or sales agent.
Heading bearing is not displayed. (---.-° is displayed)	<ul style="list-style-type: none"> Antenna Connection on the back of display may be loose. Antenna View may be blocked by obstacles. 	<ul style="list-style-type: none"> Connect the connector securely. Change the installation position of the Antenna.

Heading bearing is displayed, but heading output is not available.	<ul style="list-style-type: none"> • DATA connector of Display unit may be loose. • The baud rate output for external equipment is wrong. • Heading data output may be turned off in settings. 	<ul style="list-style-type: none"> • Tighten the connector surely. • Change the baud rate output (4800 or 38400 baud) for proper connection with external equipment.(Refer to MENU 5:Interface, 3:BAUD RATE) • Check Sentence output.
Incorrect heading bearing data is displayed / output.	<ul style="list-style-type: none"> • Cables on the back of the display may be swapped between ANT1 and ANT2 • Forward orientation of the antenna may not be correct. 	<ul style="list-style-type: none"> • Connect the bow side antenna cable to ANT 1 of Display unit, and connect the stern side antenna cable to ANT 2 of Display unit. • The direction of GPS antenna should be installed in conformity to the ship's bow. Compensate of HDG. (Refer to MENU 3: Compensation, 1:HDG)
The heading data is not compensated. The rolling/pitching data is abnormal.	<ul style="list-style-type: none"> • Compensated value of Display unit installation is wrong. 	<ul style="list-style-type: none"> • Input the Compensation correct angle value of Display unit installation correctly. (Refer to MENU 3: Compensation, 2:DISPLAY)


Error Message

The error messages are as follows.



Error message display area

Error message	Possible cause	Measure
Power Down ****	<ul style="list-style-type: none"> • Instantaneous interruption of the power source is occurred. • Power supply voltage is below normal. 	<ul style="list-style-type: none"> • Check the connection between power cable and battery. • Set the power supply voltage to more than 10.8V.
Vin High ****	<ul style="list-style-type: none"> • Power supply voltage is too high. 	<ul style="list-style-type: none"> • Set the power supply voltage below 31.2V.
Over Load ****	<ul style="list-style-type: none"> • Electrical power of internal equipment is over load. (For effect of external equipment) • Electrical power of internal equipment is over load. (Display unit may be broken.) 	<ul style="list-style-type: none"> • Check the external equipment. • Consult a repair shop or sales agent.














RTC Error ****	<ul style="list-style-type: none"> • Back up of Time Clock failure. 	<ul style="list-style-type: none"> • Consult a repair shop or sales agent.
ANT Error ****	<ul style="list-style-type: none"> • Short-circuits of the antenna cable. 	<ul style="list-style-type: none"> • Consult a repair shop or sales agent.
RAM1 Error ****	<ul style="list-style-type: none"> • Backup DATA failure. 	<ul style="list-style-type: none"> • Press  to initialize. • If the situation does not change even if the unit has been initialized, consult a repair shop or sales agent.
FPGA Error **** LSI Error **** CPU1 Error **** ROM2 Error **** CPU2 Error ****	<ul style="list-style-type: none"> • Internal circuits or parts failure. 	<ul style="list-style-type: none"> • Consult a repair shop or sales agent.

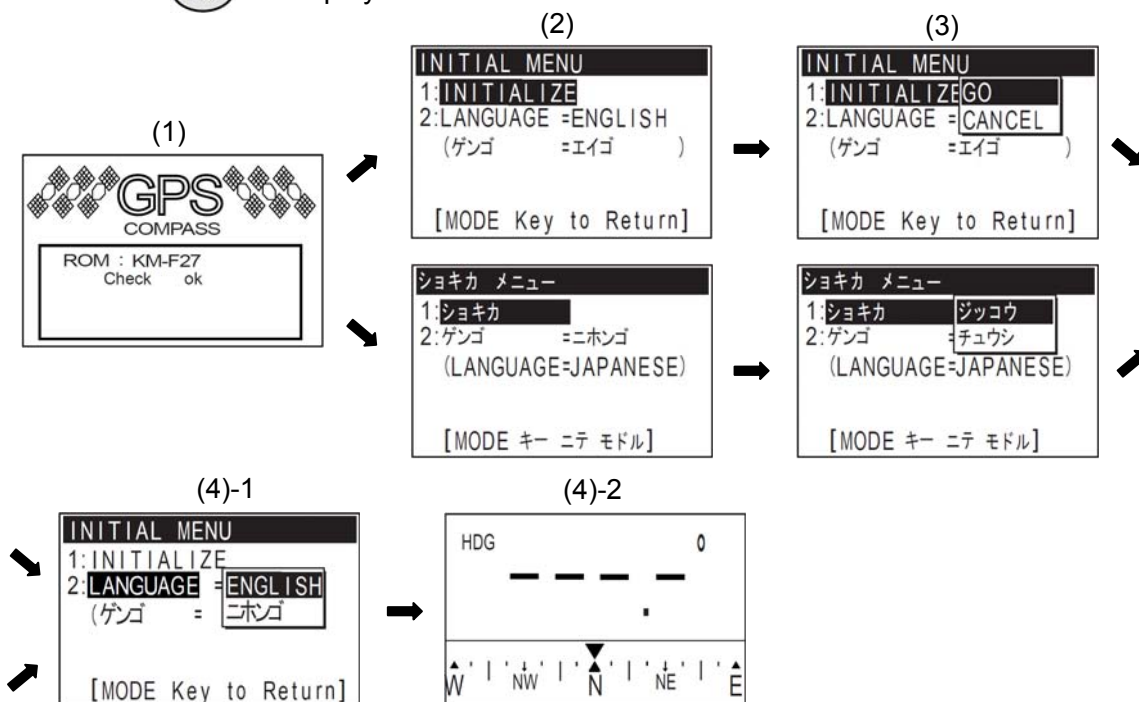
2.1 Initialize

Initialization of KGC-222 is performed.

When some malfunction of Display unit is found, following initialization procedure may be required. It returns all the settings in the menu to the factory settings. Before initializing please note all system parameters and reset them after initialize.

Initialization

- (1) Press  to power on.
- (2) Press  →  →  →  to move to INITIAL MENU during displaying self check.
- (3) [] or [INITIAL MENU] will appear at the top of the display.
Press  →  →  to initialize.
- (4) Press  /  to select the language to be used, and press  .
Press  to display the Initial screen.



Chapter 3 Installation

3.1 Items of Caution on Installation

In order to obtain the maximum performance of the GPS compass, this compass should be installed by a qualified technician. Installation procedures include the following:

- (1) Unpacking the components
- (2) Inspection of configuration unit, spare parts, accessories and installation materials
- (3) Checking of supply voltage and current capacity
- (4) Selection of installation location
- (5) Installation of Display unit and Antenna
- (6) Attachment of accessories
- (7) Planing and implementation of cable layout and connection
- (8) Coordinataion after installation

Unpacking the components

Unpack components and check that all of the items correspond with the contents discription of the packing list. When a discrepancy or damage has been found, contact the dealer you purchased this product.

Appearance varification of each unit and accessories

Inspect the appearance of each components and accessories and check that no dents or damage exist.

If any dents or damages exist and they are believed to be caused by accident during transportation, contact the transportation and insurance company and consult our sales company or our dealer nearest to you.

Selection of location for installation

In order to obtain the maximum performance of the unit, it is necessary to install following below recommendations.

1. Display unit of KGC-222

- (1) Install the display in the bridge where it will be easy to see and read.
- (2) Choose the best location from humidity, spray, rain and direct sunlight.
- (3) Keep safety distance from magnetic objects such as magnetic compasses.
- (4) Keep sufficient maintenance space around the equipment, pay attention to the back of the display where cables are connected.
- (5) Keep the equipment as far away from wireless transmitter/receivers as possible.



Caution: The Display unit is not waterproof. Avoid excessively damp place. Do not install the equipment in the place suffering from excessive water-drops. Otherwise, the corrosion may occur inside.

2. GPS antenna: GA-12

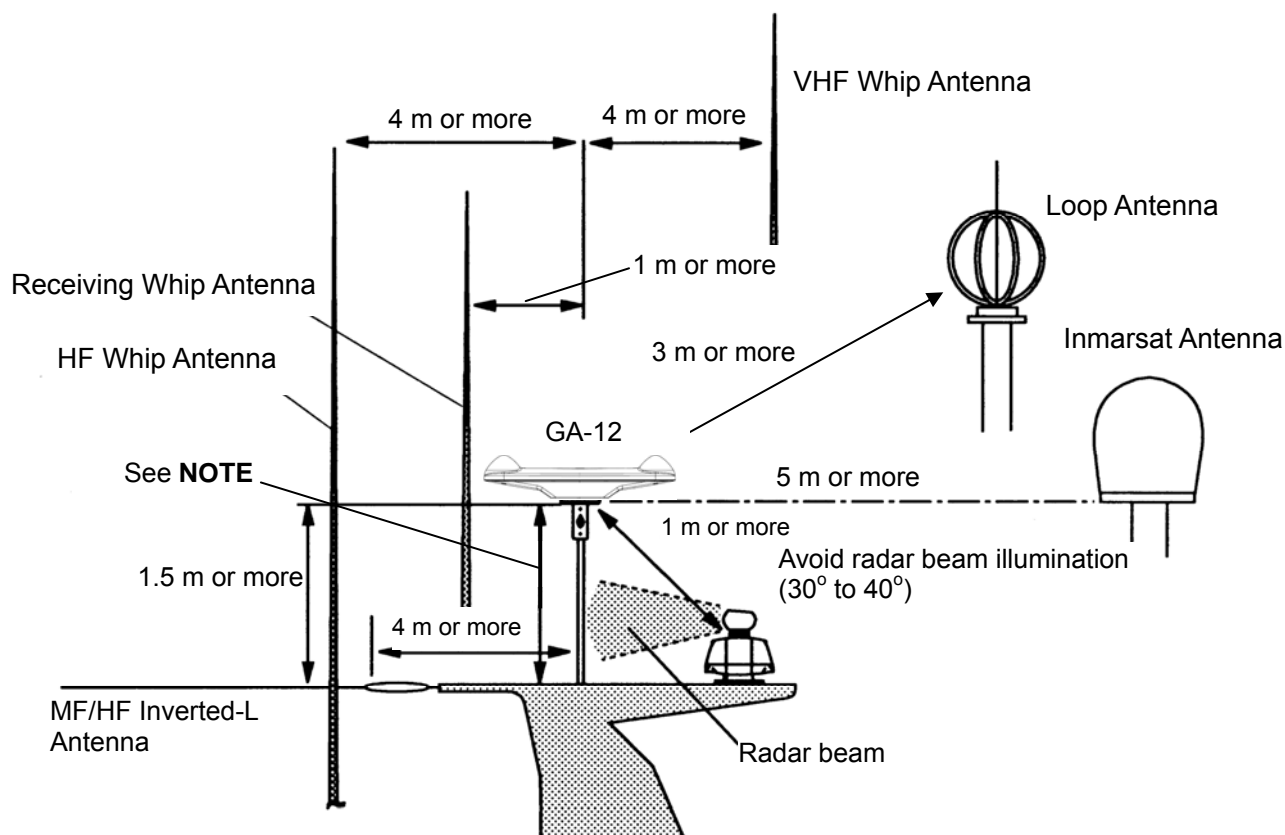
To operate the equipment in good order, the following points should be observed for installation of GPS antenna.

The GPS antenna GA-12 must be installed where good radio wave reception is achieved. No obstacles should be located above the antenna otherwise the radio wave reception may be interrupted. This causes the available GPS service hours to be reduced and degrades the positioning accuracy.

- (1) Select a site away from metallic objects, where possible.
- (2) Locate the GPS antenna at least 4 m away from radio antennas such as, Inverted-L antennas for MF/HF transmission, Whip Antennas for VHF or UHF.
- (3) Locate the GPS antenna at least 1.5 m above any Inverted-L antenna for MF/HF transmission.
- (4) Locate the GPS antenna at least 1 m from receiving antennas.
- (5) Locate the GPS antenna away from radar beams (Vertical beam width: 30° to 40°).
- (6) Locate the GPS antenna at least 1 m away from radar antennas.
- (7) Locate the GPS antenna at least 5 m away from Inmarsat radomes.
- (8) Locate the GPS antenna at least 3 m away from DF loop antennas.
- (9) Locate the GPS antenna at least 2 m away from the ship's engine.
- (10) Locate the GPS antenna at least 0.5 m away from metallic objects.

Should any of the requirements mentioned in item (1) to item (10) not be met, try to fulfill the requirements of item (10) and install the GPS Antenna as far as possible from the antennas described in item (1) to item (9). Put the GPS Antenna as trial on a promising site to make sure that the unit operates as specified before fixing the GPS Antenna position and then fix the antenna firmly. The GPS Antenna installed in an improper site may result in poor bearing accuracy and positioning error that may lead to potential hazards.

[Scale differs among drawings.]



NOTE: Keep away from metallic objects at least 0.5 m.

Laying and Connection of Cable

- (1) Keep the antenna cable and power cable as far away from the cables of other electronic equipment as possible.
- (2) The cabinet of Display unit shall be securely grounded to the hull, using the ground terminal on the rear panel.
- (3) If you connect the power cable directly to the battery, the interference from other electronic equipment is expected to be less. (See Fig. 6.1.)

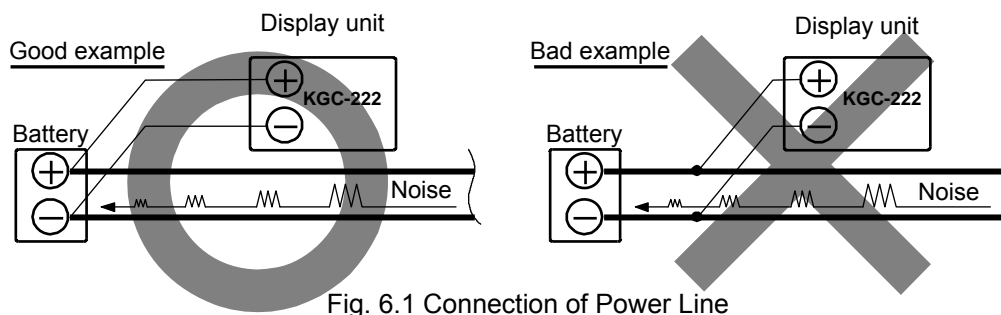


Fig. 6.1 Connection of Power Line

Confirmation after Installation

Be sure to confirm the following points before starting up this equipment. The confirmation is mandatory to operate the equipment normally.

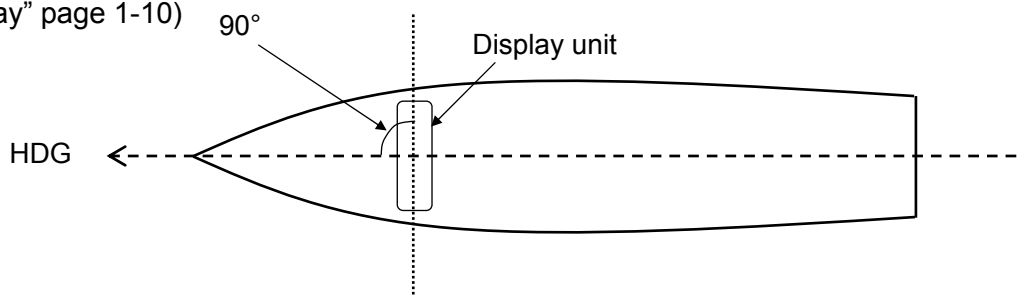
- (1) Is the power voltage in the boat within the appropriate voltage range? Is the current capacity enough?
(Voltage Range: 10.8 to 31.2 VDC when measured at the power connector input.)
- (2) Is the electric current capacity sufficient? (Power consumption: 10 W)
- (3) Is the wiring correct? Is the wiring shorted?

3.2 Installation of Display unit

Display unit can be installed either on pedestal or flush-mounted.

The following points shall be taken into consideration:

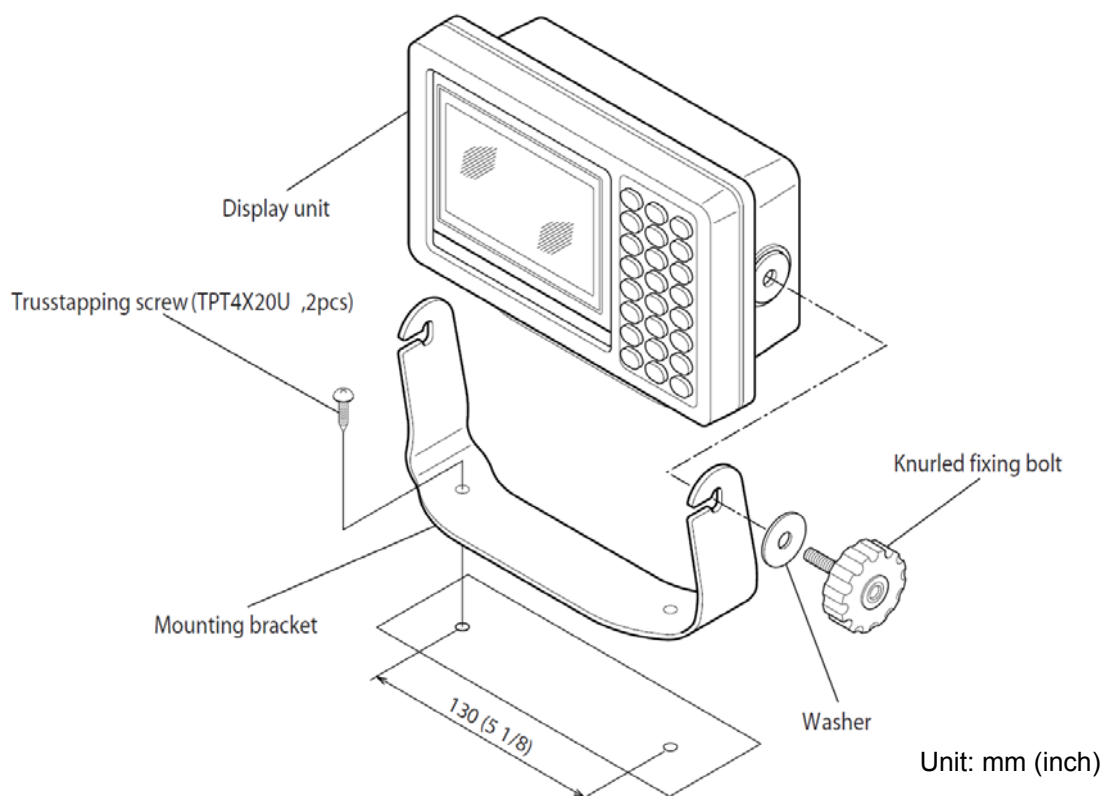
- (1) The KGC-222 has a magnetic backup sensor built in and needs to be installed as far away from other magnetic equipment or ferrous objects as possible, such as compass and others. Strong magnetic field may cause interference during backup function of the display.
- (2) When Pitch/Roll and Heaving data is used with other equipment such as echo sounder, the display needs to be installed in head up orientation, if display is installed at an angle with the bow line then it needs to be compensated in the menu. (Refer to "Setting angle of Display" page 1-10)



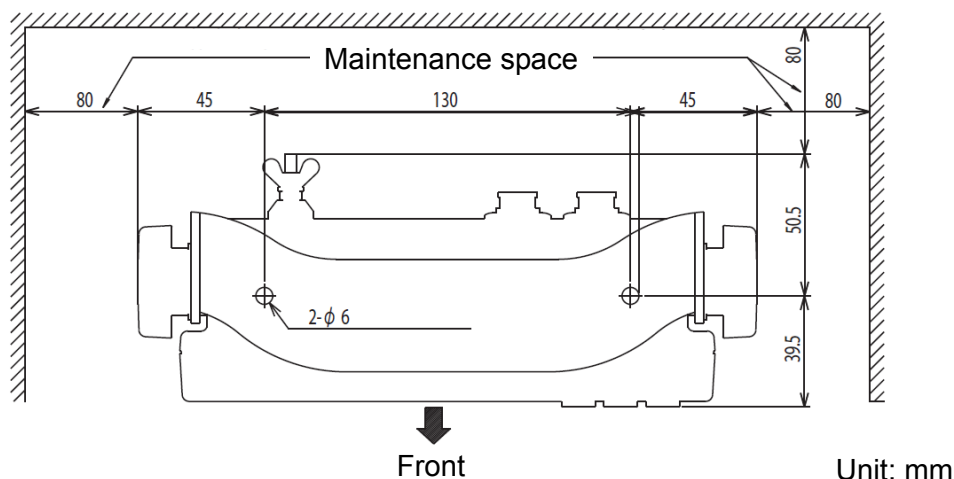
Install the Display unit as follows.

Table mounting

- (1) Remove two knob bolts fixing the display unit to the bracket.
- (2) Remove the display unit from the bracket and place it on the stable flat place.
- (3) Place the bracket on the position where the display unit will be installed and fix the bracket with two (2) attached truss tapping screws.
- (4) Place the display unit on the installation bracket and fix the display unit with two knob bolts removed in step 1.

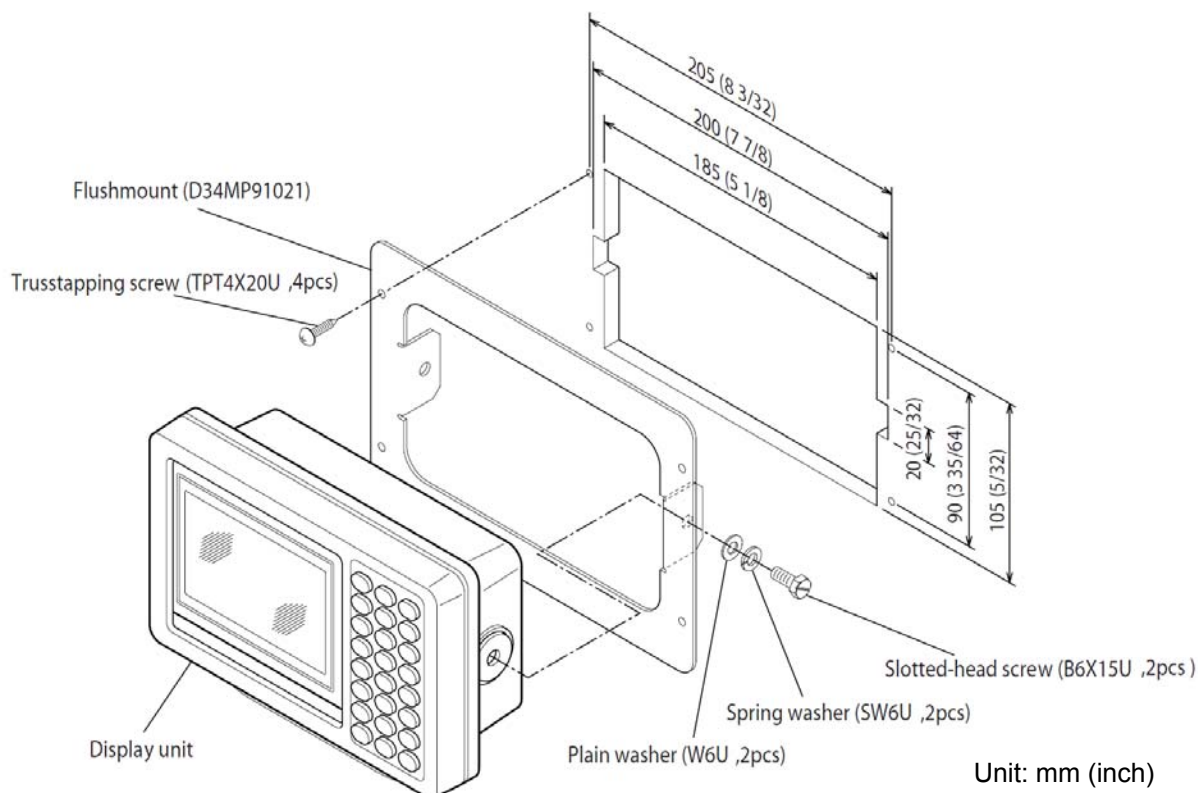


Caution: In the case of mounting the display unit on the table, some maintenance space is required for cabling, connector access, fuse replacement, fastening of bolts, etc. as shown in the following illustration.



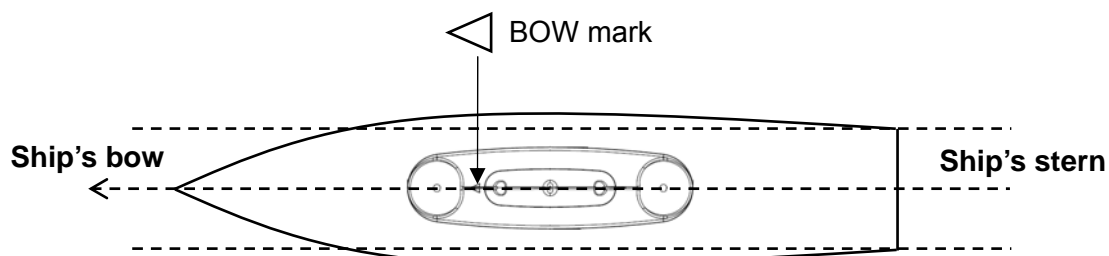
Flush mounting

- (1) Make a square hole at the location to be installed.
- (2) Loosen two (2) fixing knobs that fasten the Display unit onto the mounting bracket. The bracket and knob bolts are no longer used.
- (3) Install the Display unit on the Flush mount kit and fix it with two (2) slotted-head screws.
- (4) Connect the connectors for power, DATA, and antenna to the Display unit respectively.
- (5) Install the Display unit in the installing location (square hole) and fix it with four 4mm tapping screws. (Prepare 4mm screws suitable for thickness of installing location.)



3.3 Installation of GPS antenna GA-12

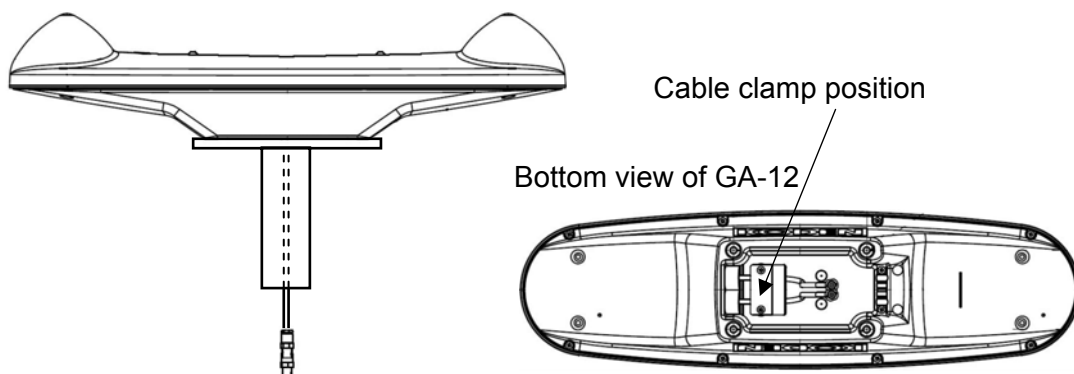
The GPS antenna GA-12 should be installed, as illustrated below, on the keel line with the BOW mark oriented to the ship's bow. If this is not possible due to the ship's superstructure, the antenna may be moved in parallel to the keel line. However, the antenna should be, where possible, installed on the midship, to minimize bearing deviation between the ship's bearing and course.



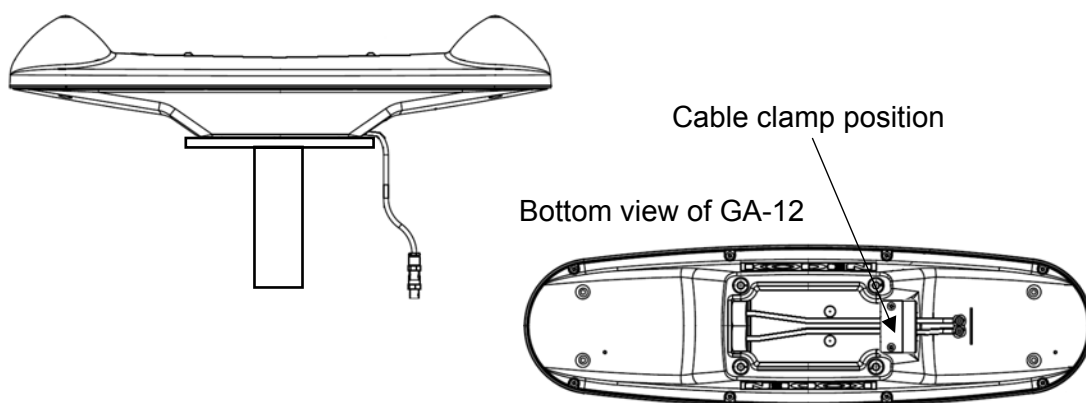
Antenna cable layout method

Two ways to run antenna cable from the antenna.

- (1) Antenna cable inserted into the bracketed and ran inside the mast pipe.

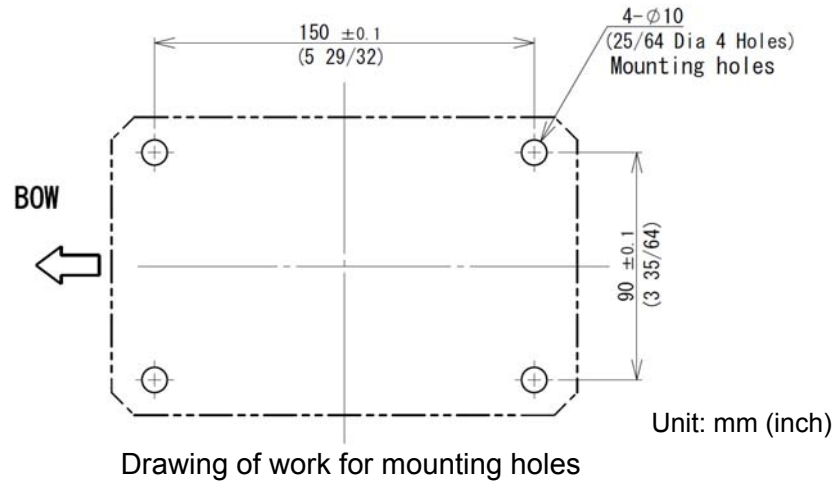


- (2) Antenna cable is dropped off from the side of the antennal and ran outside of the mast pipe.
In this case it is necessary to change the setting position of the cable clamp.

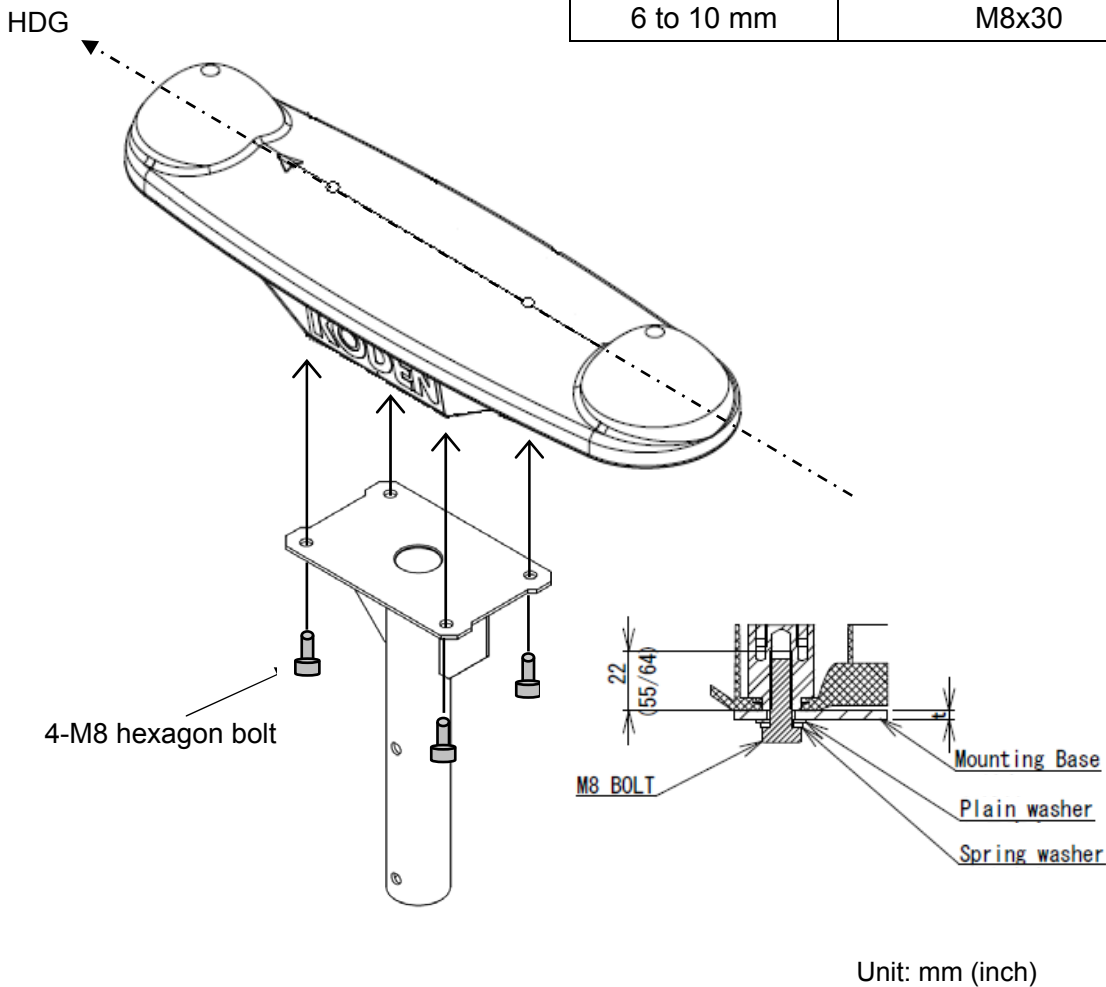


Installation of GPS antenna

To attach the GPS antenna, four (4) M8 bolts are used. Referring to the illustration below, make four (4) holes on the cradle, fix the bracket. When the thickness of the bracket is 4 to 5mm, supplied bolts may be used (M8 x 25). When the bracket is more than 6 mm thick, the bolts should be chosen from the below table.

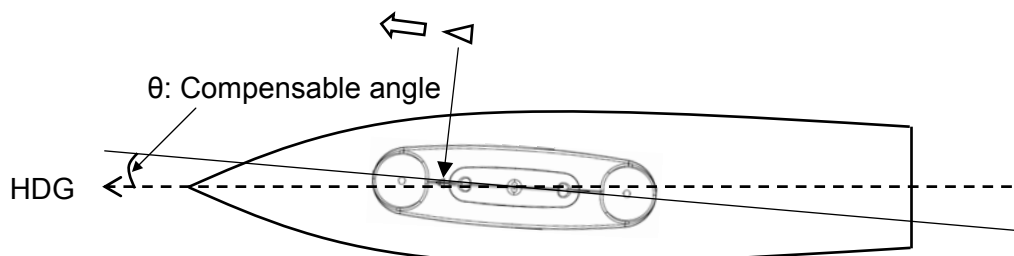


Platform thickness	Bolt for fixing the antenna
4 to 5 mm	M8x25
6 to 10 mm	M8x30



Angle compensation of Antenna

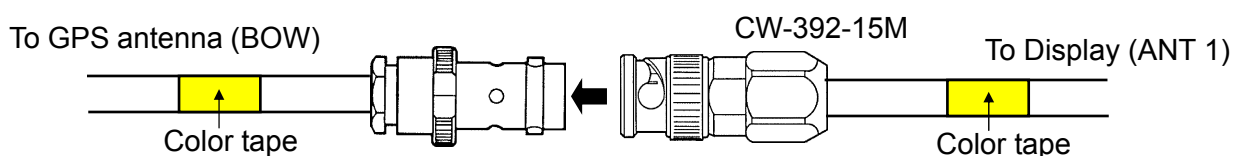
The GPS antenna should be installed on the keel line with the BOW mark oriented to the ship's bow. If not, HDG should be compensated. (Refer to "HDG Compensation" page 1-9)
When it is installed with θ° clockwise off, enter a compensation value $[-\theta]$ in the "MENU 3, COMPENSATION". When it is installed with θ° counterclockwise off, enter a compensation value $[+\theta]$ in the menu.



Connecting and waterproofing the connector

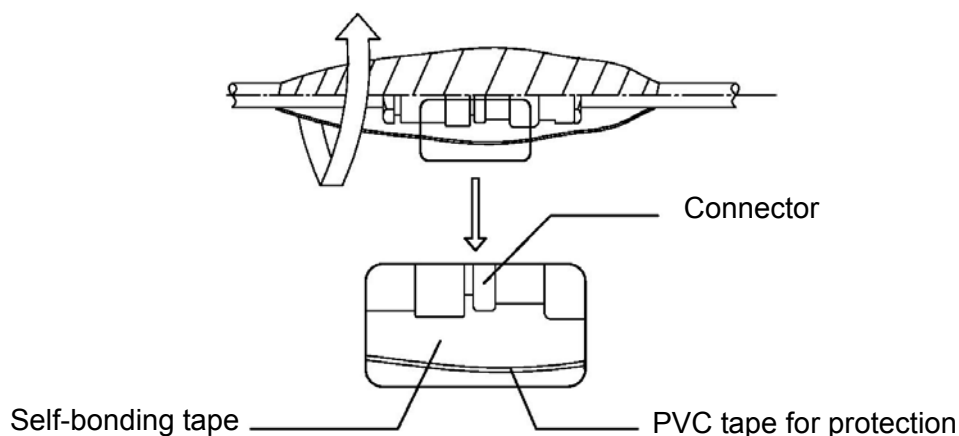
Make sure the BOW antenna cable is connected to ANT 1 of the display unit.

- (1) Pay attention to the BOW antenna cable marked with tape.

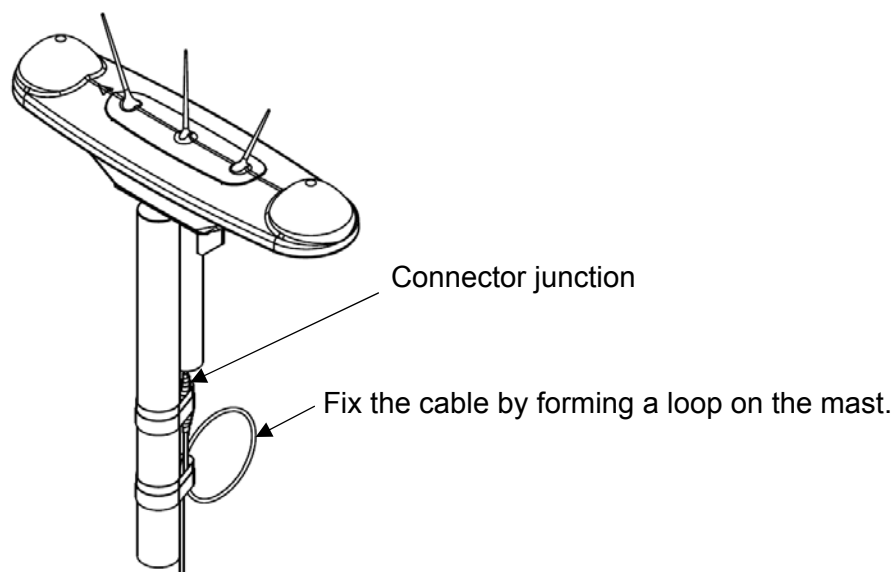


- (2) Wind the self-bonding tape around the joint section after connecting.
Pull the end of the tape and stretch it to twice its length. Wrap it around joint section a total of 3 layers. When completed, apply gentle pressure over the surface with fingers to expedite the fusion.
- (3) Use PVC tape for extra protection.
PVC tape should not be strained. Wrap it around joint section a total of 3 layers. When finished, press the surface evenly without strain for complete adhesion of the tape.

Wind the tape this way



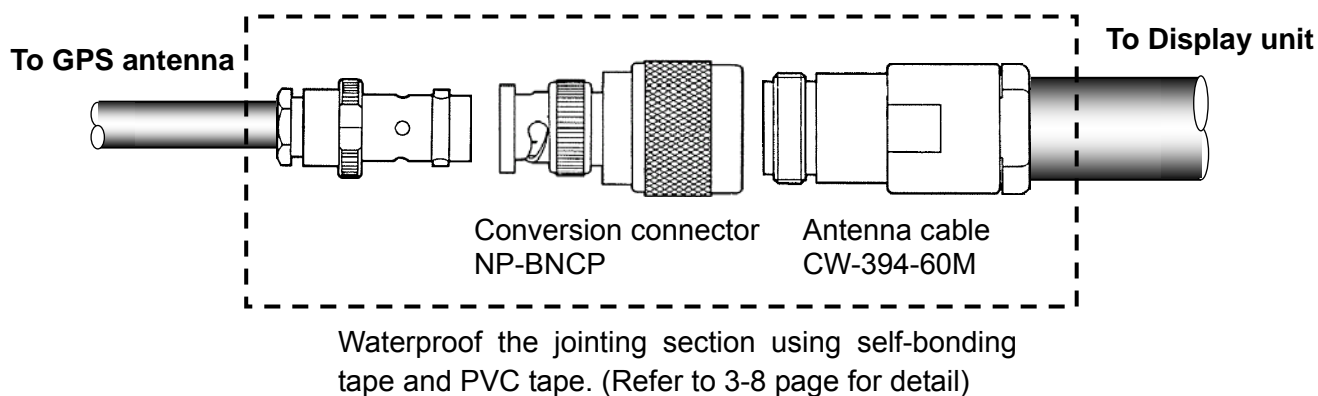
To prevent the tension hanging over the connector junction, the cable shall be fixed as described in the illustration below.



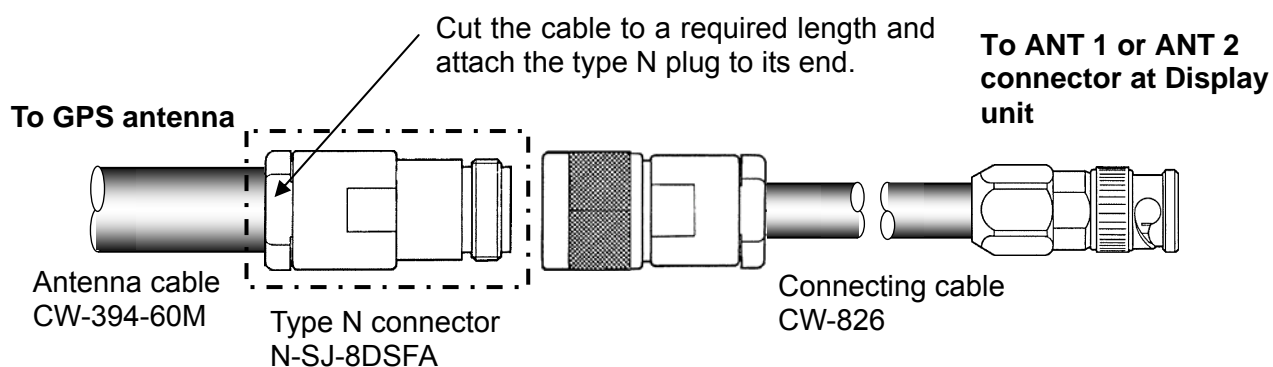
Connecting the 60m antenna cable kit CW-394.KIT to GPS antenna

The optional 60 m length cable kit, CW-394.KIT, is composed of the Antenna cable CW-394-60M and the N-to BNC conversion connector. Connect the GPS antenna and Display unit via the cable kit as shown in the following figure.

(1) Connection at GPS Antenna side

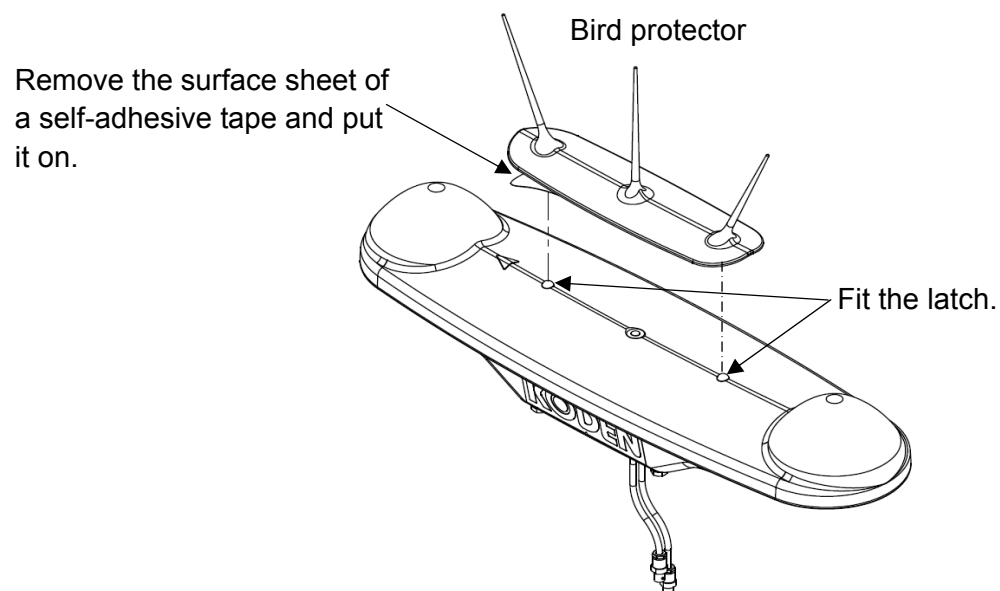


(2) Connecting the Display unit



Installing the bird protector to Antenna unit

Sea birds such as seagulls may be the cause of poor reception of the GPS signal when perched on top of the GPS antenna unit. The use of bird protector is recommended to avoid this problem. To fit this device, use the following procedure:

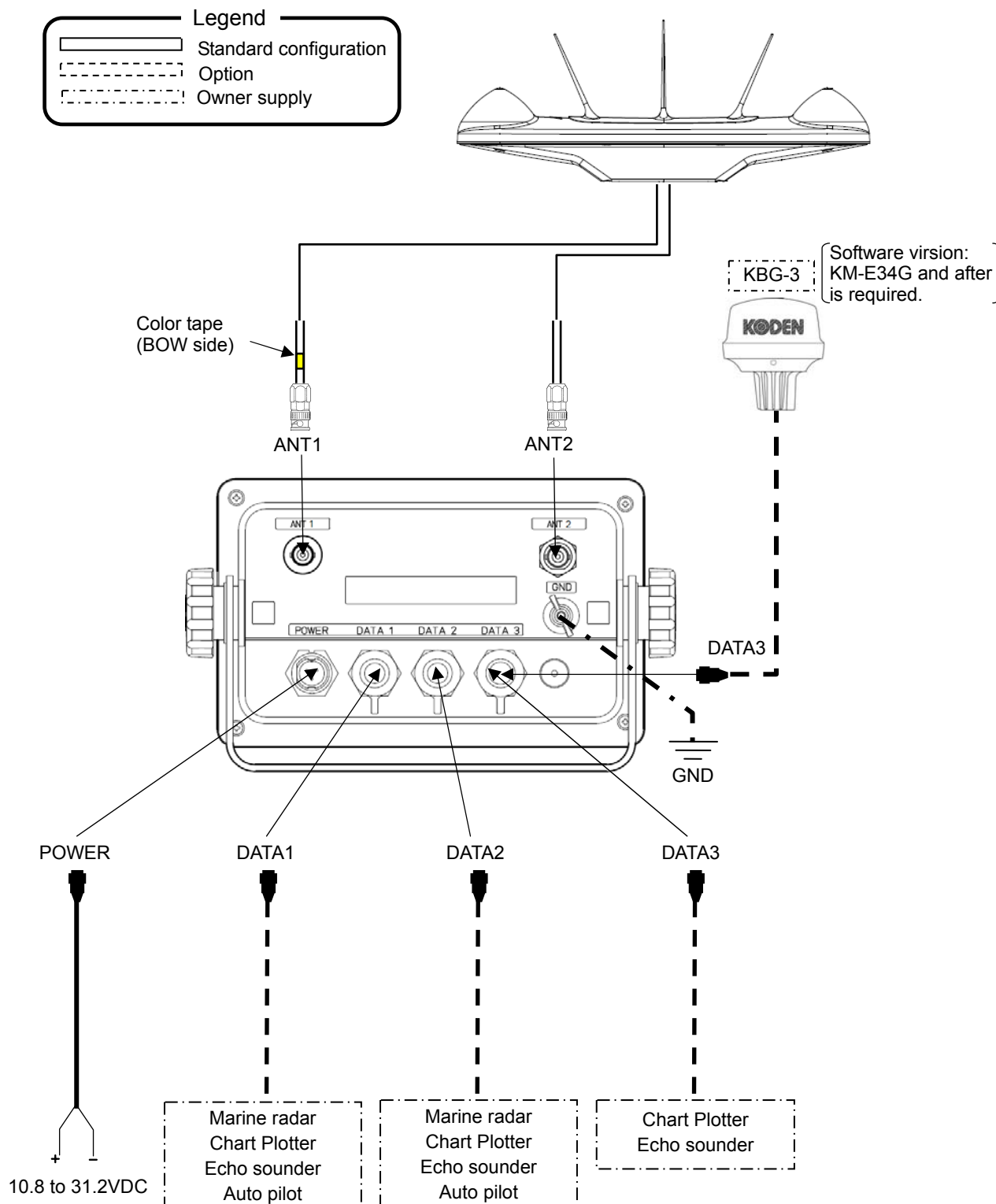


Caution: Put it on the surface without any gaps.

3.4 Wiring

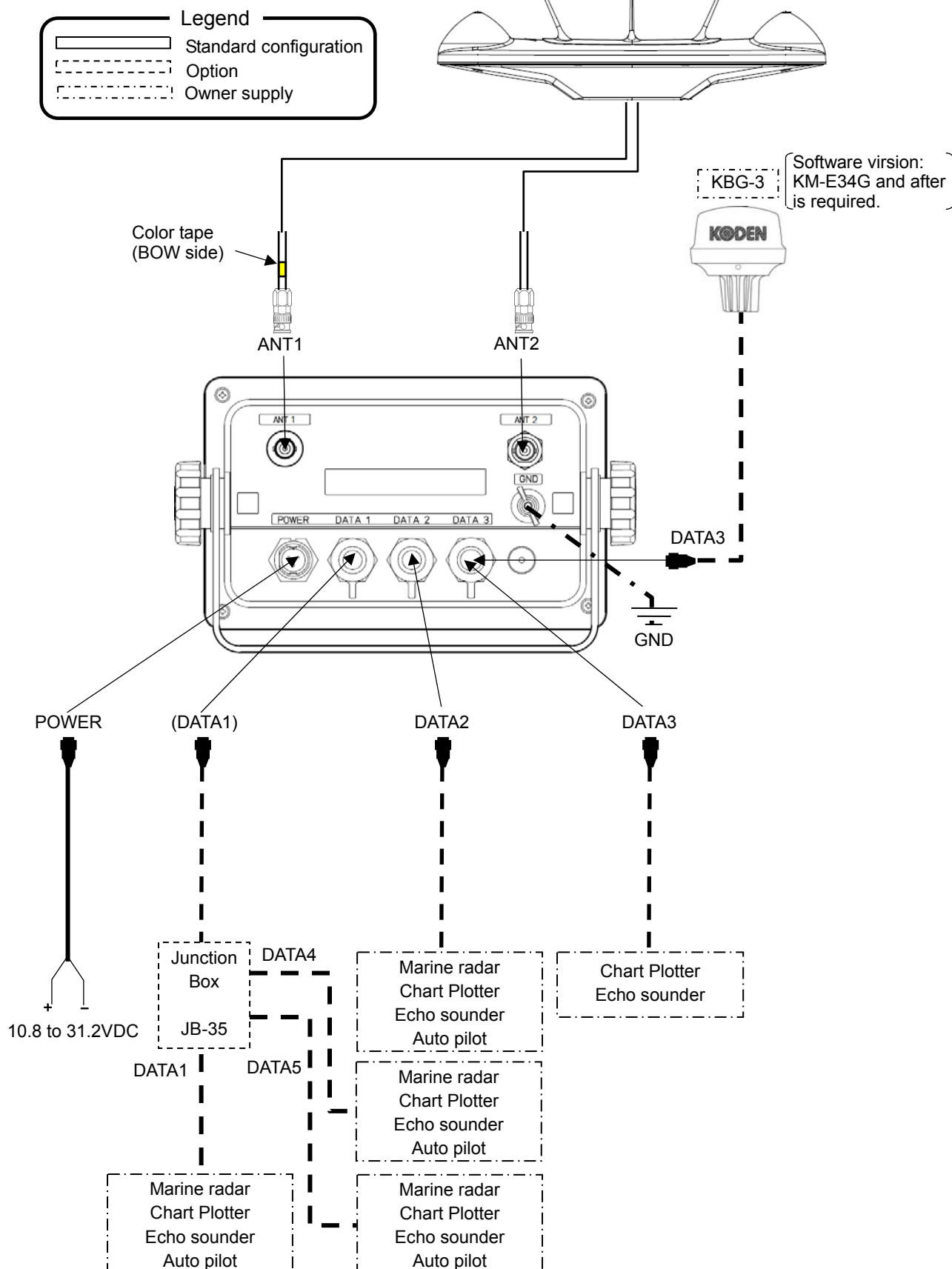
Connect the power cable and cables from the antenna to the connectors on the Display unit. Connect the cables from the external equipments to the DATA connectors on the Display unit.

- DATA 3 is for navigational data. Be sure to connect the Plotter or the KBG-3 to DATA 3.



Wiring with optional Junction box (JB-35)

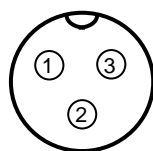
- Be sure to connect JB-35 to DATA 1.



Pin Assignment of Rear Connector

The pin assignment is viewed from the rear of the Display unit.

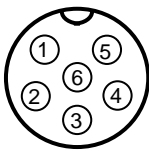
Power Input



POWER

- ① POWER+
- ② F.GND
- ③ POWER-

DATA IN/OUT



DATA1/2/3

Connector acceptable: LTWBD-06BFFA-L18

- ① GND
- ② TX+
- ③ TX-
- ④ RX+
- ⑤ RX-
- ⑥ +12V (Maximum 300mA)



Caution: The maximum current capacity is 300 mA in total, then it should not exceed.

Take care that the grand total of each connector does not exceed 300 mA.

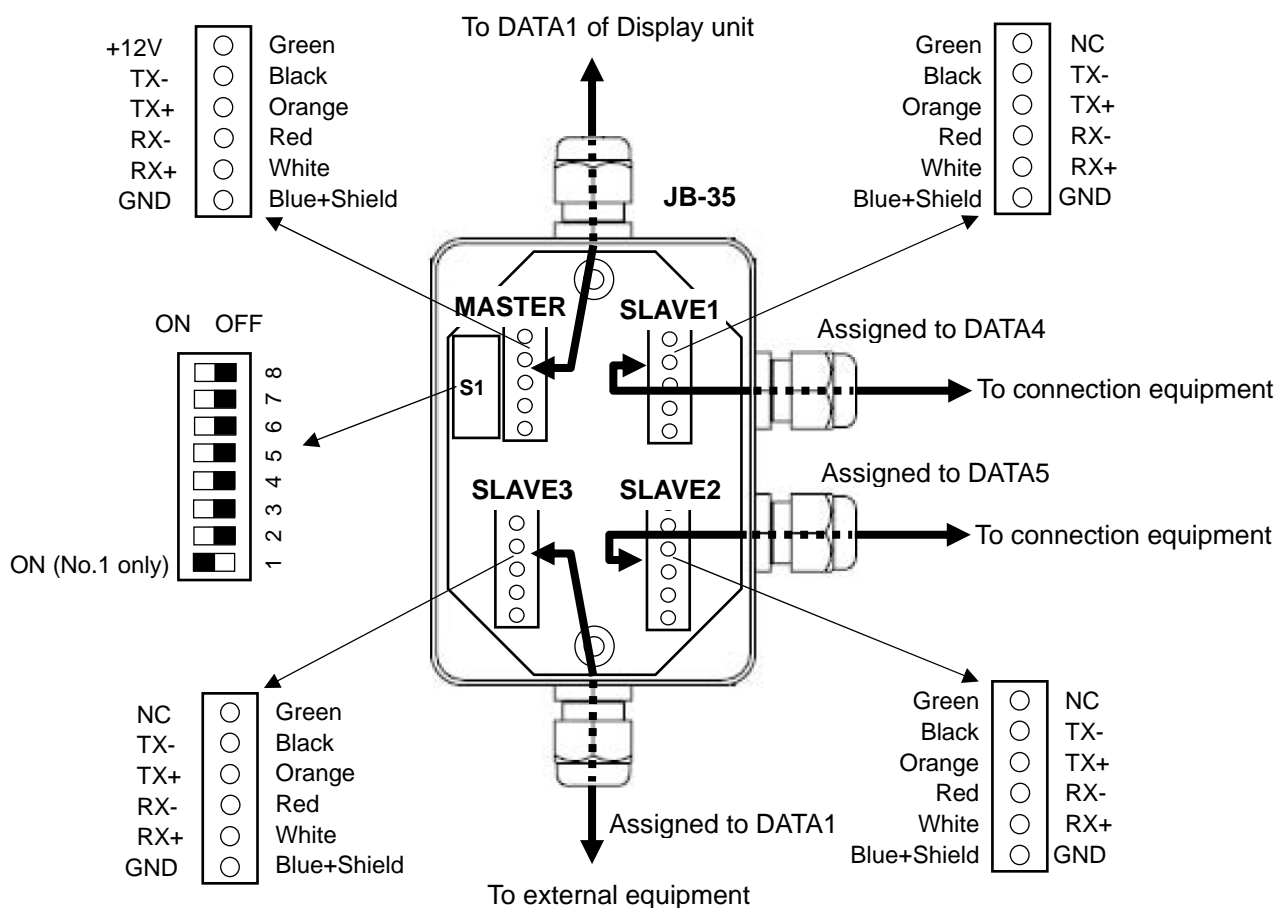
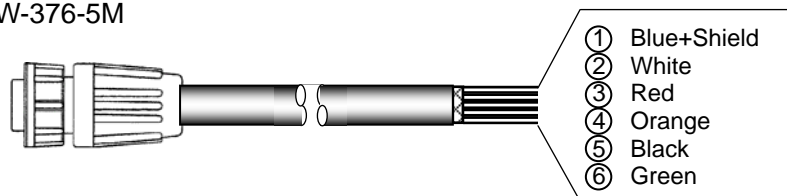
Connection with Junction box (JB-35)

To extend the ports, connect the junction box (JB-35) to the data connectors as shown in the figure below.

Set the DIP switch (S1) as shown in the figure below.

Wire the cables with the CW-376-5M (option) as shown in the following color chart.

CW-376-5M



Chapter 4 Detail of the serial output data

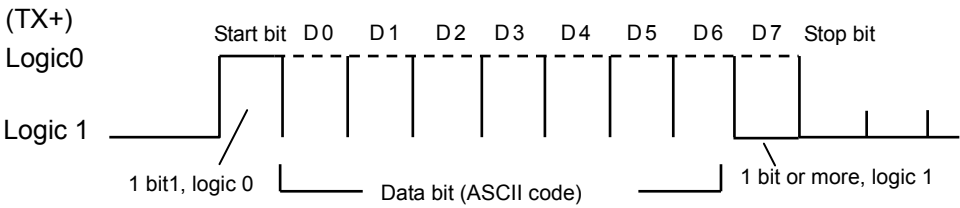
4.1 Output data format

Serial data name: NMEA0183 Ver.2.0

4.2 Details of the output data format

Data per one byte is as follows:

Parity bit: none



4.3 Output data specification

Baud rate	Output level	Output current	Sentence	TX interval
4800/38400 baud	RS-422	20mA max.	Refer to page 1-17	Refer to page 1-16

4.4 Details of output sentences

Sentence name	Data name and contents
HDT	<p>Ship's heading (True bearing)</p> <p>\$ GPHDT, xxx.x, T *hh <CR><LF></p> <p>Diagram labels: Start of sentence, Talker device code, Sentence name, Ship's Heading, Checksum</p>
HDM	<p>Ship's heading (Magnetic bearing)</p> <p>\$ GPHDM, xxx.x, M *hh <CR><LF></p> <p>Diagram labels: Ship's Heading, Checksum</p>

ROT	<p>Rate of turn</p> <p>\$ GPROT, 0/-xxx.x, a *hh <CR><LF></p> <p>(-Neg)/ Angular speed, deg/min</p> <p>Checksum</p> <p>Status A: Valid V: Void</p>
GGA	<p>GPS position data</p> <p>\$ GP GGA, hhmmss, xxxx.xxx, N/S, xxxxx.xxx, E/W, x, xx,</p> <p>Time of measurement (Hour, Min, Sec)</p> <p>Latitude</p> <p>Longitude</p> <p>Number of satellite in use</p> <p>Status of GPS fix measurement 0: Fix unable 1: GPS fix 2: DGPS fix</p> <p>xxx, 0/-xxxx, M, 0/-xxx, M, xxx, xxxx *hh <CR><LF></p> <p>HDOP value</p> <p>Antenna height</p> <p>Meter</p> <p>Gioid height</p> <p>Checksum</p> <p>DGPS reference station ID</p> <p>DGPS data correction time elapsed</p> <p>-: Negative</p>
GLL	<p>Ground position (Latitude/Longitude)</p> <p>\$ GP GLL, xxxx.xxx, N/S, xxxxx.xxx, E/W, hhmmss, a *hh <CR><LF></p> <p>Latitude</p> <p>Longitude</p> <p>N: North latitude S: South latitude</p> <p>E: East longitude W: West longitude</p> <p>Fix measurement time elapsed (Hour, Min, Sec)</p> <p>Checksum</p> <p>Status A: Valid V: Void</p>
GSA	<p>Satellite in use and DOP</p> <p>\$ GP GSA, M/A, x, xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx, x.x, x.x, x.x *hh <CR><LF></p> <p>M: Manual A: Auto</p> <p>Satellite number in use</p> <p>GPS DOP 1: Fix unable 2: 2 dimensions 3: 3 dimensions</p> <p>PDOP value</p> <p>VDOP value</p> <p>HDOP value</p> <p>Checksum</p>
GSV	<p>Available satellite</p> <p>\$GPGSV, x, x, xx, xx, xx, xx, *hh <CR><LF></p> <p>2nd sv, 3rd sv</p> <p>Checksum</p> <p>S/N (Signal to Noise ratio)</p> <p>Azimuth angle</p> <p>Elevation angle</p> <p>Satellite No.</p> <p>Available number of satellites</p> <p>Message number</p> <p>Total message number, 1 ~ 3</p> <p>First satellite</p>

ZDA	<p>Time and date</p> <p>\$ GPZDA , hhmmss , xx , xx , xxxx , *hh <CR><LF></p> <p>Time (H,M,S)</p> <p>Day Month Day Year</p> <p>Checksum</p> <p>This field is not used</p>
RMC	<p>Minimum sentence for GPS/TRANSIT navigation data</p> <p>\$ GPRMC , hhmmss , x , xxxx.xxx, N/S, xxxx.xxx, E/W, x.x , xxx.x ,</p> <p>Measurement Time (H,M,S)</p> <p>Latitude</p> <p>Longitude</p> <p>N: North latitude S: South latitude</p> <p>E: East latitude W: West latitude</p> <p>Track bearing (True bearing)</p> <p>Ground speed (KNT)</p> <p>A: Data valid V: Alarm valid for Nav receiver</p> <p>ddmmyy , x.x , E/W *hh <CR><LF></p> <p>Magnetic deviation</p> <p>E: East longitude W: West longitude</p> <p>Checksum</p>
VTG Ver2.0	<p>Course and ground speed</p> <p>\$GPVTG, xxx.x, T, xxx.x, M , xx.x, N, xx.x, K *hh <CR><LF></p> <p>Track bearing (True)</p> <p>Track bearing (Magnetic)</p> <p>Ground speed (KNT)</p> <p>Ground speed (Km/H)</p> <p>Checksum</p>
VTG 61162-1	<p>Course and ground speed</p> <p>\$GPVTG, xxx.x, T, xxx.x, M , xx.x, N, xx.x, K, a *hh <CR><LF></p> <p>Track bearing (True)</p> <p>Track bearing (Magnetic)</p> <p>Ground speed (KNT)</p> <p>Ground speed (Km/H)</p> <p>Mode</p> <p>A: Data valid D: Data void</p> <p>Checksum</p>
DTM	<p>Datum reference</p> <p>\$GPD TM, ccc, , x.x, a, x.x, a, , W84 *hh <CR><LF></p> <p>Local datum</p> <p>Lat offset, min, N/S</p> <p>Lon offset, min, E/W</p> <p>Reference datum WGS84</p> <p>Checksum</p> <p>W84: WGS84 W72: WGS72 999: user IHO datum code</p>

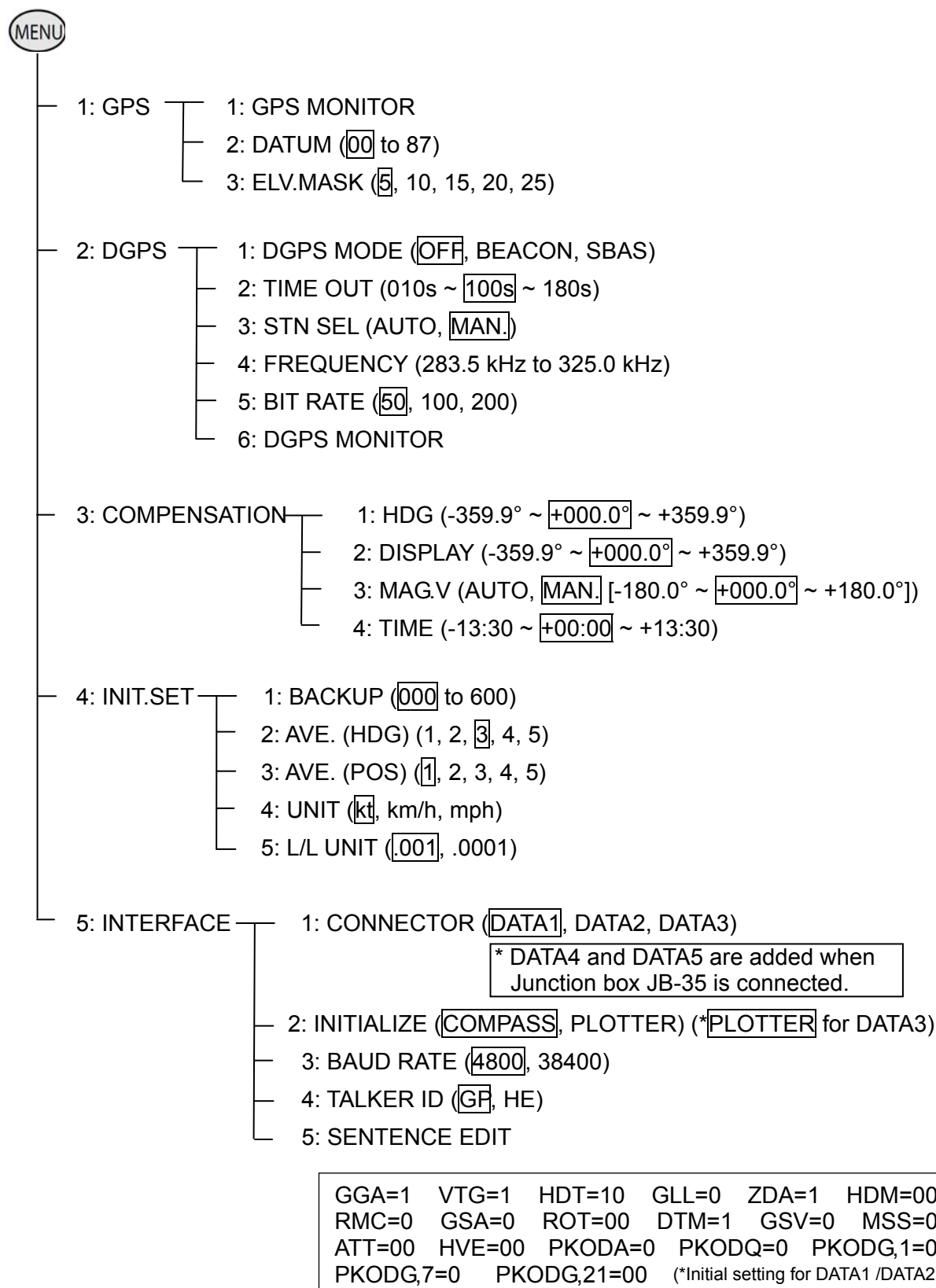
MSS	MSK receiver signal status \$ GPMSS, , xx, xxx.x, xxx <CR><LF> <p>Beacon bit rate (50, 100, 200) bits/s Beacon frequency (283.5 ~ 325.0 kHz) S/N ratio (0 ~ 31dB) This field is not used</p>
PKODA	Satellite information (KODEN proprietary sentence) \$ PKODA, P/H, xxx.x, xx, xx, xx, xx, xx, xx, xxx, M, xxx.x, N, xxx.x, 0/-xx.x, x, x <CR><LF> <p>P: PDOP H: HDOP PDOP value Satellite No. in use (1 ~ 4 channel) Antenna height Meter Ground speed Knot True bearing S/N ratio of the satellite in use (1 ~ 4 channel) Longitude (1/1000 min) Latitude (1/1000 min) X'tal deviation (0: Positive, -: Negative)</p>
PKODG1	Satellite information (KODEN proprietary sentence) \$ PKODG, 1, x, xx, +/-xx, xxx, xx, xx, xx, xx, xx, xx, xx, xx, <CR><LF> <p>Satellite No. Satellite elevation angle Satellite azimuth angle Reception quality 1: GPS fix available 0: Fix unable Elevation angle limit S/N limit value HDOP limit value PDOP limit value Averaging constant Geodetic system Day Month Year</p>
PKODG7	DGPS information (KODEN proprietary sentence) \$ PKODG, 7, x, x, xxx <CR><LF> <p>Time out value (010 ~ 180 sec) DGPS status (1: DGPS ON, 0: DGPS OFF) DGPS (0: OFF, 1: RTCM ON, 2: SBAS ON)</p>

PKODG21	<p>Ship's heading, Pitch/Roll and Heaving information (KODEN proprietary sentence)</p> <p>\$PKODG, 21 ,xxx.x, +/-xx.x, +/-xx.x, +/-xx.xxx, a *hh <CR><LF></p> <p>Checksum Status A: Valid V: Void Heaving data Rolling data Pitching data Ship's Heading</p>
PKODQ	<p>Satellite information (KODEN proprietary sentence)</p> <p>\$ PKODQ, xxxx, x.....x, xxx, xxm, xxxhPa, Wavexxm <CR><LF></p> <p>Observation time Observation point Wind direction Wind speed Atmospheric pressure (hPa) Wave height (m)</p>
GPatt	<p>Ship's heading, Pitch and Roll information (FURUNO proprietary sentence)</p> <p>\$ PEFC,GPatt, xxx.x, +/-00.0, +/-00.0 *hh <CR><LF></p> <p>Checksum Rolling data Pitching data Ship's Heading</p>
GPhve	<p>Heaving information (FURUNO proprietary sentence)</p> <p>\$ PEFC,GPhve, +/-00.011, A *hh <CR><LF></p> <p>Checksum Status A: Valid V: Void Heaving data</p>

Chapter 5 Attached table

5.1 Menu Configuration

The factory set value is shown by the surrounding boxes.



5.2 Specifications

Model	Display unit : KGC-222.MU GPS antenna : GA-12
Receiving frequency	1575.42MHz \pm 1MHz
Receiving channel	Parallel 16 channel
Sensitivity	Better than -130 dBm
Setting time	2 minutes (at standard hot-start time)
Heading accuracy	1° rms
Heading resolution	0.1°
Maximum rate of turn	45°/s
Maximum follow-up acceleration	1g
Maximum roll / pitch angle	30°
Base line length	0.5m
Time to position fix	
Cold start	50 sec (standard)
Warm start	45 sec (standard)
Hot start	20 sec (standard)
Positioning accuracy	
Position	GPS: 10m (2 drms, SA:OFF, PDOP: 3 or less) DGPS: 3m (2 drms, SA:OFF, PDOP: 3 or less)
Velocity	1 m / sec (rms, SA:OFF, PDOP: 3 or less)
Datum	88 (WGS-84, Tokyo etc.)
Output data port	3 (standard), 5 (with connecting an optional junction box)
Output data	
Format	NMEA 0183 Ver2.0
Heading data sentence	ATT, HDM, HDT, HVE, ROT, PKODG,21
Navigation data sentence	DTM, GGA, GLL, GSA, GSV, MSS, RMC, VTG, ZDA, PKODA, PKODG,1, PKODG,7, PKODQ
Data level	RS-422
Output current	20mA
Output interval	20ms, 40ms, 50ms, 100ms, 200ms, 1s
Power supply	10.8 to 31.2VDC
Power Consumption	9W or less (at 24 VDC)
Operating temperature	-15°C to +55°C
Water protection	
Display unit	IPX4
GPS antenna	IPX6
Store temperature	-30°C to +70°C
Upper limit of humidity	93% +/- 3% @ +40°C

5.3 Local geodetic system list

No.	IHO* code	Name	No.	IHO code	Name
00	W84	WGS-84	27	AIN	BAHRAIN
01	W72	WGS-72	28	ANO	COCOS
02	TOY	TOKYO	29	ARF	ARC 50
03	NAS	NAD-27	30	ARS	ARC 60
04	NAS	ALASKA/CANADA	31	ASC	ASCENSION
05	EUR	EUROPEAN 50	32	ATF	IWO JIMA
06	AUG	AUSTRALIAN 84	33	TRN	TERN
07	SOA	SOUTH ASIA	34	SHB	ST.HELENA
08	SAN	SOUTH AMERICA	35	ASQ	MARCUS
09	QUO	GREENLAND	36	IBE	EFATE
10	NAR	NAD-83	37	BER	BERMUDA 57
11	HJO	ICELAND 55	38	BOO	COLOMBIA
12	IRL	IRELAND 65	39	CAI	ARGENTIN
13	GEO	NEW ZEALAND	40	CAO	PHOENIX
14	EUS	EUROPEAN 79	41	CAC	FLORIDA
15	MOD	ROME 40	42	CGE	TUNISIA
16	CAP	SOUTH AFRICA	43	CHI	CHATHAM
17	NAH	SAUDI ARABIA	44	CHU	PARAGUAY
18	IND	INDIAN/NEPAL	45	COA	BRAZIL
19	LUZ	PHILIPPINES	46	GIZ	NEW GEORGIA
20	OGB	ENGLAND	47	EAS	EASTER
21	OHA	HAWAII	48	GAA	MALDIVE
22	BAT	DJAKARTA	49	GUA	GUAM 63
23	KEA	MALAYSIA	50	DOB	GUADALCANAL
24	TOY	JAPAN	51	HKD	HONG KONG 63
25	ADI	ETHIOPIA	52	IST	DIEGO GARCIA
26	AFG	SOMALIA	53	JOH	JHONSTON

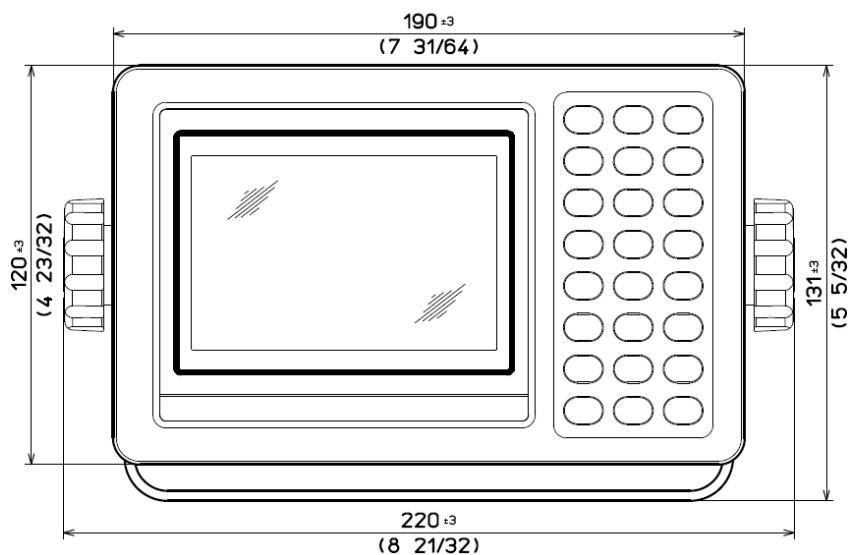
*IHO : nternational Hydrographic Organization

No.	IHO code	Name	No.	IHO code	Name
54	KAN	SRI LANKA	81	MVS	FIJI
55	KEG	KERGUELEN	82	ENW	MARSHALL
56	LCF	CAYMAN BRAC	83	ZAN	SURINAME
57	LIB	LIBERIA 64	84	999	FINLAND
58	MIK	MAHE 71	85	999	SWEDEN
59	SGM	SALVAGE	86	HTN	HU-TZU-SHAN
60	MAS	ERITREA	87	PUK	RUSSIA
61	MER	MOROCCO			
62	MID	MIDWAY 61			
63	MIN	NIGERIA			
64	NAP	TRINIDAD			
65	FLO	CORVO/FLORES			
66	OEG	EGYPT			
67	FAH	OMAN			
68	PLN	CANARY			
69	PIT	PITCAIRN			
70	HIT	SOUTH CHILE			
71	PUR	PUERTO RICO			
72	QAT	QATAR			
73	REU	MASCARENE			
74	SAE	SANTO			
75	SAO	SANTA MARIA			
76	SAP	EAST FALKLAND			
77	POS	PORTO SANTO			
78	GRA	FAIAL			
79	TIL	EAST MALAYSIA			
80	TDC	TRISTAN			

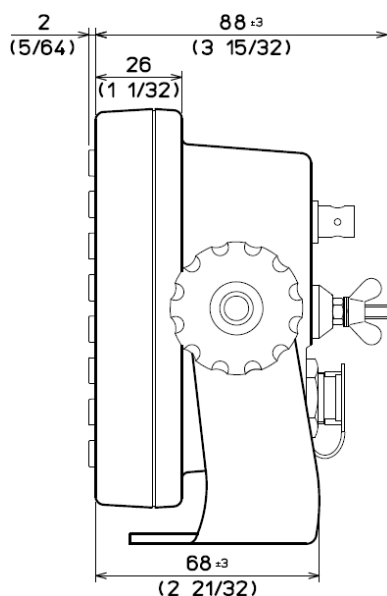
5.4 External view and dimensions

Display unit : KGC-222.MU

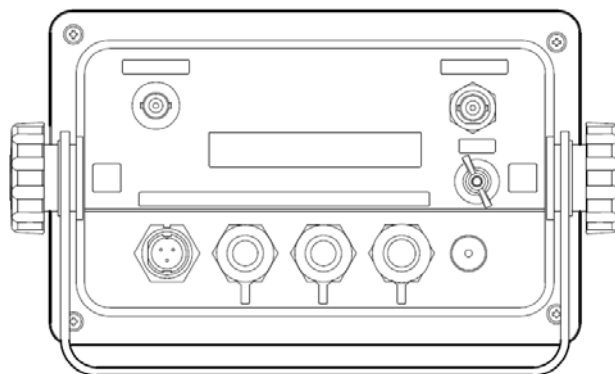
Front view



Side view

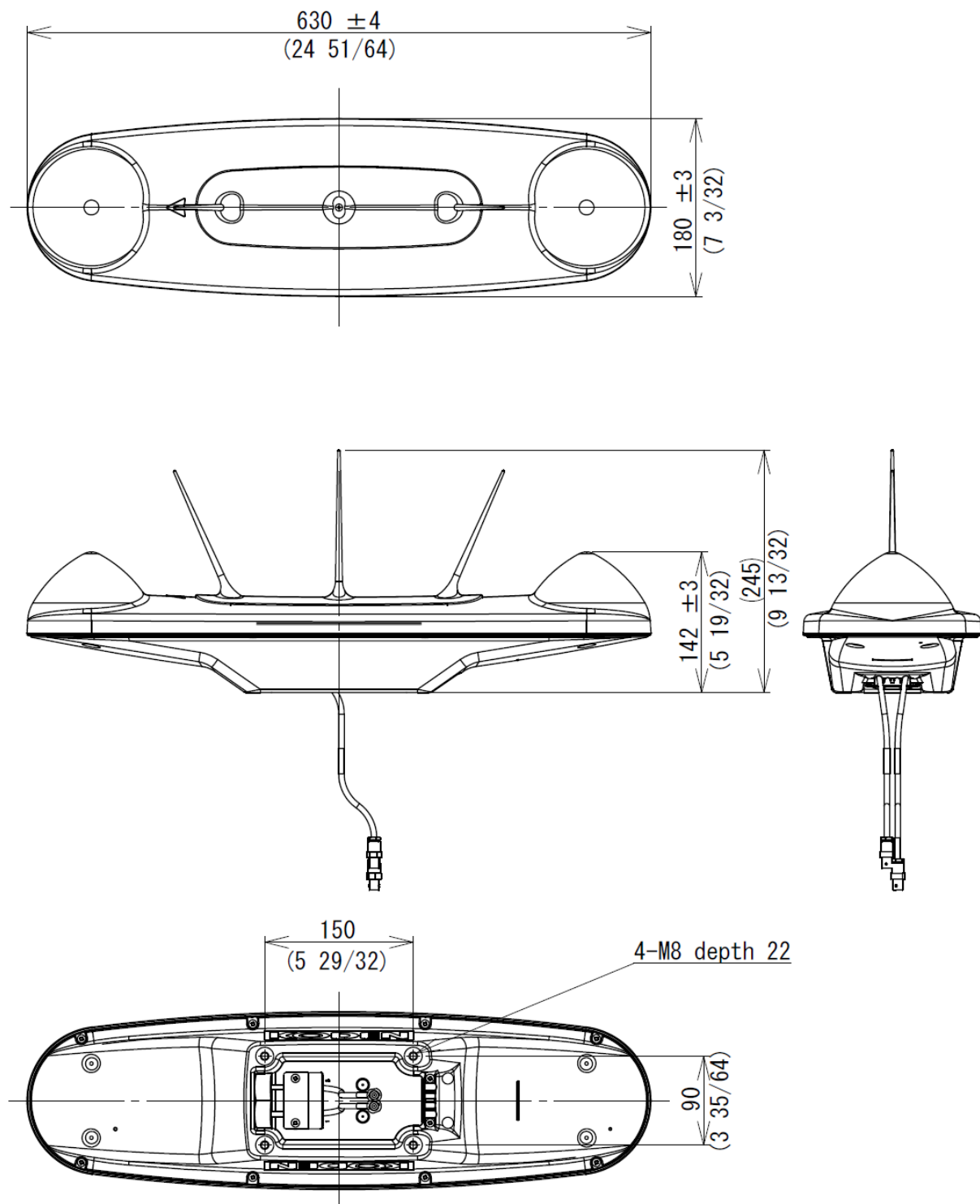


Rear view



Weight: 0.89kg (With mounting bracket)

Unit: mm (inch)

GPS antenna : GA-12

Weight: 2.2kg (With antenna cables)

Unit: mm (inch)

Chapter 6 INDEX

A

Angle compensation of Display unit 1-10
 Antenna angle compensation 3-9
 Antenna installation 3-8

B

Backup time 1-12
 Baud rate 1-16
 Beacon bit rate 1-9
 Beacon frequency 1-8
 Beacon station 1-8
 Bird protector 3-11

C

Calibration 1-12
 CW-394.KIT 3-10

D

DGPS 1-7
 DGPS monitor 1-9
 DGPS timeout 1-8

E

Elevation angle masking 1-7
 Error message 2-2
 External view 5-5

F

Flush mounting 3-6

G

Geodetic datum 1-7
 Geodetic datum list 5-3
 GPS monitor 1-6
 GPS position averaging 1-14

H

HDG averaging 1-14
 HDG compensation 1-9
 Heaving compensation 1-18

I

Initial settings 1-12
 Initialization 2-3
 Interface 1-15

J

Junction box (JB-35) 3-13

L

Lat/Lon unit 1-15

M

Magnetic variation 1-11
 Menu list 5-1
 MOB 1-5

O

Output data settings 1-15
 Output data specification 4-1
 Output sentence editing 1-16
 Output sentence initialization 1-16
 Output sentence specification 4-1

P

Pin assignment 3-14

R

Range unit 1-14

	S		Talker ID 1-16
Specification			Time 1-11
	T		
Table mounting			
		W	
		Waterproofing connection	3-9



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